

Size change, shape change, and the growth space of a community

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Colour figures: figure 1; figure 2; figure 4.

Appendices:

Appendix A Invariance under exponential growth and scaling invariance

Appendix B Existing measures of rate of shape change

Appendix C Deriving a measure of rate of shape change

Appendix D What kinds of functions are scaling invariant?

Appendix E Estimating size and shape change

Appendix F Measuring colonization and extinction

Appendix G Size and shape change in presence-absence data

R code and data used in the examples (`succession.zip`). FOR REVIEW, AVAILABLE FOR DOWNLOAD FROM <http://www.liv.ac.uk/~matts/rateofsuccession.html>.

1 Abstract

2 Measures of biodiversity change such as the Living Planet Index describe proportional change in the abundance
3 of a typical species, which can be thought of as change in the size of a community. Here, I discuss the orthogonal
4 concept of change in relative abundances, which I refer to as shape change. To be logically consistent, a measure
5 of the rate of shape change should be scaling invariant (have the same value for all data with the same vector
6 of proportional change over a given time interval), but existing measures do not have this property. I derive a
7 new, scaling invariant measure. I show that this new measure and existing measures of biodiversity change such as
8 the Living Planet Index describe different aspects of dynamics. I show that neither body size nor environmental
9 variability need affect the rate of shape change. I extend the measure to deal with colonizations and extinctions,
10 using the surreal number system. I give examples using data on hoverflies in a garden in Leicester, UK, and the
11 higher plant community of Surtsey. I hypothesize that phylogenetically-restricted assemblages will show a higher
12 proportion of size change than diverse communities.

13 1. Introduction

14 The Living Planet Index (Loh et al., 2005) and similar indices (e.g. Buckland et al., 2011; Burns et al., 2013;
15 Dirzo et al., 2014) measure proportional change in the abundance of a typical species. They are used by a number
16 of major conservation organizations and have resulted in alarming headline figures such as the mean 25% decline
17 in abundance of terrestrial vertebrate populations between 1970 and 2000 (Loh et al., 2005). I will refer to the
18 property measured by these indices as “size” change. It is obvious that there are other aspects of change in the
19 abundances of species in a community, which may also be of both theoretical and applied interest. I will concentrate
20 on one of these:

21 **Definition 1.** “Shape” change is “change in the relative abundances of species in a community” (Lewis, 1978),
22 where the relative abundance of a species is its abundance divided by the sum of abundances of all species in the
23 community.

24 Lewis (1978) used Definition 1 as part of a definition of succession, and measuring the rate of change in relative
25 abundances is an important aspect of testing theories about succession (e.g. Boit and Gaedke, 2014; Walker and
26 Wardle, 2014). However, in this manuscript I avoid the term “succession”, because it has been associated with a
27 much wider set of changes in communities and ecosystems (Odum, 1969). A number of measures of the rate of
28 shape change have been proposed (Jassby and Goldman, 1974; Lewis, 1978; Foster and Tilman, 2000), and measures
29 developed for other purposes (Field et al., 1982; Legendre and Gallagher, 2001) have also been used to measure
30 shape change. Nevertheless, there has been little systematic consideration of how such a measure should behave, or
31 of the connection to size change. I believe that the field would benefit from the kind of systematic approach that
32 has been applied to measures of evenness (e.g. Smith and Wilson, 1996) and other aspects of diversity (e.g. Jost,
33 2007; Leinster and Cobbold, 2012).

34 In this paper, I first outline the properties that a measure of rate of shape change should have. This gives
35 a rough idea of how a suitable measure can be derived. After deriving such a measure, I show that it has two
36 simple interpretations: first, as proportional to the Aitchison distance (Aitchison, 1992) between two sets of relative
37 abundance data; and second, as the among-species sample standard deviation of mean proportional population
38 growth rates over a finite time period. Note that the proportional growth rate for a species with positive abundance
39 $x(t)$ at time t is defined as $(1/x)dx/dt$, assuming that $x(t)$ is differentiable with respect to t^1 . I define the growth
40 space of a community as a real space whose axes represent proportional growth rates of each species. I show that
41 the new measure of rate of shape change and the Living Planet Index (Loh et al., 2005) are proportional to the
42 lengths of projections onto orthogonal subspaces of growth space, and thus measure distinct aspects of community
43 dynamics. The geometry of growth space leads to the results that body size, generation time and environmental
44 variability have no necessary connection to the rate of shape change. I illustrate the calculation of the rate of shape

¹Widely-used near-synonyms include ‘per capita growth rate’ and ‘specific growth rate’. However, ‘per capita’ is not strictly appropriate when individuals are not well defined (e.g. clones, colonies) or not measured (e.g. proportional cover, biomass), and the term ‘proportional growth rate’ agrees with the usages ‘proportional change’ and ‘proportional scale’, which are important in this context.

Table 1: Notation. Major symbols used in both main text and appendices. Quantities for which no dimensions are indicated are dimensionless. Abundances are shown as dimensionless here, although in some cases they will have dimensions such as numbers per unit area.

Symbol	Meaning	Dimensions
c_i	observed count of the i th species	
k_1	number of species present at start and end of a time interval	
k_2	number of species present at start but absent at end of a time interval	
k_3	number of species absent at start but present at end of a time interval	
k_4	number of species absent at start and end of a time interval	
\mathbf{M}	an $n \times n$ diagonal matrix with positive diagonal elements m_i	
n	number of species	
p_i	relative abundance $x_i / (\sum_{j=1}^n x_j)$ of the i th species	
\mathbf{q}	projection of \mathbf{r} onto the subspace orthogonal to line of equal proportional growth rates	T^{-1}
r	proportional growth rate $(1/x)dx/dt$	T^{-1}
$\tilde{r}_i(t, t + \Delta t)$	mean proportional growth rate over time interval $(t, t + \Delta t]$	T^{-1}
\mathbf{r}	vector of proportional growth rates (or mean proportional growth rates)	T^{-1}
\bar{r}	among-species sample mean of mean proportional growth rates	T^{-1}
s_r	among-species sample standard deviation of mean proportional growth rates	T^{-1}
\mathcal{S}_1	set of species present at start and end of a time interval	
\mathcal{S}_2	set of species present at start but absent at end of a time interval	
\mathcal{S}_3	set of species absent at start but present at end of a time interval	
\mathcal{S}_4	set of species absent at start and end of a time interval	
t	time	T
Δt	a time interval (not necessarily small)	T
θ	angle between \mathbf{r} and line of equal proportional growth rates	
\mathbf{u}	projection of \mathbf{r} onto the line of equal proportional growth rates	T^{-1}
v_{ij}	ratio of abundances x_i/x_j of a pair of species at a given time	
\mathbf{v}	vector of abundance ratios v_{ij}	
w_k	mean proportional rate of change in the k th abundance ratio in \mathbf{v}	
\mathbf{w}	vector of mean proportional rates of change in abundance ratios in \mathbf{v}	
x_i	abundance of the i th species	
\mathbf{x}, \mathbf{y}	abundance vectors for a set of species	
ψ	the surreal number $\omega^{1/\omega}$	
ω	simplest surreal number greater than all positive real numbers	

45 change using data on hoverflies in a garden in Leicester, UK. I then extend the approach to deal with colonization
46 and extinction, making use of the surreal number system, which includes quantities further from and closer to
47 zero than any real number (Conway, 2001). The surreal numbers are useful because, for example, an extinction
48 should represent a larger change than any reduction in abundance that does not involve extinction, and yet such
49 reductions can lead to arbitrarily large real numbers. I apply this extended method to the higher plant community
50 on the volcanic island of Surtsey. Finally, I discuss the hypothesis that phylogenetically-restricted assemblages will
51 show a relatively high proportion of size change compared to diverse communities. Notation used throughout is
52 summarized in Table 1.

53 2. Properties of a measure of rate of shape change

54 In this section, I list the properties that I believe a measure of the rate of shape change should have in order to
55 match up with biological intuition. If we accept these properties, we will know a lot about what a suitable measure
56 should look like, even before we have attempted to derive it. It is of course true that others might choose a different

57 list of properties, and thus arrive at measures that will be useful for different purposes.

58 Property 1. By Definition 1, the rate of shape change should be expressible as a function of relative abundances
59 and time alone. Although not explicit in the definition, I will here be concerned with scalar measures of
60 rate (in physical terms, “speed” rather than “velocity”). This is needed because one will often want to
61 make comparisons of rates between communities containing different sets of species, which cannot be
62 done if the rate has multiple components, each associated with a particular species or group of species.
63 If the community consists of n species (not all of which may be observed at a particular time), then
64 denote by $x_i \geq 0$ a measure of the abundance of the i th species, $i = 1, 2, \dots, n$. The abundances of
65 all species in the community at time t can then be represented as a column vector $\mathbf{x}(t) \in \mathbb{R}_{\geq 0}^n$ (the
66 n -dimensional space of positive real numbers).

67 The relative abundance of the i th species at time t is $p_i(t) = x_i(t) / \sum_{j=1}^n x_j(t)$. The set of relative
68 abundances for all species is also known as a composition, and is a vector in the unit simplex \mathbb{S}^{n-1} .
69 Although it is necessary that a rate of shape change can be expressed in terms of relative abundances
70 and time alone, many other necessary properties are easier to interpret in terms of absolute abundances.

71 Property 2. The rate should be a mean rate of change over a finite time interval. This is required if such a rate is
72 to be calculated from observations taken at discrete points in time. Furthermore, it is often useful to
73 average out stochastic variability in community composition, so as to focus on underlying trends.

Given observations at the start and end of a time interval $(t, t + \Delta t]$ and the intuitive concept of speed,
the rate of shape change should be a function of the form

$$f(\mathbf{x}(t), \mathbf{x}(t + \Delta t), \Delta t) = \frac{1}{\Delta t} g(\mathbf{x}(t), \mathbf{x}(t + \Delta t)).$$

74 This means that we need only find a suitable way of measuring the difference between two abundance
75 vectors.

76 Property 3. Defining shape change as change in relative rather than absolute abundances (Definition 1) means that
77 it should not be altered if all abundances at a given time are multiplied by a constant. In other words,

$$g(\mathbf{x}, \mathbf{y}) = g(\phi \mathbf{x}, \rho \mathbf{y}), \quad \phi > 0, \rho > 0. \quad (1)$$

78 Any function of a composition satisfying Equation 1 is expressible in terms of ratios of the form x_i/x_j
79 (Aitchison, 1992). This property also means that we can work with samples from which absolute
80 abundance data are not available (which can apply to everything from light traps to environmental
81 sequencing).

82 Property 4. If no net change has occurred over a time interval, the rate of shape change over that interval should be

83 zero. Intuitively, if all the abundances are unchanged, a measure that depends only on those abundances
 84 and the time interval should also be unchanged. In other words,

$$g(\mathbf{x}, \mathbf{x}) = 0. \tag{2}$$

Property 5. The rate of shape change should be non-negative. Intuitively, the community is different in some way
 if any of the relative abundances have changed, and a measure of the “speed” of change over some time
 interval should be positive if any change has occurred. In other words,

$$g(\mathbf{x}, \mathbf{y}) \geq 0.$$

85 Properties 4 and 5 together imply that the rate of shape change cannot be additive over subintervals.
 86 Suppose that over two successive subintervals we move from \mathbf{x} to $\mathbf{y} \neq \mathbf{x}$ and then back to \mathbf{x} . From
 87 property 4, the net change over the combined interval is $g(\mathbf{x}, \mathbf{x}) = 0$. From property 5, the net change
 88 over each of the subintervals is positive.

Property 6. If all species have the same proportional growth rate, relative abundances do not change, and the
 rate of shape change should be zero. This is the important special case of a deterministic neutral
 community. If Equations 1 and 2 hold, setting $\mathbf{y} = \mathbf{x}$ in Equation 1 shows that this will be the case.
 In all other cases, the rate should not be zero. In other words,

$$g(\mathbf{x}, \mathbf{y}) = 0 \text{ if and only if } \mathbf{y} = \phi\mathbf{x}, (\phi > 0).$$

89 Property 7. The rate of shape change should be the same for all abundance trajectories having the same vector of
 90 proportional changes over some specified time interval. This is both the most important and the most
 91 difficult requirement to grasp, and is needed in order to make the rate of shape change consistent with
 92 the way in which population growth is measured.

93 For a single species, the same amount of proportional growth has occurred if the population of that
 94 species increases from 1 to 10 as if it increases from 10 to 100 units. This can be justified at the individ-
 95 ual level by considering the population as a birth-death process. If the population changes by the same
 96 proportion in each case, then any individual experiences the same balance between proportional birth
 97 and death rates. Similarly, for a set of three species, the amount of proportional change from $[1, 1, 1]'$
 98 (where the prime denotes transpose) to $[1.1, 0.9, 1.2]'$ is the same as from $[10, 10, 10]'$ to $[11, 9, 12]'$, and
 99 from $[1, 10, 1]'$ to $[1.1, 9, 1.2]'$. Thus, we require,

$$g(\mathbf{x}, \mathbf{y}) = g(\mathbf{M}\mathbf{x}, \mathbf{M}\mathbf{y}) \tag{3}$$

100 for all $n \times n$ matrices \mathbf{M} with positive diagonal elements m_i and zero off-diagonal elements. In other

101 words, there is an equivalence class consisting of all pairs (\mathbf{x}, \mathbf{y}) such that for all $i \in 1, \dots, n$, $y_i/x_i = m_i$
102 for some species-specific constants m_i . Since multiplication by \mathbf{M} corresponds to a scaling transfor-
103 mation with factors m_1, m_2, \dots, m_n , a function satisfying Equation 3 may be called scaling invariant².
104 Figure 1 explains scaling invariance visually. Consider any arbitrary abundance trajectory (left, dashed
105 lines, here shown for three species), with two abundance vectors \mathbf{x} and \mathbf{y} lying on this trajectory, sep-
106 arated by time Δt . Applying the scaling \mathbf{M} to the entire trajectory transforms \mathbf{x} and \mathbf{y} to $\mathbf{M}\mathbf{x}$ and
107 $\mathbf{M}\mathbf{y}$ respectively (right). A function is scaling invariant if its value is unchanged by the action of any
108 scaling matrix \mathbf{M} with positive diagonal elements on any two abundance vectors \mathbf{x} and \mathbf{y} .

109 Scaling invariance is important theoretically if we want to take an organism-centred view of temporal
110 dynamics. For any species, level sets in niche space are sets of points for which the species has the same
111 proportional growth rate, and therefore experiences an environment of equivalent quality. This idea
112 extends the concept of the Hutchinson niche, which is bounded by the level set of zero proportional
113 growth rate (Maguire, 1973). A scaling \mathbf{M} applied to an abundance trajectory does not alter the
114 proportional growth rate for any species at any time, and therefore should not alter a measure that
115 tells us about how organisms experience change.

116 An unrelated but important practical consequence of scaling invariance is that there is no need to
117 measure abundance in the same units for every species, provided that the same units are used for a
118 given species at all time points. For example, the abundance of one species could be measured in
119 percentage cover, and that of another species in numbers trapped in a pitfall trap, without affecting
120 the value of a scaling invariant measure of rate of change. In this case the matrix \mathbf{M} can be thought of
121 as representing the conversion factors needed to put all abundances in the same units, and if Equation
122 3 holds, \mathbf{M} does not need to be known. Similarly, if detection probabilities differ among species but
123 remain constant over time, they do not affect the value of a scaling invariant measure of rate of change
124 (although if detection probabilities change over time in different ways for different species, such a
125 measure will be affected).

126 There is one obvious objection to the idea that change should be measured on a proportional scale: it
127 might be argued that the proportional scale gives too much weight to rare species. Many important
128 properties of communities and ecosystems can be approximated as functions of abundance. Examples
129 include the structural complexity of the community, the rate of primary production, and the conserva-
130 tion value of the community. The simplest plausible functions relating these properties to abundance
131 are linear combinations of abundances, where each species has a weight that measures the contribution

²The term used in compositional data analysis is perturbation invariant (e.g. Aitchison, 1992; Egozcue et al., 2003), but in ecology this is likely to cause confusion with the idea of a perturbation as a disturbance to a system. Note that scaling invariance is distinct from Property 3, which is sometimes called scale invariance.

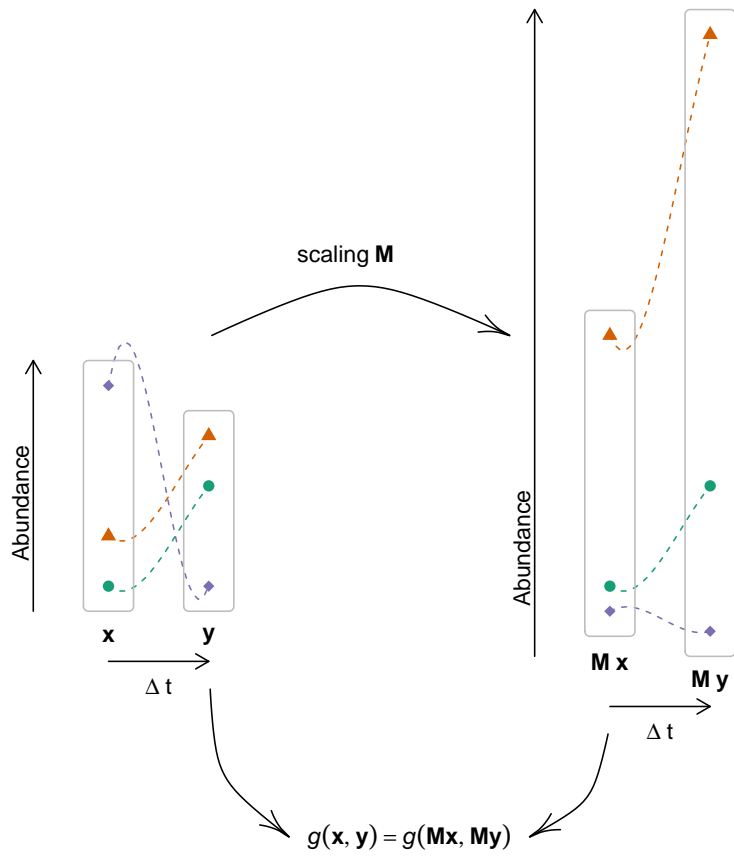


Figure 1: Scaling invariance (Property 7). Left: arbitrary abundance trajectory for three species represented as dashed lines, with abundance on the vertical axis and time on the horizontal axis. Abundance vectors \mathbf{x} and \mathbf{y} lie on this trajectory, separated by time Δt (circle, triangle and diamond symbols represent the three abundances in each vector). Applying the scaling \mathbf{M} to the whole trajectory leads to corresponding abundance vectors \mathbf{Mx} and \mathbf{My} (right). If the function $g(\mathbf{x}, \mathbf{y})$ is scaling invariant, then it is unchanged by the action of the scaling \mathbf{M} .

132 of a unit of abundance of that species to the function (e.g. Gross and Cardinale, 2005). If the abun-
133 dance of a rare species is doubled, many of these properties might be almost unchanged. In contrast,
134 doubling the abundance of a common species might result in large changes in these properties.

135 There are two answers to this objection. First, a scaling invariant function must give equal weight
136 to every species (Appendix D). Thus, the decision to take an organism-centred view of temporal
137 dynamics (which leads to scaling invariance) precludes also taking the ecosystem function-centred view
138 outlined above. Second, I believe that if changes in ecosystem function are of interest, they should
139 be studied directly, rather than through using change in abundances as a surrogate. Rare species will
140 sometimes be important to ecosystem function. For example, a rare but very large tree species might
141 have a big effect on structural complexity, a rare keystone predator might have a big indirect effect
142 on primary production, and a rare but endangered organism such as a rhinoceros might have a big
143 effect on conservation value. Thus, it is meaningless to talk about a measure that gives “too much
144 weight” to a rare species unless the right weight to give each species is known. If the weights are
145 known, the appropriate function can be studied. If the weights are unknown, studying abundances will
146 be misleading. Even the simplest families of population growth models such as the exponential and the
147 logistic are not closed under addition (Kingsland, 1985, p. 89). Thus, a weighted sum of abundances
148 of populations, each growing according to a different member of such a family, will have qualitatively
149 different behaviour from any member of the family. In summary, changes in abundance should be
150 studied only if they are of interest in their own right, not as a surrogate for some other property.

151 Exponential growth is an important idealized case in population dynamics, playing a similar role in
152 population biology to that of a body with no forces acting on it in Newtonian physics (Ginzburg
153 and Colyvan, 2004, chapter 6). It also provides an easy way to demonstrate whether a measure of
154 the rate of shape change could be scaling invariant. In this special case, each population experiences
155 an environment of constant quality, and grows at a constant proportional rate. In other words all
156 relevant aspects of the system have either zero or non-zero but constant proportional rates of change.
157 A necessary but not sufficient condition for scaling invariance is that a measure of the rate of shape
158 change is constant over time when every species is growing exponentially (Appendix A). The measures
159 of rate of shape change in common use (Jassby and Goldman, 1974; Lewis, 1978; Field et al., 1982;
160 Foster and Tilman, 2000; Legendre and Gallagher, 2001) are not constant over time under exponential
161 growth (Figure 2A and Appendix B), and are therefore not scaling invariant. For example, it is easy to
162 see that measures of the rate of shape change based on squared (Foster and Tilman, 2000) or absolute
163 (Lewis, 1978) differences in composition will not be invariant under constant proportional changes in
164 composition resulting from exponential growth.

165 The arguments above do not need the assumption that exponential growth is common in nature. Any

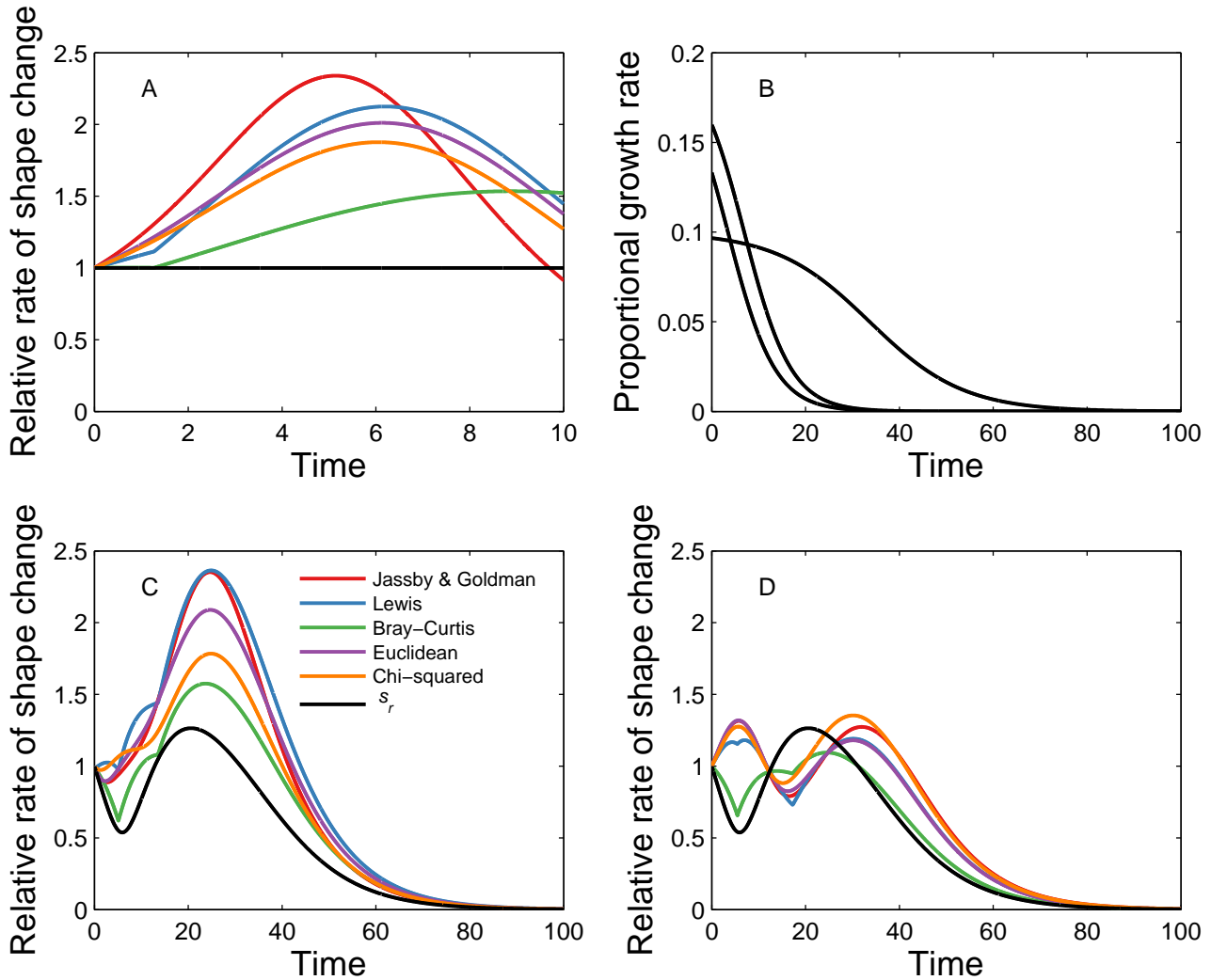


Figure 2: A: relative rate of shape change against time for three species growing exponentially, as measured by s_r (black line, Equation 5, the among-species standard deviation of proportional growth rates) and five existing measures of rate of shape change (Jassby and Goldman, 1974; Lewis, 1978; Field et al., 1982; Foster and Tilman, 2000; Legendre and Gallagher, 2001, red, blue, green, purple, orange, respectively, as in panel C key). B: proportional growth rate $[(1/x_i)dx_i/dt]$ against time for three species growing logistically. C: relative rate of shape change against time for three species growing logistically as in panel B. D: relative rate of shape change against time for three species growing logistically, as in panel B except that initial abundances and carrying capacities (and all abundances on the trajectory between these points) are scaled by $\mathbf{M} = \text{diag}(1/3, 1/9, 1/2)$, keeping proportional growth rates constant. In A, C, and D: Euclidean is $1/\Delta t$ times the distance in Foster and Tilman (2000); Chi-squared is $1/\Delta t$ times the distance in Legendre and Gallagher (2001); Bray-Curtis is $1/\Delta t$ times the distance in Field et al. (1982), calculated on relative abundances with a $1/4$ power transform; constant time interval $\Delta t = 0.001$ between observations; each measure of rate of shape change is plotted relative to its value over the first time interval. Parameters for A: initial abundances $[0.5, 0.1, 0.4]'$; proportional growth rates $[-0.2, 0.2, -0.1]'$. Parameters for B and C: initial abundances $[1, 0.3, 0.4]'$, proportional growth rates at low abundance $[0.2, 0.1, 0.2]'$, carrying capacities $[3, 9, 2]'$. Parameters for D: initial abundances $[1/3, 1/30, 1/5]'$, proportional growth rates at low abundance $[0.2, 0.1, 0.2]'$, carrying capacities $[1, 1, 1]'$.

two patterns of growth resulting in the same pattern of proportional change over a given time interval should correspond to the same rate of shape change, no matter what trajectories the populations involved followed to get from the start to the end of the interval.

Property 8. A measure of the rate of shape change should not depend (in a statistical sense) on the number of species being studied. This is important for two reasons. First, it is usually impossible to measure the abundance of every species in the community. If instead we have abundances for a random sample of species, then a measure whose expected value does not depend on the number of species sampled can be used to estimate the rate of shape change in the entire community. In general, it will be difficult to obtain a random sample of species. Selecting species at random from a complete species list is rarely possible. Choosing individuals at random and identifying them does not give a random sample of species, because more abundant species are more likely to be included in the sample. In practice, available data are often used without any attempt at random sampling (e.g. Collen et al., 2013, p. 72). Nevertheless, independence of the number of species studied remains a desirable statistical property. Second, we will often want to compare communities with different numbers of species. Other things being equal, there is no intuitive reason why a change in the number of species should be associated with a change in the rate of shape change.

3. A new measure of rate of shape change

In what follows, I initially restrict attention to cases where there is no colonization or extinction, so that all abundances are positive. I later show how to deal with colonization and extinction in a way that is consistent with the approach taken below.

Consider a single species with abundance $x(t)$ at time t , where $x(t)$ is a differentiable, positive function of time, and proportional growth rate $(1/x)dx/dt$. The mean proportional growth rate over the time interval $(t, t + \Delta t]$ is

$$\tilde{r}(t, t + \Delta t) = \frac{1}{\Delta t} \int_t^{t+\Delta t} \frac{1}{x} \frac{dx}{du} du = \frac{\log x(t + \Delta t) - \log x(t)}{\Delta t}, \quad x > 0, \quad (4)$$

(throughout, \log denotes the natural logarithm). The requirement that $x(t)$ is differentiable is not much of a limitation, because even in stochastic models where abundance may not be differentiable, there is usually a differentiable expected abundance to which we can apply Equation 4. The mean proportional growth rate is obviously a constant for all abundance trajectories resulting in the same amount of proportional growth over a given time interval. I show in Appendix C that the natural generalization of Equation 4 to a scalar measure of the rate of shape change is the among-species sample standard deviation of mean proportional growth rates,

$$s_r = \left[\frac{1}{n-1} \sum_{i=1}^n (\tilde{r}_i(t, t + \Delta t) - \bar{r}(t + \Delta t))^2 \right]^{1/2}, \quad (5)$$

194 where $\tilde{r}_i(t, t + \Delta t)$ is the mean proportional growth rate of the i th species over the time interval $(t, t + \Delta t]$, and
 195 $\bar{r}(t, t + \Delta t)$ is the among-species mean of mean proportional growth rates over this interval:

$$\bar{r}(t, t + \Delta t) = \frac{1}{n} \sum_{i=1}^n \tilde{r}_i(t, t + \Delta t). \quad (6)$$

196 I show in Appendix C that Equation 5 satisfies Properties 1 to 8 (although Property 8 is only satisfied asymptotically).
 197 In particular, this measure is scaling invariant, unlike existing measures of the rate of shape change. For
 198 example, the black line in Figure 2A is the value of s_r for a numerical example in which all species are growing
 199 exponentially. I show in Appendix C that Equation 5 is proportional to the Aitchison distance between the relative
 200 abundances at two time points. The Aitchison distance is the standard measure of distance between compositions
 201 (Aitchison, 1992; Egozcue et al., 2003). Finally, I show in Appendix C that Equation 5 can also be expressed in
 202 terms of relative abundances:

$$s_r = \frac{1}{\Delta t} \left[\frac{1}{n(n-1)} \sum_{i=1}^{n-1} \sum_{j=i+1}^n \left(\log \left(\frac{p_i(t + \Delta t)}{p_j(t + \Delta t)} \right) - \log \left(\frac{p_i(t)}{p_j(t)} \right) \right)^2 \right]^{1/2}. \quad (7)$$

203 Although I have shown that s_r is scaling invariant while a number of other proposed measures of shape change
 204 are not, one might wonder whether there are other possible scaling invariant measures of shape change. In Appendix
 205 D, I show that any scaling invariant function is a function of the vector \mathbf{r} of mean proportional growth rates. Among
 206 such functions, a function proportional to the Aitchison distance is in some sense the simplest way to measure change
 207 in relative abundances (Aitchison, 1992).

208 4. A logistic growth example

209 In this section, I illustrate how s_r and existing measures of the rate of shape change behave in the simple
 210 case of logistic growth. Exponential growth is defined by constant proportional growth rates. Under patterns of
 211 growth other than exponential, proportional growth rates do not remain constant over time, and so the rate of
 212 shape change should not in general be constant. For example, Figure 2B shows proportional growth rates for three
 213 species under logistic growth, and Figure 2C shows the corresponding values of s_r (black line) and several existing
 214 measures of rate of shape change. Applying any non-identity scaling to the abundance trajectories (for example,
 215 $\mathbf{M} = \text{diag}(1/3, 1.9, 1/2)$) leaves the proportional growth rates (Figure 2B) and s_r (Figure 2D, black line) unchanged,
 216 but causes qualitative changes in existing measures of the rate of shape change (Figure 2D, red, blue, green, purple
 217 and orange lines). In Figure 2D, the Jassby and Goldman, Lewis, Bray-Curtis, Euclidean and chi-squared measures
 218 have local minima just before time 20, which are absent in Figure 2C. All these measures can also differ qualitatively
 219 from s_r . In Figure 2D, the Jassby and Goldman, Lewis, Euclidean and chi-squared measures have local maxima
 220 close to the time at which s_r has its first local minimum, and the Bray-Curtis measure has a local minimum close
 221 to the time at which s_r has its first local maximum. It is also obvious from Figure 2C and D that rates of shape
 222 change need not be decreasing functions of time, even under very simple models of population growth. It has been

223 suggested that during succession, “rate-of-change curves are usually convex, with change occurring most rapidly at
224 the beginning” (Odum, 1969) for a wide range of ecosystem properties. The results in Figure 2 suggest that if real
225 communities typically have decreasing rates of shape change over time, some biologically interesting mechanism
226 must be generating them.

227 5. Shape change and biodiversity trends

228 In this section, I show the geometric connection between the new measure of rate of shape change (Equation
229 5) and three high-profile measures of biodiversity trends. This connection is a major strength of s_r , not shared
230 by existing measures of the rate of shape change. I consider three major measures of biodiversity trends: the the
231 Living Planet Index (Loh et al., 2005), which measures global changes in vertebrate populations; the UK Wild Bird
232 Indicators (Buckland et al., 2011), which measures changes in UK bird populations; and the Watchlist Indicator,
233 which measures population trends in 155 species of birds, mammals, butterflies, and moths of conservation priority
234 in the United Kingdom (Burns et al., 2013, pages 10 and 81). All these measures are based on the exponential of the
235 among-species mean of mean proportional growth rates. They reveal patterns of major conservation importance,
236 such as the mean 25% decline in terrestrial vertebrate populations between 1970 and 2000 (Loh et al., 2005), and
237 the mean 77% decline in species of conservation priority in the United Kingdom between 1970 and 2010 (Burns
238 et al., 2013, p. 10).

239 Such declines do not necessarily involve shape change in the sense of Definition 1: if all species decline at the
240 same rate, fewer organisms are present in total, but their relative abundances are unchanged. To understand the
241 connection between shape change and these measures of biodiversity trends, I introduce the idea of the growth
242 space of a community. For a given set of species, every vector of proportional growth rates can be represented as a
243 point in a space \mathbb{R}^n which I refer to as the growth space of the community (Figure 3 is a two-dimensional example).
244 In the following I drop the time indexing for simplicity. The line $r_1 = r_2 = \dots = r_n$ in growth space represents
245 a deterministic neutral community, in which all species have the same proportional growth rate and the rate of
246 shape change is zero (Property 6). The growth rate vector \mathbf{r} can be decomposed into two orthogonal components
247 (Appendix C). The first component \mathbf{u} is the projection of \mathbf{r} onto the line of equal proportional growth rates, which
248 represents change in abundance without shape change. The among-species mean of mean proportional growth rates
249 (Equation 6) is proportional to the length of this component and is a natural measure of size change. Size change
250 is therefore essentially the same as the natural log of the measures of biodiversity trends described above. This
251 component is important because change purely in the $r_1 = r_2 = \dots = r_n$ direction represents balanced exponential
252 growth, a state disallowed by the standard Lotka-Volterra model of consumer-resource dynamics, but possible under
253 ratio-dependent dynamics (Arditi and Ginzburg, 2012, section 6.1).

254 However, it is unlikely that precisely balanced growth will occur in a real community. The length of the second
255 component \mathbf{q} measures the extent to which growth is unbalanced. It represents change in relative abundance (shape)

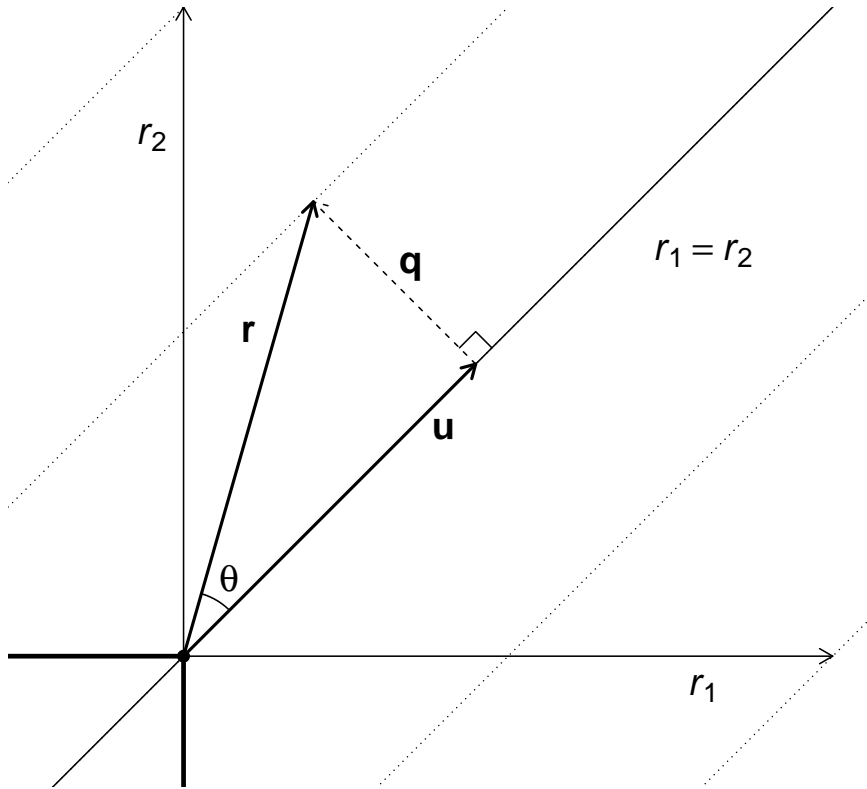


Figure 3: Geometric interpretation of the rate of shape change in a two-species community. The axes r_1 and r_2 are the proportional growth rates of the two species. The position vector \mathbf{r} represents the mean proportional growth rates for a given time interval. The diagonal line $r_1 = r_2$ represents equal proportional growth rates, and therefore no shape change. The vector \mathbf{u} is the projection of \mathbf{r} onto the $r_1 = r_2$ line. It represents the rate of change of size of the community, and each of its elements equals the among-species mean of mean proportional growth rates. The norm of the projection \mathbf{q} of \mathbf{r} onto the subspace orthogonal to the $r_1 = r_2$ line represents change in shape of the community, and is proportional to the among-species standard deviation of mean proportional growth rates. The square of the cosine of angle θ is change in size as a proportion of total change. All the internal equilibria are mapped to the origin (black dot). On the bold half-lines ($r_1 < 0, r_2 = 0$) and ($r_1 = 0, r_2 < 0$), one species declines while the other remains at constant abundance. The dotted lines are contours of constant rate of shape change, with the rate increasing away from the $r_1 = r_2$ line.

256 and is proportional to the among-species standard deviation of mean proportional growth rates (Equation 5). The
257 orthogonality of these two components implies that the proposed measure of rate of shape change is distinct from
258 measures of biodiversity trends such as the Living Planet Index (Loh et al., 2005), the UK Wild Bird Indicators
259 (Buckland et al., 2011), and the Watchlist Indicator (Burns et al., 2013).

260 Two further quantities can be obtained from Figure 3. First, the total amount of change in a community is the
261 norm $\|\mathbf{r}\|$ of the vector \mathbf{r} . This norm is zero if the community is at equilibrium, and positive otherwise. I refer to it
262 as the “activity” level of the community (with dimensions time^{-1}). To make comparisons among communities, the
263 scaled activity $n^{-1/2}\|\mathbf{r}\|$ is useful because its expected value does not depend on the number of species sampled.
264 Second, $\cos^2 \theta = (\|\mathbf{u}\|/\|\mathbf{r}\|)^2$ (Figure 3) measures the proportion of change that is size change. The value of $\cos^2 \theta$
265 is a useful way of comparing the dynamics of communities because it is dimensionless, and does not depend on
266 the number of species in the community. In terms of linear models, $\cos^2 \theta$ is the coefficient of determination for a
267 one-dimensional linear model containing only a mean term (Saville and Wood, 1991, p. 410).

268 6. Properties of growth space

269 The geometry of growth space makes it easy to visualize some properties of the rate of shape change (Figure
270 3), and leads to important theoretical results. As already mentioned, the rate of shape change is zero along the
271 line $r_1 = r_2 = \dots = r_n$ (Figure 3, solid line). Thus, the community can increase or decrease in total abundance
272 without shape change, by remaining on this line. Lines parallel to the $r_1 = r_2 = \dots = r_n$ line (Figure 3, dotted
273 lines) have constant rate of shape change, increasing away from the $r_1 = r_2 = \dots = r_n$ line in each direction. At
274 the origin ($r_1 = r_2 = \dots = r_n = 0$, Figure 3, black dot), corresponding to all the equilibria of the system, there is
275 no shape change and no growth. The bold half-lines in Figure 3 (excluding the origin) consist of points for which
276 some proportional growth rates are zero and others are negative. If all species had positive abundance for such a
277 community, and growth rates remained at a fixed point on the bold half-lines, the community would asymptotically
278 approach a boundary equilibrium at which the species with negative growth rates were absent. Since such points
279 do not lie on the $r_1 = r_2 = \dots = r_n$ line, the rate of shape change would not go to zero as the equilibrium
280 was approached (although such situations are unlikely to be common, and species with very low abundance would
281 eventually go extinct, as discussed later).

282 Similar but more complicated cases may also occur. In a Lotka-Volterra competition model for proportional cover
283 of six components in a coral reef system (Spencer and Tanner, 2008), the abundance of macroalgae and pocilloporid
284 corals is very close to zero from around 25 years onwards (Figure 4A, green and orange lines respectively). The
285 proportional growth rates of these two components have large but fluctuating negative values (Figure 4B, green
286 and orange lines respectively), while the proportional growth rates for the other components are much closer to
287 zero. In growth space, the system is approximately moving relatively far from zero in the $(-, -)$ quadrant of a
288 plane on which all components other than macroalgae and pocilloporid corals have zero proportional growth rates.

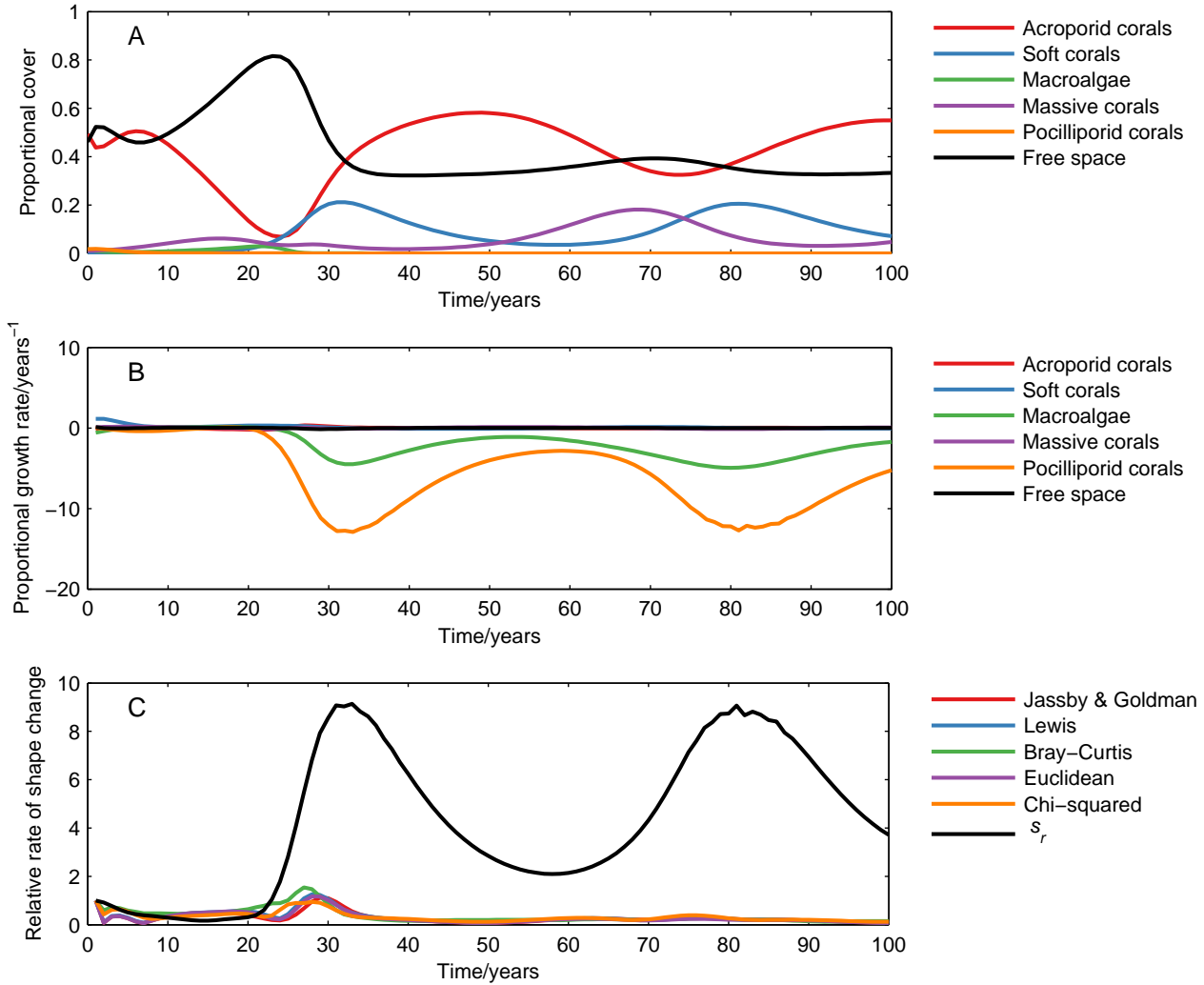


Figure 4: A: changes in proportional cover over time in a 6-component Lotka-Volterra competition model for a coral reef system (Heron Island, Protected Crest site). Parameter estimates from Table 2 in Spencer and Tanner (2008). B: Mean proportional growth rates (over one-year intervals) against time for the data in A. C: s_r (black line, Equation 5) and five existing measures of rate of shape change (red, blue, green, purple, orange, respectively: Jassby and Goldman, 1974; Lewis, 1978; Field et al., 1982; Foster and Tilman, 2000; Legendre and Gallagher, 2001). Each measure is plotted relative to its value in the first time interval.

289 Thus, from around 25 years onwards, the rate of shape change as measured by s_r is large, but fluctuates over time
 290 (Figure 4C, black line). Existing measures of the rate of shape do not have large values for this portion of the model
 291 output (Figure 4C, red, blue, green, purple and orange lines). They behave differently from s_r because they do not
 292 measure distance in growth space.

293 Two important theoretical results follow immediately from the geometry of growth space. First, there is no
 294 necessary connection between the typical body size and generation time for species in a community and the rate
 295 of shape change. Differences in generation time are likely to be associated with differences in body size and the
 296 among-species mean of maximum proportional growth rates (e.g. Drury and Nisbet, 1973; Tilman, 1988, p. 230).
 297 It is possible (although not necessarily true) that there are corresponding effects on mean proportional growth
 298 rates in the field. Nevertheless, it is only the among-species standard deviation of mean proportional growth rates

299 that determines how fast the relative abundances change. In consequence, there is no reason to assume that shape
300 change must be faster in, for example, a microbial community than in a forest. If shape change is generally faster in
301 microbial than plant communities (Fierer et al., 2010), it is not simply because microbes have faster growth rates.
302 Similarly, although there may be a relationship between body size and the rate of shape change, as Anderson (2007)
303 suggested in the broader context of succession, it is not a mathematical necessity.

304 Second, environmental variability *per se* need not affect the rate of shape change. Although such variability
305 may result in movement in growth space, the rate of shape change is only affected if this movement is not parallel
306 to the $r_1 = r_2 = \dots = r_n$ line. In other words, environmental variability only affects the rate of shape change if it
307 affects different species in different ways.

308 7. Example: temporal change in a hoverfly assemblage, Leicester, UK

309 The data analyzed here are a 30-year record of abundances of hoverflies (Diptera: Syrphidae) in a suburban
310 garden in Leicester, United Kingdom. A Malaise trap was used to catch flying insects from 1 April to 31 October,
311 on the same site every year from 1972 to 2001 (Owen, 2010, p. 37). Hoverflies were studied in more detail than
312 other insect groups, and annual numbers for the 14 species caught more than 1000 times in total were reported
313 (Owen, 2010, p. 88). Hoverflies in the UK have one, two, or more than two generations a year (Owen, 2010, p.
314 91), so 30 years is a relatively long time scale for this assemblage. Larvae of different species use different food
315 resources, including plant tissues, decaying organic matter, and aphids (Owen, 2010, p. 80), so the assemblage is
316 quite functionally diverse. Large, active species are thought to be trapped less efficiently than small species (Owen,
317 2010, p. 84). Therefore, existing measures of rate of shape change, which are not scaling invariant (Property 7),
318 will not be useful descriptions of these data.

319 Variation in annual counts is a combination of deterministic trends in true abundance, stochastic variation in
320 true abundance (process error) and observation error. I used a state-space model (Appendix E) to describe both
321 process and observation error, and calculated rates of change in size and shape using the expected abundances from
322 this model. The four occasions on which a zero count was recorded can plausibly be treated as observation error
323 based on a Poisson sampling model: a species which was not recorded in the trap sample in a given year is still
324 likely to have been present in the local area.

325 In Figure 5A, the logs of observed counts $c_i + 1$ are plotted against year, with one line for each species (note that
326 the $\log(c_i + 1)$ transformation is used only for plotting the data: a Poisson sampling model is used for analysis). The
327 slope of the line segment connecting the abundances of a given species in two successive years approximates the mean
328 proportional growth rate \tilde{r}_i for that species (except in the rare cases where the count was zero). Three important
329 features are immediately obvious. First, there was a general downward trend in abundances, which may be caused
330 by urbanization of surrounding agricultural land and a gradual increase in temperature (Owen, 2010, p. 229).
331 Second, there were year-to-year fluctuations of more than two orders of magnitude. Third, these fluctuations often

involved simultaneous increases or decreases in many species. Important causes of these fluctuations include warm weather in spring and summer, variation in food supply for species whose larvae feed on aphids, and immigration from surrounding agricultural land (Owen, 2010, pp. 86-87).

The size component (Figure 5B) fluctuated a lot despite the general negative trend in abundances, and there were many intervals in which it was positive (indicating that a typical species increased in abundance over that period). Note that for most of these intervals, the 95% confidence band for size change did not include zero, so that these short-term fluctuations are likely to be real, rather than a consequence of observation error. Similarly, the most obvious feature of the shape component was its variability from year to year (Figure 5C). I will return to the ecological meaning that can be extracted from these patterns after developing methods to deal with colonization and extinction.

8. Colonization and extinction

So far, I assumed that abundances are strictly positive (or at least that the underlying expected abundances are positive, if sampling zeros occurred). Even in cases where a complete census has been conducted, one could think of the set of individuals present as being a single realization of a stochastic process with positive expected abundances. Thus, treating absences as sampling zeros will usually be appropriate. Nevertheless, true zeros may occur, with a transition from a true zero to a positive abundance representing colonization and a transition from positive abundance to true zero representing extinction. Perhaps more importantly, the following analysis provides a link to related measures for presence/absence data.

If abundance x_i of some species is zero, the proportional growth rate $(1/x_i)dx_i/dt$ is undefined. This has important practical consequences. For example, the Watchlist Indicator (Burns et al., 2013) is closely related to the rate of change in size (Equation 6) for species of conservation priority. It would be undefined if one or more of the species of interest went extinct, yet such an event would be of even more concern than a decline in abundance without extinction.

Looking at the form of the mean proportional growth rate (Equation 4) suggests an approach. In the following explanation, I focus on extinction, because colonization is simply the mirror image. Intuitively, suppose that we would like an index based on a weighted sum of two terms, one reflecting changes in abundance measured on a proportional scale, and the other reflecting extinctions. The mean proportional growth rate (Equation 4) involves $\log x_i(t)$, and $\lim_{x_i(t+\Delta t) \rightarrow 0^+} \log x_i(t + \Delta t) = -\infty$. Choosing a real weight for extinctions is equivalent to adding an arbitrary constant to an observed zero, and it is in principle possible for abundance to be positive but less than this constant. Thus for every real choice of weight given to the extinction component and given initial abundance $x_i(t)$, there is a positive abundance $x_i(t + \Delta t)$ for which the magnitude of the mean proportional growth rate is greater than this weight. In other words, for any finite weight given to extinctions, there will be changes in abundance not involving extinction that count for more than changes involving extinction, which is intuitively unreasonable.

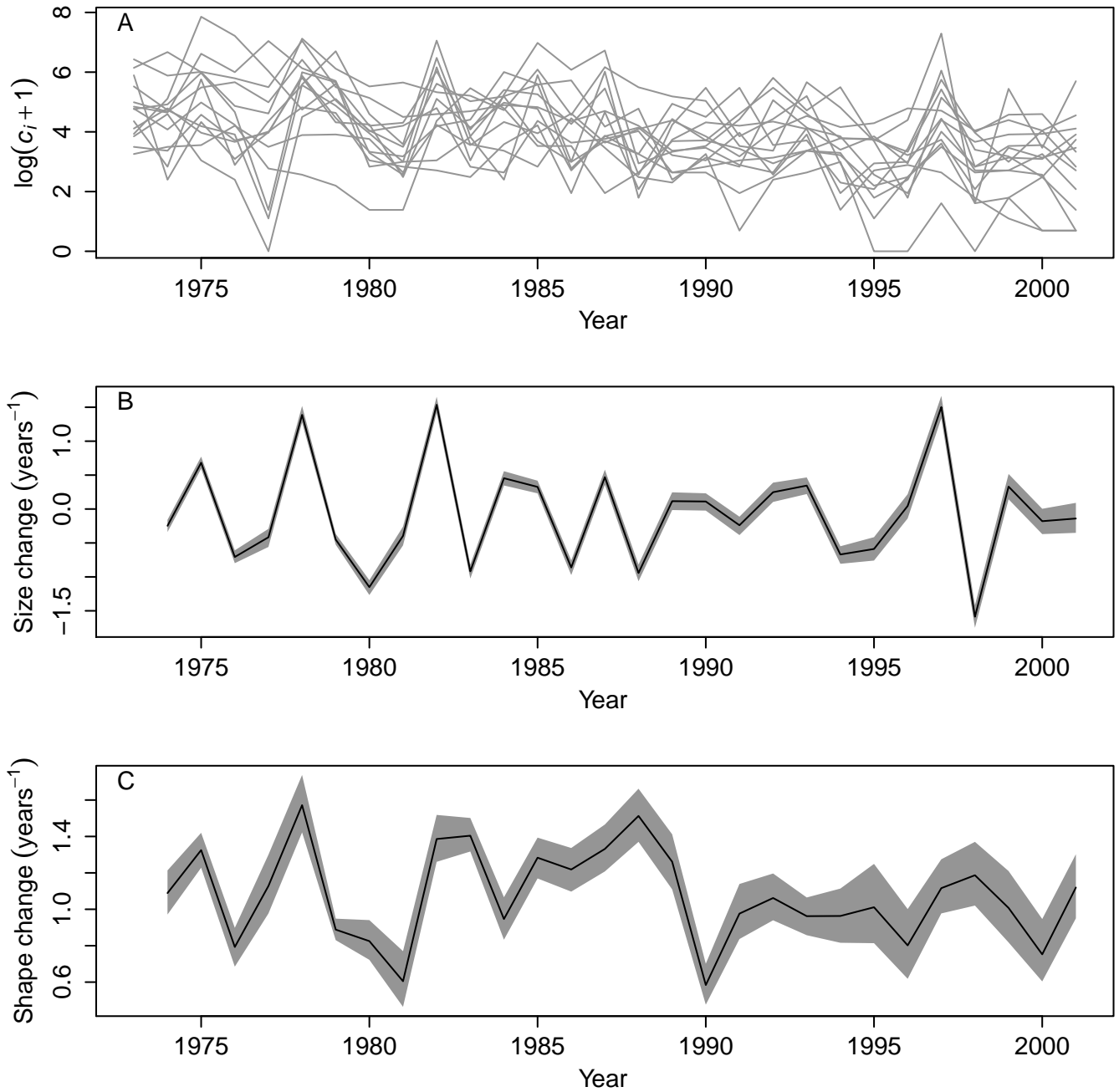


Figure 5: Dynamics of the hoverfly assemblage of a Leicester, UK garden. A: log of observed count $c_i + 1$ against time for the 14 species that were trapped more than 1000 times (one line per species). B: rate of change in size (among species mean of mean proportional growth rates \bar{r} , years⁻¹) against time. C: rate of change in shape (among-species standard deviation of mean proportional growth rates, s_r , years⁻¹) against time. In B and C, the black line is the mean estimate, and the grey area is a 95% confidence band.

365 Therefore the weight given to an extinction should have greater magnitude than any real number.

366 Simply calling the weight given to an extinction infinite is not satisfactory. Intuitively, one would like the
 367 extinction of a common species to represent a larger change than the extinction of a rare species. Also, one would
 368 like the transition from a given non-zero abundance to zero abundance to represent a more negative rate of change
 369 if it occurs over a shorter time interval Δt . Arithmetic operations involving infinite quantities are not defined in
 370 the real number field, so these properties will not hold.

371 There is a natural solution. Instead of replacing zero abundances by $\lim_{x_i \rightarrow 0^+}$, replace them by a number larger
 372 than zero but smaller than all positive real numbers. Such numbers exist in the surreal number field (Conway, 2001),
 373 and their logarithms have magnitude greater than all positive real numbers. The surreal number field contains the
 374 real numbers, but has arithmetic operations defined for infinite as well as finite numbers. These operations behave
 375 as expected when applied to real numbers. If a species has nonzero abundance at time t but zero abundance at time
 376 $t + \Delta t$, define its mean proportional growth rate as $(\log(1/\omega) - \log x_i(t))/\Delta t$, where $1/\omega$ is the simplest number
 377 that is greater than zero but smaller than all positive real numbers (Conway, 2001, p. 12). Under this definition,
 378 the mean proportional growth rate is more negative if $x_i(t)$ is larger, or if Δt is smaller, as required.

379 The size and shape components of the rate of change for a community can then be calculated as described in
 380 Appendix F. The size component becomes a surreal number with an infinite and a real part:

$$\bar{r}(t, t + \Delta t) = \frac{(k_3 - k_2)\psi}{n\Delta t} + \frac{a - b}{n\Delta t}, \quad (8)$$

381 where k_3 is the number of colonizations, k_2 is the number of extinctions, $\psi = \omega^{1/\omega}$ is the negative of the natural
 382 logarithm of $1/\omega$ (and is larger than all positive real numbers), a is the sum of log abundances for all species with
 383 nonzero abundance at time $t + \Delta t$, and b is the sum of log abundances for all species with nonzero abundance at time
 384 t . Equation 8 reduces to Equation 6 if there are no colonizations or extinctions. The coefficient of ψ in Equation 8
 385 is the among-species mean of a variable taking the values $-1/\Delta t$ for extinctions, $1/\Delta t$ for colonizations, and zero
 386 otherwise (Appendix G). If the difference between the numbers of colonizations and extinctions is not zero, the
 387 magnitude of this term will always be greater than the magnitude of the second term (the real part, proportional
 388 to $a - b$). To understand how Equation 8 works, consider a case where a community loses one species but gains
 389 another, whose final abundance is the same as the initial abundance of the lost species. No other species change
 390 abundance. Intuitively, there has been no change in size. If the species gained has lower final abundance than the
 391 species lost, there has been a reduction in size, but not as large as if a species was lost and no new species, however
 392 rare, colonized.

393 If there are extinctions and colonizations, the shape component also has infinite and real parts:

$$s_r \simeq \frac{\alpha^{1/2}\psi}{(n-1)^{1/2}\Delta t} + \frac{\beta}{2[\alpha(n-1)]^{1/2}\Delta t}, \quad (9)$$

394 where

$$\begin{aligned}\alpha &= k_2 + k_3 - \frac{1}{n}(k_3 - k_2)^2, \\ \beta &= 2 \left(\sum_{i \in \mathcal{S}_2} \log x_i(t) + \sum_{i \in \mathcal{S}_3} \log x_i(t + \Delta t) - \frac{1}{n}(a - b)(k_3 - k_2) \right),\end{aligned}\tag{10}$$

395 and \mathcal{S}_2 and \mathcal{S}_3 are the sets of species going extinct and colonizing, respectively. Equation 9 is approximate in
396 the sense that it ignores terms whose magnitude is less than any positive real number. The coefficient of ψ in
397 Equation 9 is the among-species standard deviation of a variable taking the values $-1/\Delta t$ for extinctions, $1/\Delta t$ for
398 colonizations, and zero otherwise (Appendix G). Thus the infinite part will be large if there is a lot of change in the
399 set of species present ($k_2 + k_3$ is large), but there is little change in the number of species present ($k_3 - k_2$ is small).
400 The second term in Equation 9 (the real part) will be large if the species going extinct had large abundances at
401 time t and/or the species colonizing had large abundances at time $t + \Delta t$.

402 The scaled activity level and the proportion of change that is size change in the presence of colonizations and
403 extinctions can be calculated as described in Appendix F. Because standard probability distributions are not defined
404 over the whole of the surreal number field, and there is so far no generally satisfactory definition of an integral for
405 surreal functions (Fornasiero, 2003; Rubinstein-Salzedo and Swaminathan, 2014), parametric statistical analyses of
406 these quantities would be difficult. However, surreal numbers can be ranked unambiguously (Appendix F), and
407 so statistics based on ranks of the scaled activity level and of the proportion of change that is size change are
408 straightforward.

409 If only presence/absence data are available, only the infinite terms in Equations 8 and 9 can be calculated.
410 The coefficients of these terms are natural measures of size and shape change for presence/absence data, and it is
411 not necessary to make any explicit use of the surreal number system to calculate them. Appendix G summarizes
412 the calculation of scaled activity and proportion of change that is size change from presence-absence data. The
413 measures of rate of succession from presence/absence data defined by Anderson (2007) are based on rescalings of
414 $k_2 + k_3$, which is proportional to the squared activity level from presence/absence data (Appendix G).

415 9. Example: the higher plant community on Surtsey

416 I calculated the rate of shape change s_r (Equation 9) and the among-species mean proportional growth rate
417 \bar{r} (Equation 8) for the higher plant community on the volcanic island of Surtsey, using data and background
418 information from Fridriksson (1989). The island was formed in 1963, and its higher plant community has been
419 surveyed annually since the first plant was found in 1965, initially by complete census, and later by quadrat and
420 transect samples (Fridriksson, 1987). Relatively few plant species are found on the island, because of the scarcity of
421 water, low nutrient levels, salt spray, sand abrasion, and wave action (Fridriksson, 1989). However, soil formation
422 has been fairly rapid, due to organic matter being washed ashore (Fridriksson, 1987). I used the data for 1965 to
423 1981 in Table 1 of Fridriksson (1989). Data from later years were excluded because there was no count for the most
424 abundant species after 1981. By 1981, 22 taxa had been observed, including one that was identified only to genus

425 and a category of unidentified plants. There were many zero values.

426 It is plausible that abundances were exactly known, and therefore that zeros represent true absences (at least
427 during the early part of the study, when complete censuses were made). The counts themselves can only take
428 natural number values, so cannot be differentiable functions of time. Nevertheless, it is reasonable to treat expected
429 abundances conditional on the data (which coincide with the counts at sampling times) as differentiable functions
430 of time, and therefore to calculate the rates of change in size and shape using Equations 8 and 9 respectively.

431 Figure 6A shows the logs of observed counts $c_i + 1$ against year, with the same interpretation as Figure 5A
432 when abundances were nonzero (again, the $\log(c_i + 1)$ transformation is used only for plotting, not for analysis).
433 However, colonization and extinction were major features of these data. Species arrived at different times, with
434 dispersal by birds probably the most common route (Fridriksson, 1987). Of these arrivals, most did not persist
435 or remained at low abundance, some increased in abundance and then decreased again, and one (the sandwort
436 *Honckenya peploides*, Figure 6A, black line) became numerically dominant.

437 Equation 8 gives the among-species mean \bar{r} of mean proportional growth rates, including colonizations and
438 extinctions. In Figure 6B, the dots connected by lines represent the infinite part of \bar{r} , while the lengths of the
439 arrows represent the real part (on a separate scale, magnified by a factor of 0.1ψ). The most striking feature of
440 the temporal pattern in \bar{r} is that it does not increase systematically over time, despite changes in the environment
441 that might be expected to favour plant growth. For example, over the last two time periods, the abundance of
442 the dominant species *Honckenya peploides*, and the total number of individuals, were increasing rapidly. Biomass
443 production and soil fertility, driven by inputs of fish waste and guano from seabirds, were also increasing (Fridriksson,
444 1989). Furthermore, as the abundance of *H. peploides* increased, dense stands of this plant modified the environment
445 in ways that increased the germination and survival rates of two other species (Fridriksson, 1987), an example of
446 the type of positive interaction thought to be important in facilitating succession (Bertness and Callaway, 1994).
447 Nevertheless, both the infinite and real parts of \bar{r} were lower in the last two time periods than in much of the first
448 half of the series. In other words, for a typical species, the environment was less favourable at the end than the
449 start of the time series.

450 The rate of change in shape, s_r (Equation 9) had relatively high values in the middle of the study period (Figure
451 6C). Inspection of Figure 6A shows that in the middle part of the series, there were relatively large numbers of
452 colonizations and extinctions (values of $\log(c_i + 1)$ changing to and from zero). Simultaneous colonizations and
453 extinctions tend to make the infinite part of s_r large (Figure 6C, dots connected by lines). There was little obvious
454 temporal pattern in the real part of s_r (Figure 6C, arrows, on a separate scale magnified by a factor of 0.1ψ).
455 Figure 6A shows that at most time points, there was substantial among-species variability in changes in abundance.
456 At least over this time scale, the idea that rates of shape change are decreasing over time is not supported. In
457 retrospect this is unsurprising, because as Figures 2C and D show, it is easy to construct cases in which rates of
458 change are not decreasing over time in the short term.

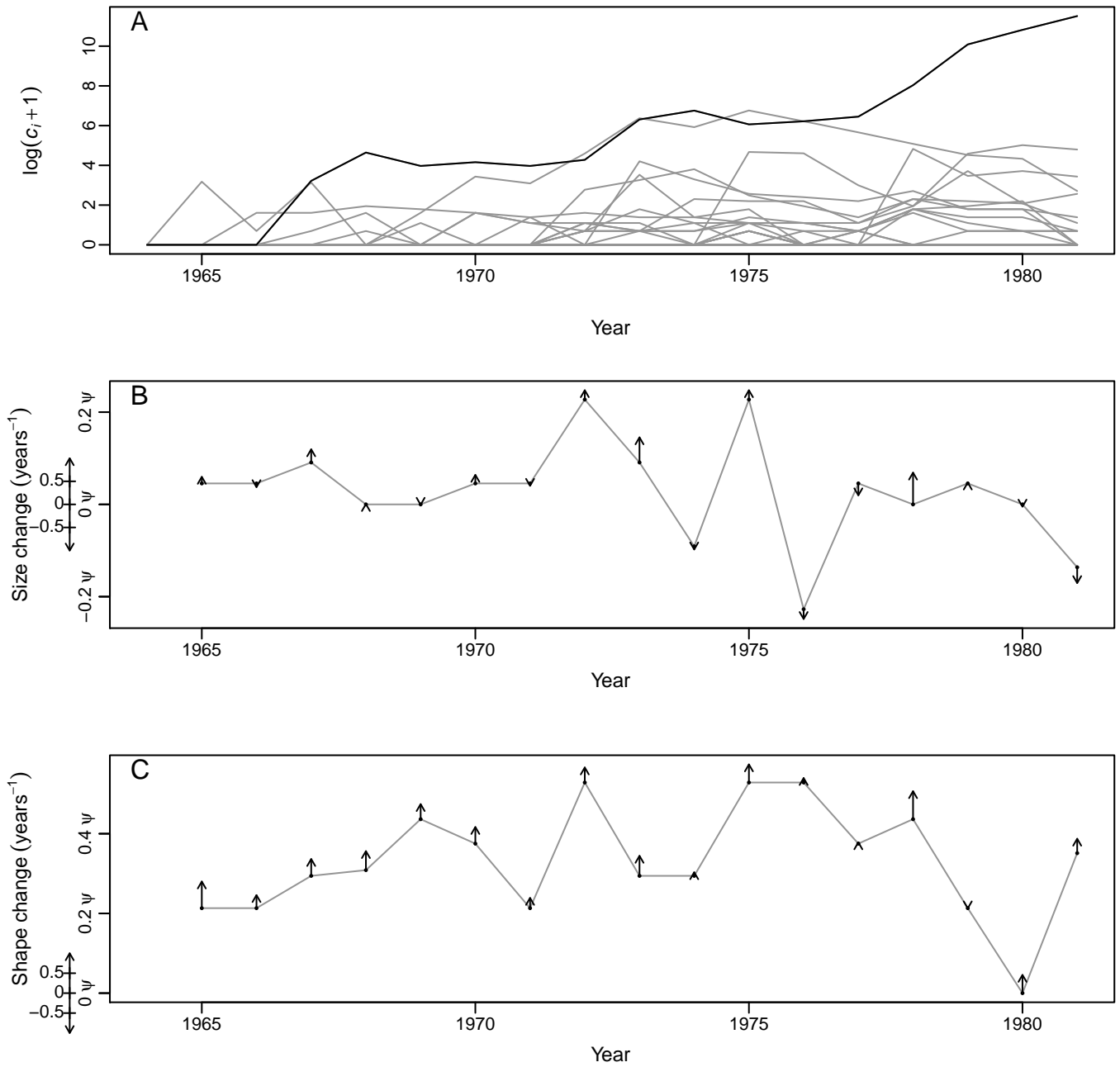


Figure 6: Higher plant community on Surtsey, 1965 to 1981. A: log of observed count $c_i + 1$ against time for each species. Black line is the dominant species *Honckenya peploides*, grey lines are other species. B: rate of change in size (among-species mean of mean proportional growth rates \bar{r} , years⁻¹) against time. Dots represent the infinite part (measured in units of ψ , main scale) and lengths of arrows represent the real part (secondary scale, magnified by 0.1ψ). C: rate of change in shape (among-species standard deviation of mean proportional growth rates, s_r , years⁻¹) against time. Infinite and real parts represented as in B.

459 The amount of change in the Surtsey plant community was almost always not commensurate with that in the
460 Leicester hoverfly assemblage, in the sense that colonization and extinction represent infinitely larger changes than
461 any change in abundance not involving such events. Nevertheless, the proportion of change that is size change
462 ($\cos^2 \theta$) can be directly compared (Figure 7). This proportion was strikingly higher for the Leicester hoverfly
463 assemblage (median 0.22, lower quartile 0.07, upper quartile 0.35) than for the Surtsey higher plant community
464 (median 0.05, lower quartile 0.02, upper quartile 0.09), although a hypothesis test is not appropriate because
465 no hypothesis was proposed before looking at the data. In general, one might expect phylogenetically restricted
466 assemblages of organisms such as the Leicester hoverflies to show larger amounts of size change than more diverse
467 assemblages of organisms such as the Surtsey higher plants. This is because if there is strong niche conservatism
468 (Wiens et al., 2010), closely-related species will tend to have similar proportional growth rates under most sets of
469 environmental conditions, and when proportional growth rates are similar, $\cos^2 \theta$ will tend to be large (Figure 3).
470 Conversely, in a diverse assemblage, it is unlikely that all species will have similar proportional growth rates under
471 most sets of environmental conditions, and $\cos^2 \theta$ will generally be small. Thus, in diverse assemblages, indices of
472 size change such as the Living Planet Index may be relatively uninformative about community dynamics. I will
473 not attempt to test this hypothesis here, because such a test will require data from a wide range of assemblages of
474 differing taxonomic diversity, but it is closely connected to the idea that compensatory dynamics (predominantly
475 positive interspecific covariances in abundance) will occur in assemblages where many species are functionally
476 equivalent (Houlahan et al., 2007).

477 In summary, the Surtsey higher plant data illustrate how patterns in size change may not accord with simple
478 perceptions of the favourability of an environment, and do not support the idea that rates of shape change will
479 generally be decreasing over time. Change in shape was much more important in the Surtsey higher plant assemblage
480 than in the Leicester hoverfly assemblage.

481 10. Discussion

482 Here, I have derived a measure of the rate of shape change (in the sense of Definition 1) that is consistent with
483 the basic principles of population dynamics and takes an organism-centred view. The most important result is
484 that if two abundance trajectories have the same proportional growth rates at corresponding time points, they are
485 equivalent from an organism's point of view, and should therefore have the same rate of shape change. It may seem
486 surprising that equal proportional changes make equal contributions to the rate of shape change (and to indices of
487 biodiversity change such as the Living Planet Index) whether they occur in rare or common species. Thus, shape
488 change could be rapid in a community whose dominant species do not change in abundance. Population biologists
489 have accepted the idea that the proportional scale is appropriate for analyses of single-species dynamics (Gaston
490 and McArdle, 1994). A reluctance to apply the same logic at the community level (e.g. Lewis, 1978; Field et al.,
491 1982; Legendre and Gallagher, 2001) might imply that some variable other than the composition of the community

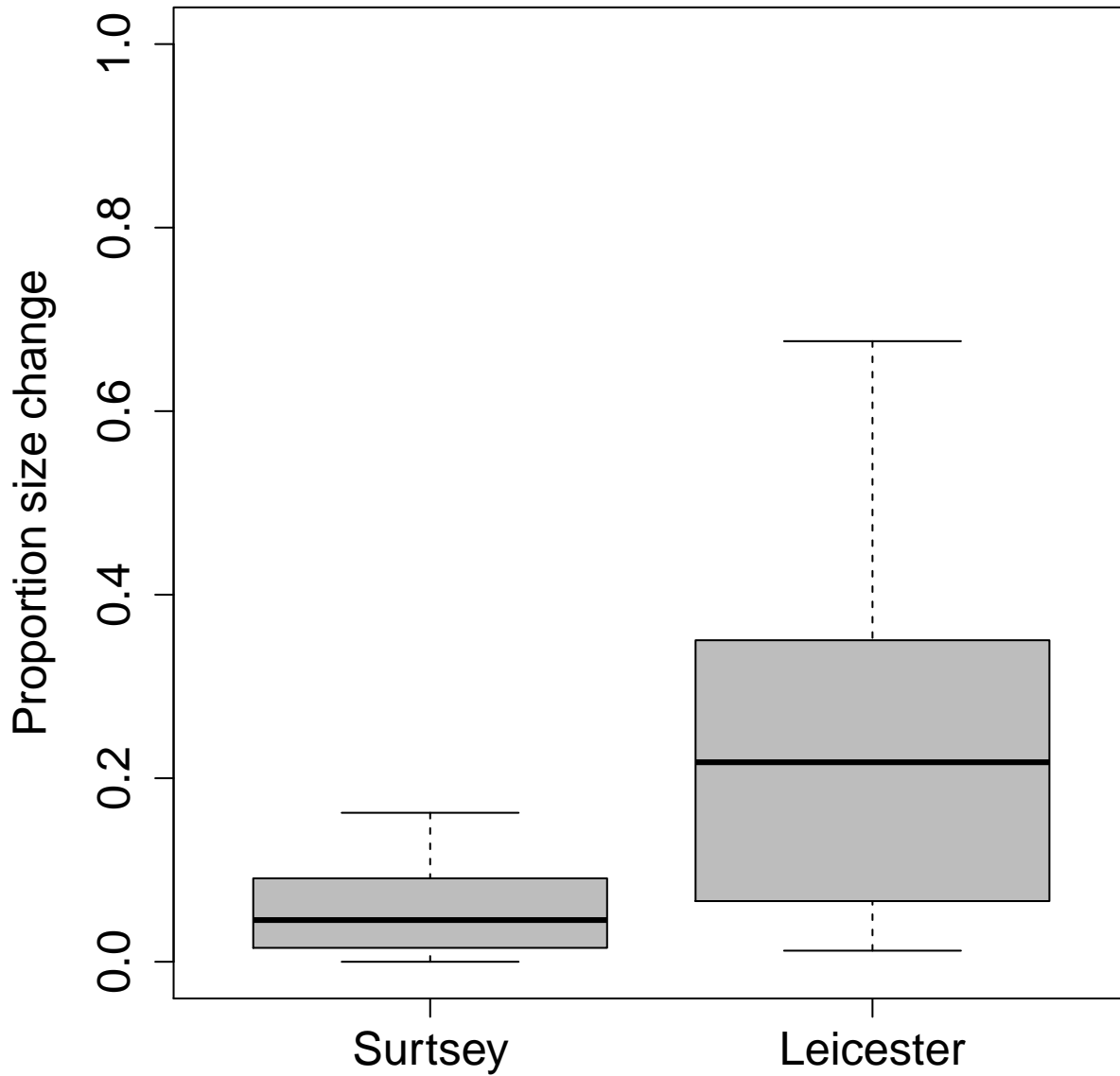


Figure 7: Boxplots of proportion of change that is size change ($\cos^2 \theta$) for higher plants on Surtsey (17 annual time intervals: infinitesimal parts not shown) and hoverflies in a Leicester, UK, garden (29 annual time intervals, bootstrap mean values plotted). Thick line: median. Box extends from the lower to the upper hinges, which are approximately the lower and upper quartiles. Whiskers extend from the ends of the box to the furthest observations no more than 1.5 times the width of the box away.

492 is in fact of primary interest. Such variables might include total biomass or its distribution among species, nutrients,
493 phylogenetic diversity, or structural complexity. These are all important aspects of a broader concept of succession.
494 Nevertheless, one should not object to a measure of the rate of shape change on the grounds that it does not describe
495 the rate of change of some other variable. The properties studied by community ecologists (such as abundances)
496 and the properties studied by ecosystem ecologists (such as biomass, nutrients, and structural complexity) may
497 behave in quite different ways.

498 Other interesting measures of community dynamics could be obtained under different invariance principles. For
499 example, one might argue that for a single population, all points on the same logistic growth curve are equivalent in
500 the long term. Under this argument, one would want a measure (such as the carrying capacity) that indexes long-
501 term behaviour rather than short-term dynamics. There are two key differences from the approach taken in this
502 manuscript. First, situations that will be equivalent in the long term are not equivalent from an organism's point
503 of view. Instead, they might represent equivalence in properties such as long-term conservation value. Second,
504 such an approach requires a parameterized model of community dynamics. There are fairly simple and general
505 stochastic models of community dynamics (e.g. Ives et al., 2003; Mutshinda et al., 2009; Hampton et al., 2013),
506 but they will not apply to all situations. The model would (I think) have to be parameterized, because it would be
507 difficult to find a useful measure that was invariant over the space spanned by all members of a family of models,
508 rather than the space spanned by a particular member of that family. There is a similar issue with measures of
509 physiological time. It is easy to find a physiological time scale on which some process such as organism growth has
510 a constant proportional rate, but impossible to find a universal time scale on which all relevant processes will have
511 this property (van Straalen, 1983). In contrast, the approach used here does not rely on any parameterized model
512 of community dynamics (other than in the trivial sense that because we do not usually know abundances exactly,
513 we have to use a model to estimate proportional growth rates).

514 There may be a deeper connection between measures of diversity and measures of the rate of shape change.
515 Diversity indices are scalar summaries of a relative abundance vector, while measures of the rate of shape change
516 are scalar summaries of changes in relative abundance vectors. Most diversity indices can be expressed in terms of
517 Hill numbers, a family of functions indexed by the weight they give to evenness (Hill, 1973; Jost, 2006). There are
518 generalizations that account for functional or taxonomic similarity (Leinster and Cobbold, 2012; Chiu and Chao,
519 2014). The obvious place to look for a connection between the concepts of diversity and rate of shape change is beta
520 diversities, which measure differences in diversity between communities. Beta diversities based on Hill numbers
521 unify a wide range of measures of community similarity (Jost, 2007), including the Jaccard and Morisita-Horn
522 indices used by Dornelas et al. (2014) to measure temporal change in communities. They are not scaling invariant
523 (M. Spencer, unpublished results, unless no weight is given to evenness, in which they only measure colonization
524 and extinction), but the possibility of a less obvious connection remains.

525 Traditionally, multivariate community ecology has focussed on variation among sites (e.g. Gauch, 1982). Even

526 when samples form a time series, the usual approach is to analyze them in “abundance space”, where each ob-
527 servation represents the abundance vector at a single time (e.g. Warwick et al., 2002; Lear et al., 2008). This is
528 implicitly a static view of communities, in which abundance is directly determined by environmental conditions. It
529 is in conflict with the dominant view in population dynamics that environmental conditions act on the proportional
530 growth rate of a species, rather than directly on its abundance (Birch, 1953; Hutchinson, 1957; Maguire, 1973).
531 In contrast, the decomposition of patterns of change into size and shape components gives an ecologically mean-
532 ingful low-dimensional representation of dynamics, which may offer a useful alternative to traditional ordination.
533 Furthermore, it can be extended to deal with colonizations and extinctions, or to data on presence/absence alone.
534 Related work includes the regression method used by Ives (1995) to study the responses of communities to long-term
535 directional perturbations, although this focusses on responses of mean abundance to environmental change, rather
536 than on decomposing empirical patterns of proportional growth rates.

537 What could measures of size and shape change be used for? One obvious idea is to quantify global patterns
538 in community change. There is evidence of global variation in size change in vertebrate assemblages since 1970
539 (Collen et al., 2009, 2013). For example, among terrestrial species, tropical populations appear to be declining while
540 temperate populations are increasing. For marine species, populations in the Southern and Indian Oceans appear
541 to be declining, while populations in the Pacific and Atlantic are relatively stable. Thus, there is clearly shape
542 change as well as size change at the global scale, and some of this change can be explained by simple geographical
543 differences. Similarly, among insects there was an overall 45% decline in abundance between 1970 and 2010, but
544 declines were less severe in Lepidoptera than in other insects (Dirzo et al., 2014). The geometric approach taken
545 here shows that we can think of the Living Planet Index and related indices as being based on a one-dimensional
546 linear model (e.g. Saville and Wood, 1991, chapter 5). Rather than fitting separate one-dimensional models for
547 subgroups, as is currently done (Collen et al., 2013), it would be productive to fit a single linear model with an
548 overall size change pattern, differences between groups (e.g. tropical and temperate populations) represented as
549 orthogonal contrasts (e.g. Saville and Wood, 1991, section 7.3), and a residual shape change component. This
550 will allow quantification of the amount of change that can be explained by simple differences such as tropical vs
551 temperate, and the amount of unexplained but ecologically meaningful shape change. The fact that abundances
552 do not need to be measured in the same units for different species moves the task of studying such global patterns
553 from impossible to merely very difficult. Furthermore, it may be possible to calculate the analogous measures for
554 presence/absence data in cases where abundances cannot be reliably estimated. For example, it would be possible
555 to calculate size and shape change indices from historical records and fossil communities, and hence study global
556 patterns of change over very long time scales.

557 In the two communities I analyzed, there was a striking difference in the proportion of change that was size
558 change. It therefore seems likely that size-based indices such as the Living Planet Index will be much more
559 informative about some communities than others. I hypothesized that phylogenetically-restricted assemblages might

560 show mainly size change, while diverse assemblages might show mainly shape change. For example, hydrothermal
561 vent communities occur are characterized by evolutionary radiations of a fairly small group of taxa (Van Dover
562 et al., 2002). It seems plausible that such communities might show a relatively high proportion of size change.
563 In contrast, one might expect tropical forests and coral reefs, with high phylogenetic diversity, to show a high
564 proportion of shape change.

565 In conclusion, shape change is distinct from but complementary to the property measured by indices such as
566 the Living Planet Index. The rate of shape change should be measured in a way that is consistent with population
567 dynamics. The measures I have derived satisfy this requirement. The key to understanding their properties is the
568 geometry of growth space, whose axes are the proportional growth rates of each species involved.

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579 **Appendix A. Invariance under exponential growth and scaling invariance**

Theorem 1. *A measure of the rate of shape change satisfying Property 7 is invariant under exponential growth, in the sense that it will have the same value for any pairs of vectors \mathbf{x} , \mathbf{y} generated by a given initial abundance vector \mathbf{x}_0 , a constant vector of species-specific proportional growth rates \mathbf{r} and a constant time interval Δt . In other words,*

$$g(\mathbf{x}, e^{\mathbf{R}\Delta t}\mathbf{x}) = g(e^{\mathbf{R}t}\mathbf{x}, e^{\mathbf{R}(t+\Delta t)}\mathbf{x}).$$

Proof. Property 7 is that

$$g(\mathbf{x}, \mathbf{y}) = g(\mathbf{M}\mathbf{x}, \mathbf{M}\mathbf{y})$$

for all $n \times n$ matrices \mathbf{M} with positive diagonal elements and zero off-diagonal elements. Choose $\mathbf{x} = \mathbf{x}_0$, $\mathbf{y} = e^{\mathbf{R}\Delta t}\mathbf{x}$ where $\mathbf{R} = \text{diag}(\mathbf{r})$, and $\mathbf{M} = e^{\mathbf{R}t}$ for any time t . Then by Property 7,

$$g(\mathbf{x}_0, e^{\mathbf{R}\Delta t}\mathbf{x}_0) = g(e^{\mathbf{R}t}\mathbf{x}_0, e^{\mathbf{R}(t+\Delta t)}\mathbf{x}_0)$$

580 for any t . □

581 **Theorem 2.** *Invariance under exponential growth is necessary for Property 7.*

582 *Proof.* Suppose that there exist a set of proportional growth rates \mathbf{r} and a time interval Δt for which the measure
583 is not invariant. In other words, for some initial vector \mathbf{x} , $\mathbf{y} = e^{\mathbf{R}\Delta t}\mathbf{x}$ and $\mathbf{z} = e^{\mathbf{R}\Delta t}\mathbf{y}$, but $g(\mathbf{x}, \mathbf{y}) \neq g(\mathbf{y}, \mathbf{z})$. Then
584 for $\mathbf{M} = e^{\mathbf{R}\Delta t}$, Property 7 does not hold. □

585 **Theorem 3.** *Invariance under exponential growth is not sufficient for Property 7. For example, a measure which
586 is invariant under exponential growth from any given initial conditions, but with a different value for each initial
587 condition, does not satisfy Property 7.*

588 *Proof.* Suppose that for any initial condition \mathbf{x} , $\mathbf{y} = e^{\mathbf{R}\Delta t}\mathbf{x}$. Choose \mathbf{x}_1 so that there is no t for which $\mathbf{x}_1 = e^{\mathbf{R}t}\mathbf{x}$,
589 and $\mathbf{y}_1 = e^{\mathbf{R}\Delta t}\mathbf{x}_1$. Suppose that $g(\mathbf{x}, \mathbf{y}) \neq g(\mathbf{x}_1, \mathbf{y}_1)$, then Property 7 does not hold for \mathbf{M} such that $\mathbf{x}_1 = \mathbf{M}\mathbf{x}$. □

590 **Appendix B. Existing measures of rate of shape change**

591 Here, I review some widely-used measures of the rate of shape change. The original authors did not use the
 592 term shape change. Instead, they used terms such as “succession rate”, “rate of change” and “compositional
 593 dissimilarity” to describe what they were measuring. Nevertheless, they all fit Definition 1.

594 The most obvious choice for a measure of the mean rate of shape change (Foster and Tilman, 2000) is $1/\Delta t$
 595 times the Euclidean distance between the relative abundance vectors at times t and $t + \Delta t$,

$$\frac{1}{\Delta t} \left[\sum_{i=1}^n (p_i(t + \Delta t) - p_i(t))^2 \right]^{1/2}. \quad (\text{B.1})$$

596 As a physical analogy, this is the way one would calculate the mean speed of an object in space, given its position
 597 at two points in time. However, although Euclidean distance is the natural choice for points in the real space \mathbb{R}^n ,
 598 relative abundances lie in the unit simplex \mathbb{S}^{n-1} , for which Euclidean distance is not a natural choice. For example,
 599 the Euclidean distance between $[0.5, 0.5]'$ and $[0.4, 0.6]'$ is the same as that between $[0.1, 0.9]'$ and $[0.2, 0.8]'$, but
 600 the latter case represents a much larger proportional change. Since exponential growth corresponds to constant
 601 proportional change, Euclidean distance is not invariant under exponential growth (Figure 2A, purple line).

In an insightful paper, Jassby and Goldman (1974) pointed out that an absolute abundance vector can be
 mapped to a point \mathbf{e} on the unit s -sphere by the transformation $e_i(t) = x_i(t)/[\sum_{i=1}^n (x_i(t))^2]^{1/2}$. As the community
 changes, it traces out a path on the sphere of length

$$S(t) = \int_0^t \left| \frac{d\mathbf{e}}{du} \right| du.$$

602 They therefore proposed

$$\sigma = dS/dt = \left[\sum_{i=1}^n (de_i/dt)^2 \right]^{1/2} \quad (\text{B.2})$$

603 as a measure of the instantaneous rate of shape change. They estimated σ using a finite-difference approximation,
 604 replacing de_i/dt by $\Delta e_i/\Delta t$, for small Δt . However, their measure is not invariant under exponential growth (Figure
 605 2A, red line).

606 Lewis (1978) argued (wrongly, in my view) that σ does not weight each species equally, and proposed

$$\sigma_s = \frac{1}{\Delta t} \sum_{i=1}^n |p_i(t + \Delta t) - p_i(t)| \quad (\text{B.3})$$

607 (over sufficiently small time intervals Δt) as a more equitable measure of the instantaneous rate of shape change.
 608 The community is represented as a point on the surface of a polygon embedded in \mathbb{R}^n , and distance is measured
 609 as the sum of absolute distances along each dimension. This is a rescaling of the taxicab metric, which is discussed
 610 extensively by Miller (2002). While it has a simple geometric interpretation, it does not measure proportional
 611 change, and is not invariant under exponential growth (Figure 2A, blue line).

612 The Bray-Curtis distance is widely used as a measure of dissimilarity between communities, and changes in Bray-

613 Curtis distances among samples in a sequence are sometimes interpreted as changes in the rate of shape change
614 (e.g. Nicholson et al., 1979). It is particularly popular with marine ecologists studying changes in communities
615 (Field et al., 1982). Most of this marine ecological work has been based on the ranks of distances rather than the
616 distances themselves, but clearly, a rank-based approach relies to some extent on the properties of the underlying
617 distance. Denote by $\kappa_i(t) = h(x_i(t))$ the score for species i at time t , where h is some suitable transformation.
618 Then a Bray-Curtis-based measure of the rate of change in scores per unit time is

$$\frac{\sum_{i=1}^n |\kappa_i(t + \Delta t) - \kappa_i(t)|}{\Delta t \sum_{i=1}^n [\kappa_i(t + \Delta t) + \kappa_i(t)]} \quad (\text{B.4})$$

619 (Field et al., 1982). If $\kappa_i(t) = p_i(t)$, then this is just 1/2 times Lewis's σ_s (Equation B.3). However, Field et al.
620 (1982) recommend a transformation that reduces the weighting given to very abundant species, such as the fourth
621 root. For relative abundances, this is $\kappa_i(t) = [p_i(t)]^{1/4}$. Whether the transformation is applied to relative or to
622 absolute abundances, the result is not invariant under exponential growth (Figure 2A, green line, using relative
623 abundances).

Plant ecologists often use methods based on correspondence analysis to search for relationships between envi-
ronmental variables and community structure (ter Braak, 1985). Correspondence analysis preserves the chi-square
distance between communities:

$$d_{\chi^2}(t, t + \Delta t) = (x_{..})^{1/2} \left[\sum_{i=1}^n \frac{1}{x_{.i}} (p_i(t + \Delta t) - p_i(t))^2 \right]^{1/2},$$

624 where $x_{..}$ is the sum of abundances over all species and times, and $x_{.i}$ is the sum of abundances of the i th species
625 over all times (Legendre and Gallagher, 2001). The desire to interpret distances on a correspondence analysis biplot
626 as measures of the amount of change leads to

$$\frac{d_{\chi^2}(t, t + \Delta t)}{\Delta t} \quad (\text{B.5})$$

627 as a possible measure of the rate of shape change. Equation B.5 is not invariant under exponential growth (Figure
628 2A, orange line). Detrended correspondence analysis (Hill and Gauch, 1980) is one of the most popular methods
629 based on correspondence analysis, and distances on a detrended correspondence analysis plot are sometimes viewed
630 as amounts of change (e.g. Jacobson and Grimm, 1986; Bush et al., 2004; Walker and del Moral, 2003, p. 253). I
631 do not discuss detrended correspondence analysis in detail, but the additional ad-hoc operations it involves do not
632 alter the basic conclusion that chi-square distances are not invariant under exponential growth.

633 The patterns of change over time in Equations B.2 to B.5 in a community of exponentially-growing species
634 depend on the proportional growth rates and initial abundances of the species, so that they may in other cases
635 show patterns quite different from those in Figure 2A. I therefore do not attempt to make any statements about
636 their relative usefulness, other than that changes in their values cannot be used to identify ecologically meaningful
637 changes in the rate of shape change.

638 **Appendix C. Deriving a measure of rate of shape change**

639 Here, I derive a measure of the rate of shape change which has Properties 1 to 8, for the case where there are
640 no colonizations or extinctions.

I start with an analogous but simpler problem. Consider a single species with abundance $x(t)$ at time t , where $x(t)$ is a differentiable, positive function of time. Denote by $\tilde{r}(t, t + \Delta t)$ the mean proportional growth rate over the time interval $(t, t + \Delta t]$, which is

$$\tilde{r}(t, t + \Delta t) = \frac{1}{\Delta t} \int_t^{t+\Delta t} \frac{1}{x} \frac{dx}{du} du = \frac{\log x(t + \Delta t) - \log x(t)}{\Delta t}, \quad x > 0,$$

641 (throughout, \log denotes the natural logarithm). This mean proportional growth rate is obviously a constant for
642 all patterns of change resulting in the same amount of proportional growth in a given time.

643 I will now derive a similar measure of the mean rate of proportional change in relative abundances (thus satisfying
644 Properties 1 and 2). All the information in relative abundance data is contained in the set of ratios $v_{ij} = x_i/x_j$,
645 $i = 1, \dots, n-1, j = i+1, \dots, n$, satisfying Property 3). In other words, a basis for the space of relative abundances
646 can be constructed from functions of these ratios (Egozcue et al., 2003). We therefore need only consider the vector
647 of ratios $\mathbf{v}(t) = [v_{12}(t), v_{13}(t), \dots, v_{1n}(t), v_{23}(t), \dots, v_{n-1,n}(t)]'$. Although $\mathbf{v}(t)$ is a generating set for the space of
648 relative abundances, it is not a minimal generating set (basis). Nevertheless, treating all its elements symmetrically
649 makes it easy to see the biological interpretation of the resulting measure, and results in the same measure as would
650 be obtained from a basis.

There are $c = n(n-1)/2$ elements in $\mathbf{v}(t)$, but their order is not important in what follows. Denote by w_k the mean proportional rate of change in the k th element of \mathbf{v} (which I index by v_{ij}) over the time interval $(t, t + \Delta t]$, and denote by $\tilde{r}_i(t, t + \Delta t)$ the mean proportional growth rate of the i th species over the time interval $(t, t + \Delta t]$, defined as in Equation 4. Then, assuming v_{ij} is a differentiable function of time,

$$\begin{aligned} w_k &= \frac{1}{\Delta t} \int_t^{t+\Delta t} \frac{1}{v_{ij}} \frac{dv_{ij}}{du} du, \quad v_{ij} > 0, \\ &= \frac{\log v_{ij}(t + \Delta t) - \log v_{ij}(t)}{\Delta t} \\ &= \frac{1}{\Delta t} \left[\log \frac{x_i(t + \Delta t)}{x_j(t + \Delta t)} - \log \frac{x_i(t)}{x_j(t)} \right] \\ &= \frac{1}{\Delta t} [(\log x_i(t + \Delta t) - \log x_i(t)) - (\log x_j(t + \Delta t) - \log x_j(t))] \\ &= \tilde{r}_i(t, t + \Delta t) - \tilde{r}_j(t, t + \Delta t). \end{aligned}$$

651 This expression will be zero for any i and j if $\mathbf{x}(t + \Delta t) = \mathbf{x}(t)$ (Property 4), or if $\mathbf{x}(t + \Delta t) = a\mathbf{x}(t)$, where $a > 0$
652 (Property 6). Because w_k is the difference between mean proportional growth rates, any pattern of growth that
653 leads to the same proportional change in species i and j over a given time interval will result in the same value of
654 w_k , and Property 7 is satisfied.

655 The obvious scalar measure of the mean rate of proportional change in relative abundances is then the Euclidean

656 norm of the vector $\mathbf{w} = [w_1, w_2, \dots, w_c]'$, which is

$$\begin{aligned}
\|\mathbf{w}\| &= \left[\sum_{k=1}^c w_k^2 \right]^{1/2} \\
&= \frac{1}{\Delta t} \left[\sum_{i=1}^{n-1} \sum_{j=i+1}^n [\log v_{ij}(t + \Delta t) - \log v_{ij}(t)]^2 \right]^{1/2} \\
&= \left[\sum_{i=1}^{n-1} \sum_{j=i+1}^n [\tilde{r}_i(t, t + \Delta t) - \tilde{r}_j(t, t + \Delta t)]^2 \right]^{1/2}.
\end{aligned} \tag{C.1}$$

657 Squaring each element in \mathbf{w} ensures that the measure will be non-negative (Property 5).

658 The second line of Equation C.1 expresses $\|\mathbf{w}\|$ in a way that shows it is proportional to the Aitchison distance
659 (Aitchison, 1992; Egozcue et al., 2003) between the relative abundance vectors at times t and $t + \Delta t$. The Aitchison
660 distance is in some sense the simplest measure of difference between two compositions that satisfies Properties 3, 4
661 and 7, as well as the additional requirements of symmetry and invariance under arbitrary reorderings of the species
662 (Aitchison, 1992). It also satisfies the triangle inequality. The third line of Equation C.1 expresses $\|\mathbf{w}\|$ in a way
663 that shows it is a function of the mean proportional growth rates of all the species.

664 To obtain a measure that is independent of the number of species (Property 8), I will use a geometric inter-
665 pretation of Equation C.1. For a given set of species, every vector of proportional growth rates \mathbf{r} (dropping the
666 time indexing for simplicity) can be represented as a point in a space \mathbb{R}^n which I refer to as the growth space of
667 the community (Figure 3 is a two-dimensional example). The growth rate vector \mathbf{r} can be decomposed into two
668 orthogonal components. The first component is the projection \mathbf{u} of \mathbf{r} onto the line of equal proportional growth
669 rates, which represents change in abundance without shape change. I call this size change. It is straightforward
670 (e.g. Saville and Wood, 1991, p. 69) to show that $\mathbf{u} = \bar{r}\mathbf{1}$, where

$$\bar{r} = \frac{1}{n} \sum_{i=1}^n \tilde{r}_i, \tag{C.2}$$

with dimensions time^{-1} . In other words, each element of \mathbf{u} is the among-species sample mean of mean proportional
growth rates. The second component \mathbf{q} is orthogonal to \mathbf{u} , and the square of its Euclidean norm is

$$\|\mathbf{q}\|^2 = \sum_{i=1}^n (\tilde{r}_i - \bar{r})^2,$$

(e.g. Saville and Wood, 1991, pp. 49-50). It is straightforward to show that $\|\mathbf{w}\|^2 = n\|\mathbf{q}\|^2$:

$$\begin{aligned}
\|\mathbf{w}\|^2 &= \sum_{i=1}^n \sum_{j=i+1}^n [\tilde{r}_i - \tilde{r}_j]^2 \\
&= \frac{1}{2} \sum_{i=1}^{n-1} \sum_{j=1}^n [\tilde{r}_i - \tilde{r}_j]^2 \\
&= \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n [(\tilde{r}_i - \bar{r}) - (\tilde{r}_j - \bar{r})]^2 \\
&= \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n [(\tilde{r}_i - \bar{r})^2 - 2(\tilde{r}_i - \bar{r})(\tilde{r}_j - \bar{r}) + (\tilde{r}_j - \bar{r})^2] \\
&= n \sum_{i=1}^n (\tilde{r}_i - \bar{r})^2 - \sum_{i=1}^n \left[(\tilde{r}_i - \bar{r}) \sum_{j=1}^n (\tilde{r}_j - \bar{r}) \right] \\
&= n \sum_{i=1}^n (\tilde{r}_i - \bar{r})^2 - \sum_{i=1}^n \left[(\tilde{r}_i - \bar{r}) \left(\sum_{j=1}^n \tilde{r}_j - n\bar{r} \right) \right] \\
&= n \sum_{i=1}^n (\tilde{r}_i - \bar{r})^2 - \sum_{i=1}^n (\tilde{r}_i - \bar{r}) (n\bar{r} - n\bar{r}) \quad \text{from Equation C.2} \\
&= n \sum_{i=1}^n (\tilde{r}_i - \bar{r})^2 - \sum_{i=1}^n (\tilde{r}_i - \bar{r}) \times 0 \\
&= n\|\mathbf{q}\|^2.
\end{aligned}$$

671 In other words, the norm of \mathbf{q} is proportional to the proposed scalar measure of mean rate of proportional change
672 in relative abundances (Equation C.1), which can be thought of as measuring change in shape of the community.

673 An obvious measure of rate of shape change that is independent of the number of species is therefore

$$\begin{aligned}
s_r &= \left[\frac{1}{n-1} \sum_{i=1}^n (\tilde{r}_i - \bar{r})^2 \right]^{1/2} \\
&= \frac{1}{(n-1)^{1/2}} \|\mathbf{q}\| \\
&= \frac{1}{(n(n-1))^{1/2}} \|\mathbf{w}\|,
\end{aligned} \tag{C.3}$$

674 which is just the sample standard deviation of the mean proportional growth rates, with dimensions time^{-1} . Since
675 the sample standard deviation is an asymptotically unbiased estimator of the population standard deviation of
676 the mean proportional growth rates, the expected value of s_r will (in the limit of a large number of species) be
677 constant among communities with different numbers of species but the same population standard deviation of mean
678 proportional growth rates, or among random samples of different numbers of species from a single community.
679 Thus Property 8 is satisfied asymptotically in principle. However, the above argument assumes that the mean
680 proportional growth rates are known exactly. In reality, the true abundances (and hence true mean proportional
681 growth rates) will be uncertain. This uncertainty may affect how the value of s_r depends on the number of species,
682 but the way in which it does so will depend on how abundances are estimated. Furthermore, s_r is biased for finite

683 samples. In principle, this bias can be corrected, but only by assuming a particular distribution, such as the normal,
684 for the proportional growth rates (e.g. Gurland and Tripathi, 1971).

685 To obtain Equation 7, use Equation C.1 with $v_{ij} = x_i/x_j = p_i/p_j$ and Equation C.3.

686 **Appendix D. What kinds of functions are scaling invariant?**

687 It is worth asking whether there are many kinds of scaling invariant functions other than s_r , and if so, what
 688 they look like. The theorem below is essentially a rephrasing of Aitchison (1992, p. 373). It leads to the result that
 689 other scaling invariant functions take particular forms (such as contrasts), and cannot involve any kind of weighting
 690 by abundance.

691 **Theorem 4.** *All scaling invariant functions are functions of the vector \mathbf{r} of mean proportional growth rates over
 692 some fixed time interval.*

693 *Proof.* Denote by \mathcal{Z} the set of pairs of abundance vectors $z = (\mathbf{x}, \mathbf{y}) \in \mathbb{R}_{>0}^n \times \mathbb{R}_{>0}^n$. A scaling can be represented by
 694 an $n \times n$ matrix \mathbf{M} with positive diagonal elements, that maps (\mathbf{x}, \mathbf{y}) to $(\mathbf{M}\mathbf{x}, \mathbf{M}\mathbf{y})$ (property 7). Denote by $\mathbf{M}z$
 695 the action of \mathbf{M} on z .

696 The matrices \mathbf{M} form a group \mathcal{M} under matrix multiplication (Pollatsek, 2009, problem 4.5.8). The orbit O_z
 697 of any $z \in \mathcal{Z}$ is the set of elements of \mathcal{Z} that can be reached by the action of any $\mathbf{M} \in \mathcal{M}$ on z , and is the set of
 698 pairs of abundance vectors equivalent to the pair $z = (\mathbf{x}, \mathbf{y})$ under scaling (Eaton, 1989, p. 21).

699 A function g is invariant if $g(z) = g(\mathbf{M}z)$ for all $\mathbf{M} \in \mathcal{M}$, and maximal invariant if it is invariant and if
 700 $g(z_1) = g(z_2)$ implies $z_1 = \mathbf{M}z_2$ for some $\mathbf{M} \in \mathcal{M}$ (Eaton, 1989, Definition 2.4). In other words, a maximal
 701 invariant has the same value for all members of an orbit, and a different value for each different orbit. Any invariant
 702 function is a function of a maximal invariant (Eaton, 1989, Theorem 2.3). Thus, we need to show that \mathbf{r} is a
 703 maximal invariant.

First, we show that \mathbf{r} is invariant under scaling. Denote by m_i the i th diagonal element of \mathbf{M} . The i th mean
 proportional growth rate for some fixed time interval Δt is

$$r_i = \frac{1}{\Delta t} \log \left(\frac{y_i}{x_i} \right) = \frac{1}{\Delta t} \log \left(\frac{m_i y_i}{m_i x_i} \right).$$

704 Thus the vector \mathbf{r} of mean proportional growth rates is scaling invariant.

Second, we show that $\mathbf{r}^{(1)} = \mathbf{r}^{(2)}$ implies $\mathbf{r}^{(1)} = \mathbf{M}\mathbf{r}^{(2)}$, for two mean proportional growth rate vectors $\mathbf{r}^{(1)}$, $\mathbf{r}^{(2)}$,
 some matrix $\mathbf{M} \in \mathcal{M}$, and some fixed time interval Δt . Consider the i th elements of $\mathbf{r}^{(1)}$ and $\mathbf{r}^{(2)}$:

$$\begin{aligned} r_i^{(1)} &= r_i^{(2)} \\ \frac{1}{\Delta t} \log \left(\frac{y_i^{(1)}}{x_i^{(1)}} \right) &= \frac{1}{\Delta t} \log \left(\frac{y_i^{(2)}}{x_i^{(2)}} \right) \\ \frac{y_i^{(1)}}{y_i^{(2)}} &= \frac{x_i^{(1)}}{x_i^{(2)}} \\ y_i^{(1)} &= \frac{x_i^{(1)}}{x_i^{(2)}} y_i^{(2)} \end{aligned}$$

705 Thus, $z_1 = \mathbf{M}z_2$ for the diagonal matrix \mathbf{M} with i th diagonal element $m_i = x_i^{(1)}/x_i^{(2)}$. In consequence, \mathbf{r} is a
 706 maximal invariant under scaling, and any scaling invariant function must be a function of \mathbf{r} . \square

707 In this paper, I considered only the mean and standard deviation of the elements of \mathbf{r} . By Theorem 4 and the
 708 obvious result that any function of a maximal invariant is an invariant function, there are lots of other potentially
 709 interesting scaling invariant functions of \mathbf{r} . For example, contrasts (differences between the means of subsets of the
 710 elements of \mathbf{r}) are also scaling invariant, and can be used to measure differences in rates of change between groups
 711 of organisms. However, Theorem 4 shows that there is no need to consider functions that cannot be written in
 712 terms of proportional growth rates. For example, a scaling invariant function cannot involve any kind of weighting
 713 by abundance, because such weightings do not appear in the maximal invariant \mathbf{r} .

714 **Appendix E. Estimating size and shape change**

715 To estimate s_r and \bar{r} from the hoverfly data, estimates of abundance in each year are needed. The following
 716 simple approach is adequate to demonstrate the behaviour of s_r and \bar{r} for these data, and accounts for both
 717 parameter uncertainty and stochasticity.

I treated each species as independent. At each time t , I modelled the observed count $c_i(t)$ of the i th species as being generated by a Poisson distribution with parameter $\lambda_i(t)$, the expected abundance. I modelled the log of the Poisson parameter as a random walk (in discrete time, because the observations were made at annual intervals). The model is

$$\begin{aligned}\log \lambda_i(t + 1) &= \log \lambda_i(t) + \epsilon_i(t) \\ \epsilon_i(t) &\sim \mathcal{N}(0, \sigma^2) \\ c_i(t) &\sim \text{Poisson}(\lambda_i(t))\end{aligned}$$

718 This is about the simplest model that could be used to describe these data. In particular, it does not include density
 719 dependence, interspecific competition or consistent trends in proportional growth rates. It is not likely to make
 720 good long-term predictions, but it is being used for smoothing, rather than forecasting. Expected log abundances
 721 were almost indistinguishable from observed abundances.

722 I fitted this model in 64-bit R version 3.0.1 for Linux (R Core Team, 2012) using the package `sspir 0.2.10`
 723 (Dethlefsen and Lundbye-Christensen, 2006). I used Iterated Extended Kalman Smoothing (Durbin and Koopman,
 724 2001) to obtain an approximating Gaussian model. I estimated σ^2 using maximum likelihood, with the Brent
 725 algorithm in R function `optim`. I initialized the Kalman filter with $E(\log \lambda_i(0)) = \log c_i(0)$ and $V(\log \lambda_i(0)) =$
 726 1×10^6 , so that expected initial abundance matched the observations but had high uncertainty. I did not include
 727 the first time interval in the analyses of patterns in s_r and \bar{r} . This is a quick and dirty approach, but the Kalman
 728 filter converges quickly, so that the choice of initialization has little effect on the results for later time intervals.

729 Using the fitted approximating Gaussian model, I sampled 1000 replicate time series of the conditional distri-
 730 bution of $\log \lambda_i$ and used them to calculate the distributions of s_r and \bar{r} as follows:

- 731 1. Draw a value σ^{2*} from the normal sampling distribution of σ^2 , specified by the maximum likelihood estimate
 732 and its asymptotic variance.
- 733 2. Draw a value $\log \lambda_i^*(t)$ for each time from the conditional distribution of $\log \lambda_i(t)$, given the entire observation
 734 vector $\mathbf{c}_i = [c_i(0), c_i(1), \dots]'$. This was done using the `ksimulate` function in `sspir`, with the sampled σ^{2*} .
3. Obtain simulated proportional growth rates

$$\tilde{r}_i^*(t, t + 1) = \log \lambda_i^*(t + 1) - \log \lambda_i^*(t),$$

735 for intervals of length one year (Equation 4 with $\Delta t = 1$).

736 4. Use the simulated proportional growth rates to calculate simulated values of s_r (Equation 5) and \bar{r} (Equation
737 C.2).

738 I report the mean and 0.025- and 0.975-quantiles of the simulated distributions of s_r and \bar{r} . The whole procedure
739 took less than an hour with an 3.2 GHz Intel Xeon processor and 16G RAM. The code is included as an electronic
740 enhancement.

741 Appendix F. Measuring colonization and extinction

742 *Motivation*

743 The proportional growth rate of a single species, $\frac{1}{x} \frac{dx}{dt}$, is undefined if $x = 0$. This makes it difficult to deal with
744 colonization and extinction in the framework of proportional change. Here, I describe a solution.

745 When calculating a mean proportional growth rate (Equation 4) it is reasonable to replace zero abundances $x = 0$
746 by $\lim_{x \rightarrow 0^+} x$, since abundances cannot be negative. Then because $\lim_{x \rightarrow 0^+} \log x = -\infty$, a colonization or extinction
747 can be thought of as representing an infinite amount of proportional change. This creates additional difficulties.
748 First, it does not discriminate between extinction of rare and common species, because $-\infty + \log x(t) = -\infty$ for
749 any real $\log x(t)$. Second, it does not discriminate between fast and slow extinctions, because $-\infty/\Delta t = -\infty$ for
750 any real Δt . Third, the arithmetic operations involved in the size and shape components of change (Equations 6
751 and 5) will often be undefined.

752 All these problems can be solved by working with surreal rather than real numbers. The surreal numbers
753 (Conway, 2001) are a field which contains all the real numbers, and many others besides, including infinite and
754 infinitesimal numbers. Arithmetic operations such as addition and multiplication, and logical comparisons such as
755 greater than, are well-defined for all surreal numbers. Instead of taking the limit as $x \rightarrow 0^+$, zero abundances can
756 be replaced by the surreal number $1/\omega$, which is greater than zero but smaller than all positive real numbers. This
757 is similar to the idea of non-standard analysis, in which infinitesimals are used instead of limits (Conway, 2001, p.
758 44). The integral in Equation 4 is valid for surreal numbers (Fornasiero, 2003, section 5.1). The natural logarithm
759 function is defined for all positive surreal numbers, and $\log(1/\omega) = -\omega^{1/\omega}$ (Gonshor, 1986, pp. 161-163), which is
760 more negative than all the real numbers, and therefore satisfies the requirement that a colonization or extinction
761 represents a greater amount of proportional change than any event not involving a colonization or extinction. The
762 choice $1/\omega$ is not unique, because there are many other numbers greater than zero but smaller than all positive
763 real numbers (for example, $2/\omega$ and $1/\omega^2$). Choosing one of these other numbers would give the same qualitative
764 result, but $1/\omega$ is in some sense the simplest number having the required properties (Conway, 2001, p. 12).

765 *Size change*

The among-species mean proportional growth rates (the size component) can be calculated as follows. For each
time interval $(t, t + \Delta t]$, divide the set of species being considered into four subsets, depending on whether they are
present or absent at the start and end of the interval:

$$\mathcal{S}_1 = \{i : x_i(t) > 0 \wedge x_i(t + \Delta t) > 0\}, \quad (\text{always present}),$$

$$\mathcal{S}_2 = \{i : x_i(t) > 0 \wedge x_i(t + \Delta t) = 0\}, \quad (\text{extinctions}),$$

$$\mathcal{S}_3 = \{i : x_i(t) = 0 \wedge x_i(t + \Delta t) > 0\}, \quad (\text{colonizations}),$$

$$\mathcal{S}_4 = \{i : x_i(t) = 0 \wedge x_i(t + \Delta t) = 0\}, \quad (\text{never present}).$$

Denote by k_1, k_2, k_3, k_4 the cardinalities of these sets. Denote by a_i the function

$$a_i = \begin{cases} \log x_i(t + \Delta t), & x_i(t + \Delta t) > 0, \\ -\omega^{1/\omega}, & x_i(t + \Delta t) = 0, \end{cases}$$

Denote by b_i the similar function of $x_i(t)$. Denote by a and b the sums of log abundances for species present at times $t + \Delta t$ and t respectively:

$$a = \sum_{i \in \mathcal{S}_1 \cup \mathcal{S}_3} a_i,$$

$$b = \sum_{i \in \mathcal{S}_1 \cup \mathcal{S}_2} b_i.$$

766 Then the among-species mean of mean proportional growth rates over $(t, t + \Delta t]$ is

$$\begin{aligned} \bar{r} &= \frac{1}{n} \sum_{i=1}^n \frac{a_i - b_i}{\Delta t} \\ &= \frac{1}{n\Delta t} \left[\sum_{i \in \mathcal{S}_1} (\log x_i(t + \Delta t) - \log x_i(t)) \right. \\ &\quad + \sum_{i \in \mathcal{S}_2} (-\omega^{1/\omega} - \log x_i(t)) \\ &\quad + \sum_{i \in \mathcal{S}_3} (\log x_i(t + \Delta t) - (-\omega^{1/\omega})) \\ &\quad \left. + \sum_{i \in \mathcal{S}_4} (-\omega^{1/\omega} - (-\omega^{1/\omega})) \right] \\ &= \frac{1}{n\Delta t} [(k_3 - k_2)\omega^{1/\omega} + a - b]. \end{aligned} \tag{F.1}$$

767 This reduces to Equation 6 if all species have non-zero abundance at all times. Otherwise, \bar{r} has an infinite part
768 which will be positive if there are more colonizations than extinctions, zero if there are equal numbers of colonizations
769 and extinctions, and negative if there are more extinctions than colonizations. The finite part of \bar{r} has contributions
770 from changes in abundance that do not involve colonization or extinction, the initial abundances of species that
771 went extinct, and the final abundances of species that colonized.

772 *Shape change*

773 To calculate the among-species standard deviation of mean proportional growth rates (the shape component), it
774 is easiest to first find the among-species variance and then take its square root. The among-species sample variance
775 is

$$\frac{1}{n-1} \left(\sum_{i=1}^n \tilde{r}_i^2 - n\bar{r}^2 \right). \tag{F.2}$$

776 The first term in the parentheses in Equation F.2 is

$$\begin{aligned}
\sum_{i=1}^n \tilde{r}_i^2 &= \frac{1}{(\Delta t)^2} \sum_{i=1}^n (a_i - b_i)^2 \\
&= \frac{1}{(\Delta t)^2} \left[\sum_{i \in \mathcal{S}_1} (\log x_i(t + \Delta t) - \log x_i(t))^2 \right. \\
&\quad + \sum_{i \in \mathcal{S}_2} (-\omega^{1/\omega} - \log x_i(t))^2 \\
&\quad + \sum_{i \in \mathcal{S}_3} (\log x_i(t) - (-\omega^{1/\omega}))^2 \\
&\quad \left. + \sum_{i \in \mathcal{S}_4} (-\omega^{1/\omega} - (-\omega^{1/\omega}))^2 \right] \\
&= \frac{1}{(\Delta t)^2} \left[(k_2 + k_3)\omega^{2/\omega} + 2\omega^{1/\omega} \left(\sum_{i \in \mathcal{S}_2} \log x_i(t) + \sum_{i \in \mathcal{S}_3} \log x_i(t + \Delta t) \right) \right. \\
&\quad \left. + \sum_{i \in \mathcal{S}_1} (\log x_i(t + \Delta t) - \log x_i(t))^2 + \sum_{i \in \mathcal{S}_2} (\log x_i(t))^2 + \sum_{i \in \mathcal{S}_3} (\log x_i(t + \Delta t))^2 \right].
\end{aligned} \tag{F.3}$$

777 From Equation F.1, the second term in the parentheses in Equation F.2 is

$$\begin{aligned}
n\bar{r}^2 &= n \left[\frac{1}{n\Delta t} [(k_3 - k_2)\omega^{1/\omega} + a - b] \right]^2 \\
&= \frac{1}{n(\Delta t)^2} [(k_3 - k_2)^2\omega^{2/\omega} + 2(a - b)(k_3 - k_2)\omega^{1/\omega} + (a - b)^2].
\end{aligned} \tag{F.4}$$

778 Using Equations F.3 and F.4, the among-species sample variance in mean proportional growth rates can be written
779 in the form

$$\frac{1}{(n-1)(\Delta t)^2} (\alpha\omega^{2/\omega} + \beta\omega^{1/\omega} + \gamma), \tag{F.5}$$

where the coefficients α, β, γ are the real numbers

$$\begin{aligned}
\alpha &= k_2 + k_3 - \frac{1}{n}(k_3 - k_2)^2, \\
\beta &= 2 \left(\sum_{i \in \mathcal{S}_2} \log x_i(t) + \sum_{i \in \mathcal{S}_3} \log x_i(t + \Delta t) - \frac{1}{n}(a - b)(k_3 - k_2) \right), \\
\gamma &= \left(\sum_{i \in \mathcal{S}_1} (\log x_i(t + \Delta t) - \log x_i(t))^2 + \sum_{i \in \mathcal{S}_2} (\log x_i(t))^2 + \sum_{i \in \mathcal{S}_3} (\log x_i(t + \Delta t))^2 - \frac{1}{n}(a - b)^2 \right).
\end{aligned}$$

If all species have non-zero abundance at all times, $\alpha = \beta = 0$ and the sample standard deviation is given by Equation 5. Otherwise, to find the sample standard deviation, write the second factor in Equation F.5 as

$$\alpha\omega^{2/\omega} + \beta\omega^{1/\omega} + \gamma = \alpha\omega^{2/\omega}(1 + \delta),$$

where

$$\delta = \frac{\beta\omega^{1/\omega} + \gamma}{\alpha\omega^{2/\omega}}$$

780 is an infinitesimal number. Then

$$[\alpha\omega^{2/\omega}(1+\delta)]^{1/2} = \alpha^{1/2}\omega^{1/\omega} \left[1 + \frac{1}{2}\delta + \frac{1}{2} \left(\frac{1}{2} - 1 \right) \frac{\delta^2}{2} + \dots \right] \quad (\text{F.6})$$

(Conway, 2001, Theorem 24). Using Equations F.5 and F.6, the sample standard deviation is

$$\frac{1}{(n-1)^{1/2}\Delta t} \left(\alpha^{1/2}\omega^{1/\omega} + \frac{\beta}{2\alpha^{1/2}} + \text{infinitesimal terms} \right).$$

781 Unless the infinitesimal terms can be shown to have any biological interpretation, it seems reasonable to discard
782 them, leaving just the infinite and real terms (at least for drawing graphs).

783 *Activity and $\cos^2 \theta$*

784 The norm $\|\mathbf{r}\|$ is given by the square root of Equation F.3, which can be evaluated using Equation F.6. Values
785 of the scaled activity level $n^{-1/2}\|\mathbf{r}\|$ can be ranked by comparing coefficients of powers of ω in Equation F.3 in
786 descending order. The value of the first coefficient that differs between two values determines their rank.

787 The squared norm $\|\mathbf{u}\|^2$ is given by Equation F.4. The proportion of change that is size change, $\cos^2 \theta =$
788 $(\|\mathbf{u}\|/\|\mathbf{r}\|)^2$, will then be a ratio of the form

$$\frac{a\omega^{2/\omega} + b\omega^{1/\omega} + c}{d\omega^{2/\omega} + e\omega^{1/\omega} + f}, \quad (\text{F.7})$$

with real coefficients a, b, c, d, e, f . Dividing the numerator and the denominator by $\omega^{2/\omega}$,

$$\cos^2 \theta = \frac{a}{d + e\omega^{-1/\omega} + f\omega^{-2/\omega}} + \text{infinitesimal terms},$$

789 whose value will be close to a/d . I therefore use the real approximation $\cos^2 \theta \simeq a/d$ in graphs. However, the
790 infinitesimal parts may be important in resolving ties. It is straightforward to rank two ratios of the form (F.7), by
791 cross-multiplying by their denominators and comparing the coefficients of matching powers of ω . I use this approach
792 when calculating statistics based on the ranks of $\cos^2 \theta$.

793 **Appendix G. Size and shape change in presence-absence data**

794 In the notation of Appendix F, the mean proportional growth rate over the interval $(t, t + \Delta t]$ for the i th species
 795 is $\tilde{r}_i = (a_i - b_i)/\Delta t$. The coefficient of $\psi = \omega^{1/\omega}$ in \tilde{r}_i is the only part that can be calculated if only presence/absence
 796 data are available. Denote this coefficient by $r_i^{(\psi)}$. Its value is

$$r_i^{(\psi)} = \begin{cases} \frac{-1}{\Delta t}, & \text{extinction,} \\ \frac{1}{\Delta t}, & \text{colonization,} \\ 0, & \text{otherwise.} \end{cases} \quad (\text{G.1})$$

797 The among-species mean of these coefficients is a natural measure of size change:

$$\begin{aligned} \frac{1}{n\Delta t} \sum_{i=1}^n r_i^{(\psi)} &= k_2(-1) + k_3(1) \\ &= \frac{k_3 - k_2}{n\Delta t}, \end{aligned} \quad (\text{G.2})$$

798 where k_2 is the number of extinctions and k_3 is the number of colonizations. Equation G.2 is the coefficient of ψ in
 799 Equation 8.

The among-species sample standard deviation of these coefficients is a natural measure of shape change:

$$\begin{aligned} &\frac{1}{\Delta t} \left[\frac{1}{n-1} \left(\sum_{i=1}^n (r_i^{(\psi)})^2 - \frac{1}{n} \left(\sum_{i=1}^n r_i^{(\psi)} \right)^2 \right) \right]^{1/2} \\ &= \frac{1}{\Delta t} \left[\frac{1}{n-1} \left(k_2(-1)^2 + k_3(1)^2 - \frac{1}{n} (k_3(1) + k_2(-1))^2 \right) \right]^{1/2} \\ &= \frac{1}{\Delta t} \left[\frac{1}{n-1} \left(k_2 + k_3 - \frac{1}{n} (k_3 - k_2)^2 \right) \right]^{1/2}, \end{aligned}$$

800 which is the coefficient of ψ in Equation 9.

The coefficient of ψ^2 in the squared activity level is

$$\begin{aligned} \sum_{i=1}^n (r_i^{(\psi)})^2 &= \frac{k_2(-1)^2 + k_3(1)^2}{(\Delta t)^2} \\ &= \frac{k_2 + k_3}{(\Delta t)^2}. \end{aligned}$$

801 Thus, the measures of rate of shape change proposed by Anderson (2007), which are proportional to $k_2 + k_3$, are
 802 measures of squared activity.

803 Finally, using the results above, the scaled activity from presence-absence data is $(1/(n^{-1/2}\Delta t))(k_2 + k_3)^{1/2}$,
 804 and the proportion of change that is size change is $\cos^2 \theta = (k_3 - k_2)^2 / (n(k_2 + k_3))$.

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