# Experimental round-robin evaluation of structure-borne sound source force-power test methods

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# ABSTRACT

The determination of the structure-borne noise from operational equipment in airplanes is a complex process that requires much source and receiver component information in the analysis. Different test setups and instrumentation usually are required to obtain these quantities separately; for example, free velocity, blocked force, source and receiver mobilities, isolator properties and transmitted power. A previously proposed approach, combining the inverse force method (IFM) and the reception plate method (RPM), and enabling dual force-power measurement from a single test platform, was demonstrated in laboratory tests. This paper reports on the measurement variations of blocked force and transmitted power from the integrated test setup. To gauge the practicality and readiness of the test methods, an experimental round-robin evaluation was arranged and coordinated with four industrial participants. The same source was used in the round robin evaluation with controlled mounting details, in order to investigate the source installation sensitivity. In general, good agreements were observed between powers obtained by the two methods from data acquired at each test site;

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larger variations were observed in measurement across test sites. Work continues to determine the test method uncertainty; however, both test methods are considered acceptable and ready for wider industry applications.

# **1** INTRODUCTION

In modern airplane development, more lightweight structures and high performance systems (mechanical/hydraulic/electrical equipment) are utilized to achieve higher fuel efficiency, better flight characteristics, and better passenger and crew comfort. The structure-borne noise (SBN) from onboard system operations has been identified as a major source of airplane interior noise, impacting flight deck pilot communication, noise exposure to crew members, and general passenger comfort.

Equipment noise characterisation is an important part of specifying the airplane interior noise level requirement. In addition, it is an essential component for modelling and testing at various development stages, in order to minimize weight of required noise and vibration treatments.

The airplane SBN analysis process comprises two main steps: (1) characterizing the input from a vibration source to the airplane structure and (2) determining the vibration propagation and structural acoustic radiation in the airplane. The second step usually requires some form of transfer path analysis, either by in situ measurement or by modelling, using, as examples, the Finite Element Method (FEM) and/or Statistical Energy Analysis (SEA). Both approaches require SBN inputs from Step (1) in terms of vibration force, velocity, or power. The focus of this paper is to evaluate an integrated test approach for measuring both blocked force and transmitted power.

When removed from the installed situation, the equipment under test can be characterised by the blocked force (which is interchangeable with free vibration velocity if the source mobility is known) at the contact points with the supporting (i.e. power receiving) structure. The blocked force is an independent property of the source, i.e. independent of the installation condition, and can be used with available transfer functions measured from airplane ground tests, to obtain sound pressure in the far field. When the equipment is installed in an airplane, its transmitted power will vary with the supporting structural element at various locations. In the absence of information of the support structure's impedance, the transmitted power, combined with force and velocity information at the contacts of the installed equipment gives the most complete input information for noise analysis. Moreover, most equipment systems are developed by suppliers in parallel with airplane development, and the availability of equipment SBN inputs from suppliers becomes more important before final airplane integration. A force-power SBN measurement test approach, combining the Reception Plate Method (RPM)<sup>1</sup> and the Inverse Force Method (IFM)<sup>2</sup> has been demonstrated to provide both SBN data previously<sup>3-5</sup>. This paper describes a development of this work, which involved the participation of industrial parties in a round robin, to evaluate the test method experimentally and collect feedback from an industrial perspective.

#### 2 SBN FORCE-POWER TEST METHOD OVERVIEW

#### 2.1 Inverse Force Method (IFM)

For an ideal point vibration source, its blocked force can be directly measured with a rigid boundary condition or obtained from its free source velocity  $v_{fs}$  and source mobility  $Y_s$ indirectly. Consider a source mounted on a non-rigid receiver through one contact and through one degree of freedom, giving a force perpendicular to the receiving structure of mobility  $Y_R$ . The source blocked force can be inversely obtained from the contact point velocity  $v_c = v_{fs}Y_R/(Y_s + Y_R)$  and the source-receiver coupled mobility  $Y_C$  expressed in terms of  $Y_s$  and  $Y_R$  (i.e.  $Y_C^{-1} = Y_S^{-1} + Y_R^{-1}$ ). The blocked force thus can be obtained for any receiver mobility, rather than for the normally required very low receiver mobility (the 'inert' receiver structure). This is given in Eq. (1).

$$f_{bl} = \frac{v_{fs}}{Y_s} = \frac{\frac{Y_R v_{fs}}{Y_s + Y_R}}{\frac{Y_R Y_s}{Y_s + Y_R}} = \frac{v_c}{Y_C} \,. \tag{1}$$

By extending the single point expression to the multi-point and multi-DOF (degree of freedom) situation, e.g., a pump mounted at 4 points with three translational and three rotational components, the source blocked force can be obtained in terms of vectors and matrices given in Eq. (2):

$$\mathbf{f}_{bl} = \left[\mathbf{Y}_{A,cc}\right]^{-1} \mathbf{v}_{fs} = \left\{\mathbf{Y}_{B,cc}\left[\mathbf{Y}_{A,cc} + \mathbf{Y}_{B,cc}\right]^{-1} \mathbf{Y}_{A,cc}\right\}^{-1} \mathbf{v}_{c} = \left[\mathbf{Y}_{C,cc}\right]^{-1} \mathbf{v}_{c}, \qquad (2)$$

where A is the source, B the receiver, and C the coupled structure; c is the index of DOFs at the A-B contact interface, and the subscript -1 denotes the matrix inversion.

If perpendicular forces only are considered, Eq. (2) offers an indirect two-step approach to measurement of the associated source blocked force *in situ*, by measuring (1) the source-receiver coupled mobility  $\mathbf{Y}_{C,cc}$  without the source in operation, and (2) the source operational vibration velocities  $\mathbf{v}_{c}$  at all mount points. However, the practical implementation of the approach may be limited by the  $\mathbf{Y}_{C,cc}$  measurement, when the contact points are inaccessible.

Reciprocity is utilized to overcome the implementation / instrumentation challenge. The velocities at the contacts  $\mathbf{V}_{c}$  can be obtained by measuring velocities away from the contact points,  $\mathbf{V}_{b}$ , with the transfer mobility matrix of the receiver between the contact points and the remote points, as:

$$\mathbf{v}_{c} = \mathbf{Y}_{\mathbf{B}, cc} \left[ \mathbf{Y}_{\mathbf{B}, bc} \right]^{-1} \mathbf{v}_{b} \,. \tag{3}$$

By substituting Eq. (3) into Eq. (2), the cluster of source and receiver mobility terms can be greatly simplified into the single transfer mobility term of the coupled system <sup>1</sup>:

$$\mathbf{f}_{\mathbf{b}\mathbf{l}} = \left[ \mathbf{Y}_{\mathbf{C},\mathbf{c}\mathbf{b}}^{\mathrm{T}} \right]^{-1} \mathbf{v}_{\mathbf{b}} \,. \tag{4}$$

The superscript T is the matrix transpose, and the subscript cb in the coupled transfer mobility  $\mathbf{Y}_{C,cb}$  indicates excitations applied at b (*m* accessible points on the receiver structure) and responses measured at c (*n* DOFs at equipment mount points, n < m).

The revised Equation (4) offers an improved test method for situations when the equipment mounting points are not accessible to an instrumented impact hammer, required for the couple mobility  $\mathbf{Y}_{C,cb}$ . With a sufficient number of excitations on the receiver  $(n \le m)$ , not only can over-determination reduce the matrix inversion error, but it also enables integration with the Reception Plate Method (RPM) for measuring the transmitted power and other additional structure-borne quantities.

# 2.2 Reception Plate Method (RPM)

The concept of the reception plate method is based on the power balance principle. On a reception plate, the transmitted power from a vibration source into the plate is equal to the power

dissipated by the plate, which can be estimated from the plate's total energy and loss factor  $\eta$ . For resiliently mounted equipment, the vibration energy output from the source is mostly transmitted into reception plate flexural vibrations with the total plate energy being twice its kinetic energy. Therefore, the transmitted power from the vibration source can be approximated by:

$$\Pi_{input} = \Pi_{dissipated} = \eta \omega m \left\langle v_b^2 \right\rangle.$$
(5)

*m* is the plate total mass,  $\omega$  the angular frequency, and  $\langle v_b^2 \rangle$  the reception plate spatiallyaveraged vibration velocity power spectrum, which can be measured with *p* points within the plate reverberant region,

$$\left\langle v_{b}^{2}\right\rangle \cong \frac{1}{p} \sum_{i=1}^{p} \left| v_{bi}^{2} \right|.$$
(6)

When the measured structure-borne noise power is expressed in octave or in 1/3-octave frequency band,  $\langle v_b^2 \rangle$  is integrated over the frequency band and  $\omega$  is the center frequency of the band. The measurement uncertainty of the reception plate method depends on the accuracy of  $\langle v_b^2 \rangle$  and it can be improved either by averaging over a larger numbers of measurement points or by optimizing measuring point selection. However, this measurement variation is difficult to validate, and thus provides the motivation to integrate the RPM with the inverse force method.

It should be noted that because the transmitted power from a vibration source varies with location, i.e. with supporting structure, care should be taken when applying the measured power by the reception plate method for intended purposes. For applications like an equipment structure-borne noise source ranking or benchmarking, the reception plate method can greatly reduce the testing effort with only plate vibration measurements required.

#### 2.3 Force-Power Integration Test Setup

The development of a test setup, integrating the inverse force method on a reception plate, was driven by the need for both structure-borne force and power measurements, and by the reduced measurement effort and hardware, in integrating two methods<sup>3</sup>. Whilst the blocked force is an inherent property of a vibration source and independent of the installed condition, a reception plate can be used as a general test platform for equipment designed to be installed on plate-like structures.

The measurement effort and instrumentation, in the integrated test setup, is reduced significantly. For example, the response velocity  $\mathbf{v}_{\mathbf{b}}$ , measured by the same set of accelerometers, can be used for both force and power calculations, described in Equations (4) and (6). The frequency response functions, from IFM mobility measurements, also can be used for the loss factor calculation with the impulse response decay method.

In addition to the blocked force by IFM and power by RPM, other SBN quantities can also be obtained with a simple pre-test step on the reception plate. Similar to Eq. (3), the forces at the contacts  $\mathbf{f}_{c}$  can be obtained with the transfer mobility  $\mathbf{Y}_{B,bc}$  of the reception plate measured during the loss factor impact testing as shown in the following,

$$\mathbf{f}_{\mathbf{c}} = \left[ \mathbf{Y}_{\mathbf{B},\mathbf{b}\mathbf{c}} \right]^{-1} \mathbf{v}_{\mathbf{b}} \,. \tag{7}$$

By combining  $\mathbf{f}_{c}$  with the contact velocities  $\mathbf{v}_{c}$ , the transmitted power is obtained,

$$\Pi = \mathbf{f}_{c} \cdot \mathbf{v}_{c} \,. \tag{8}$$

The two independent measurements by the two test methods, Eq. (5) and Eq. (8), of the same vibration source power also provide a useful self-check of quality.

## **3 ROUND ROBIN EVALUATION**

In order to evaluate the practicality and measurement variation of the test setup and test methods under typical industrial conditions, an experimental round robin evaluation was designed and coordinated with four industrial partners. The same measurements were conducted at each test facility with the same tested source, to minimize measurement variations due to hardware differences.

#### 3.1 TEST HARDWARE AND INSTRUMENTATION

The selected SBN source was an off-the-shelf commercial constant-speed air pump which was shipped from one test site to the next during the round robin evaluation. Each test site (labeled Test Site #1, #2, #3 and #4) procured or fabricated a stainless steel reception plate with dimensions 38.0 in by 54.0 inches by 3/16 inches (965.2 mm by 1371.6 mm by 4.8 mm). The plates, of approximate weight of 48.5 kg, were supported by visco-elastic damping strips along four edges on a support stand. Accelerometers were mounted under the plate but marked on the plate upper surface to improve the excitation-response alignment for the impact hammer test. The test setups at the four test facilities are shown in Figure 1.

While each test site followed the same guidelines on setting up the test rig and instrumentation, the pump source was allowed to be installed at different positions and orientations with respect to the plate geometry and measured with different numbers of accelerometers at different locations. The purpose was to evaluate the measurement variations due to these installation differences and the sensitivity of the two test methods, with respect to the source-receiver coupled structures.

# **3.2 TEST PROCEDURES**

All test participants were instructed to follow test standards as much as possible: ISO 5348 <sup>7</sup> on vibration accelerometer mounting, ISO 16063-21 <sup>8</sup> on accelerometer calibration and ISO 7626-2 <sup>9</sup> for the measurement of mechanical mobility.

## **Pre-Test**

Prior to mounting the test source onto the test stand, a pre-test was conducted to finalize measurement locations and check the data acquisition system for measurement of the loss factor of the reception plate using an impact hammer. The measured loss factor was little affected by the source contact condition, including with no source attached (see Figure 2), and need only be measured once, prior to test. During the loss factor measurement, the plate mobility  $Y_{B,bc}$ , required to calculate the contact force  $\mathbf{f}_c$  in Eq. (7), was also obtained from the subset of acquired frequency response functions.

## Step-One

After the pre-test, with the reception plate loss factor and plate mobility recorded, the source was then attached the reception plate, and the impact hammer measurement of the source-receiver coupled mobility  $\mathbf{Y}_{C,cb}$  performed with the source turned off (i.e., the power off

condition). This test step is similar to the pre-test step, except with the source installed on the plate and actually requires fewer impacting points.

#### Step-Two

The pump was operated at controlled specified conditions, and the response velocities recorded at the accelerometer locations remote from the source,  $\mathbf{v}_{b}$  and at the source mount points  $\mathbf{v}_{c}$ . With the loss factor available, only the measured plate velocity  $\mathbf{v}_{b}$  is required for the transmitted power by the Reception Plate Method.

Although the test procedure comprises three steps, the procedure is quite straight forward. However, the importance of measurement location, selection and data channel indexing, before test, is emphasized. A well thought-out plan can significantly increase the test efficiency, reduce required instrumentation, and improve measurement accuracy<sup>3</sup>.

## 4 TEST RESULTS AND MEASUREMENT VARIATIONS

There were four source mounting configurations for the round robin evaluation: the air pump rigidly mounted on the plate, and resiliently mounted with three different sets of vibration isolators. The measurement variation analysis reported in this paper is based on the mounting configuration without isolator at all test sites, with one data set (Test Site #1) selected to show the comparison on the transmitted power with and without isolators, obtained by the two methods. The selected quantities for variation analysis are: loss factor, source contact vibration velocity, blocked force, and transmitted powers by both IFM and RPM. Data at all sites were acquired from 0 to 10,000 Hz with 3 Hz resolution and were processed into 50 Hz to 8000 Hz in 1/3 octave bands. The measurement standard deviations (STD) are calculated for each 1/3

octave band with data from all test sites listed in Table 1. All measured quantities are plotted, including the mean values with +/- STD.

#### 4.1 VARIATIONS DUE TO TEST SETUP AND SOURCE OPERATION

#### 4.1.1 LOSS FACTOR

Various loss factor calculation methods were tried. The impulse response decay method was selected and used to calculate the loss factor of test setup at all sites. The loss factors obtained at the four test sites are presented on the dB scale  $(10\log_{10})$  and plotted as the mean value and +/- STD in Figure 3.

The differences in reception plate dimensions and plate material properties appear not to be significant, compared to other factors in this round robin evaluation. Major variations in measured loss factors were attributed to (1) types and amount of damping materials used to support the plate, (2) test stands to support the reception plate, (3) differences in numbers of accelerometers, and (4) excitation-response alignment consistency of the impact hammer testing.

#### 4.1.2 SOURCE OPERATION

Next measurement variation investigated was due to the air pump operation at all test sites, which could be caused by hardware changes during transportation, handling and installation, or by test environment differences in electrical power quality, temperature, humidity, etc. The source contact velocity  $\mathbf{V}_{c}$  was selected as an indication of the pump performance, to indicate any damage or other change during the round-robin. Unfortunately, the contact velocity  $\mathbf{V}_{c}$  also includes the variations due to the pump installation differences. The measured pump vibration

velocity (averaged from four mount points) is expressed in dB level  $(20\log_{10} \text{ re } 1 \text{ m/s})$ , and plotted with mean values in Figure 4.

#### 4.2 BLOCKED FORCE AND TRANSMITTED POWERS

The target SBN quantities are the source blocked force and transmitted power. The blocked force calculations were performed according to Eq. (4) with the same processing procedures and parameters applied to data acquired from all test sites. The blocked forces at four mounting points were first obtained through narrow-band matrix inversion, and then integrating into 1/3 octave bands for each contact force, and then averaging the four site values. The blocked force is expressed in dB level ( $20\log_{10}$  re 1 Newton), and plotted with mean values in Figure 5.

Two transmitted powers, measured by RPM and IFM, were calculated independently according to Eq. (5) and (8), respectively, based on data acquired by different sets of accelerometers in the same test. In RPM, the plate average velocity measured in narrow bands was first integrated into 1/3 octave bands before combining with loss factor. The RPM transmitted powers are expressed in dB level ( $10\log_{10}$  re 1 picowatt) and plotted with mean values in Figure 6.

The calculation of IFM transmitted power requires more data processing: calculate the transmitted force at each contact, multiply the force and velocity at each contact and sum them, then integrate the narrow band data into 1/3 octave bands. Again, the IFM powers are expressed in dB level ( $10\log_{10}$  re 1 picowatt) and plotted with mean values in Figure 7. To better illustrate the overall variation in transmitted power measurements across the four test sites and the consistency of the power measurements obtained by the two methods, all measured powers are compared in Figure 8.

# 4.3 DISCUSSION

All STDs, listed in Table 1, are to compare variations of select measured quantities in each 1/3 octave frequency band, and provide an indication on the repeatability and reproducibility. However, it is not immediately obvious which one quantity has a smaller variation than another from Table 1. An overall estimate of measurement variation of selected quantities was to average all 1/3 octave band STDs to simplify the comparison. Two averages over two frequency ranges, 50 Hz – 8,000 Hz and 100 Hz – 8,000 Hz respectively, are calculated and summarized in Table 2.

The variation in the loss factor measurement is noticeably smaller than of the other quantities. It is expected that the same reception plate, when mounted on two test stands and producing different loss factors, will have different response velocity levels, i.e., higher velocities on the lower loss factor stand and lower velocities on the higher loss factor stand. As a result, the variation in the measured RPM power, contributed by the loss factor, should be smaller than the STDs shown in both Table 1 and 2. The loss factor STD measured here is to provide a quantitative indication on the variation to be expected from a reception plate test setup in typical industrial facilities.

Although the sample size (four data sets) are not statistically sufficient to quantify the difference of the two test methods, the averaged STDs in the blocked force and transmitted power measured by IFM are slightly smaller than those by the RPM. Smaller STDs in IFM measurements can be found in 1/3 octave bands. The blocked force measurements show a 8 dB range across the four test sites, where power measurements show a range of 13 dB above 100 Hz, with most bands within 10 dB. An early published study in structure borne sound source

characterizing test technique also reported a similar accuracy in their round robin test (+/- 5 dB in predicted transmitted power)  $^{6}$ .

Based on data acquired from the same test setup, the agreement between transmitted powers by RPM and IFM is about 3 dB in most 1/3-octave bands from all four test sites. One example from Test Site #1 is shown in Figure 9.

## **5** CONCLUSIONS

For structure-borne noise, both source blocked force and transmitted power are needed in order to apply empirical (transfer-function based) and numerical (BEM/FEM/SEA based) airplane models to predict equipment noise in the airplane crew and passenger spaces. The same processes are also required to specify noise and vibration limits for equipment suppliers. Being able to integrate the Inverse Force Method and the Reception Plate Methods on the same test setup has the advantage of obtaining more SBN quantities more effectively than if the two tests were perform separately.

In this round robin evaluation, with the same test source and similar test rigs, the variations show that the SBN measurement is sensitive to structural changes of the test setup. When applicable, the relatively simple structure of a reception plate can be an ideal test platform.

Tonal noise, at the fundamental frequency and higher harmonics of operating equipment, often dominate the sound quality metrics and impacts the crew and passenger comfort. The measurement variation in these frequency bands needs to be more carefully controlled. It is necessary and possible to design a test setup with proper instrumentation and layout to improve the measurement accuracy over the target frequency range accordingly.

Although combining the two methods on a single setup adds to the complexity to the test, with a well thought-out plan the integrated rig can take the full advantage of the two methods and provide more measurement quantities for less effort.

This round robin highlighted the practicality of integrating the two test methods and the collaboration with the industrial participants provided feedback, helpful in identifying practical issues, for the development of the test methods for wider industrial applications.

## **6** ACKNOWLEDGEMENTS

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1/3 Oct. Band Cntr. Freq. (Hz)	Loss Factor (dB re 1)	Source Velocity (dB re 1 m/s)	Blocked Force (dB re 1 N)	Power IFM (dB re 1 pW)	Power RPM (dB re 1 pW)
50	3.0	6.1	2.3	6.3	10.0
63	2.7	8.6	4.7	4.3	6.2
80	1.7	9.2	8.2	7.0	4.2
100	2.3	9.8	7.3	7.5	5.3
125	1.9	5.5	1.7	5.4	5.0
160	2.0	4.6	9.3	1.7	5.2
200	1.6	4.9	6.4	4.7	8.3
250	1.5	3.9	3.5	3.3	6.4
315	1.7	2.4	1.9	2.0	3.2
400	2.1	4.3	3.4	3.1	3.7
500	2.3	4.1	2.7	1.7	4.1
630	2.4	3.2	6.1	6.3	2.6
800	1.3	4.8	0.8	2.6	2.7
1000	1.8	3.0	2.3	1.2	2.6
1250	2.0	1.9	2.5	2.0	3.0
1600	2.1	2.9	3.1	2.8	2.9
2000	2.2	4.3	5.0	4.4	3.8
2500	1.6	3.4	2.9	2.9	3.8
3150	1.4	5.3	3.5	3.9	4.5
4000	1.0	4.6	1.9	2.2	3.8
5000	0.4	3.4	2.2	2.8	4.0
6300	0.5	3.3	0.9	2.5	3.1
8000	0.6	4.1	1.8	3.2	4.3

Table 1 - Standard deviations of measured SBN quantities in one-third octave bands.

Table 2 – Frequency averaged standard deviations of measured SBN quantities.

SBN Quantity	η	$\langle {f f}_{bl}  angle$	$\mathbf{f}_{\mathbf{c}} \cdot \mathbf{V}_{\mathbf{c}}$	$\langle \mathbf{v_c} \rangle$	$\omega\eta m \left\langle v_{b}^{2} \right\rangle$
Frequency Averaged STD	Loss Factor (dB ref. 1)	Blocked Force (dB ref. 1 N)	Power IFM (dB ref. 1 pWA)	Source Velocity (dB ref. 1 m/s)	Power RPM (dB ref. 1 pWA)
Avg. Over 50-8000 Hz	1.7	3.7	3.6	4.7	4.5
Avg. Over 100-8000 Hz	1.6	3.5	3.3	4.2	4.1



(a) Test Site #1





(c) Test Site #3



Fig. 1 - Test setups at four participant facilities with the same SBN source (an air pump).

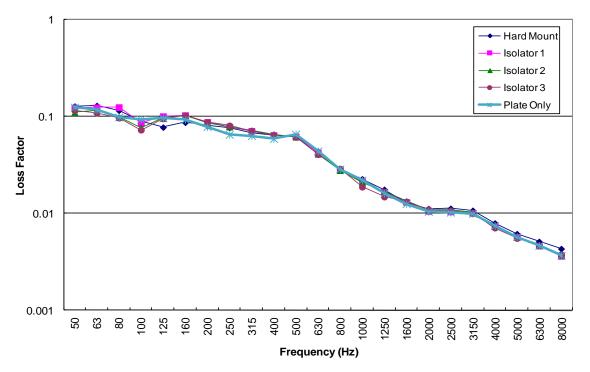


Fig. 2 - Loss factors of the reception plate, with and without the source installed, Test Site #1.

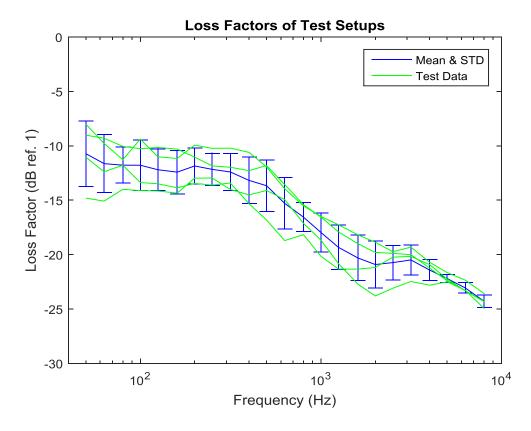


Fig. 3 - Loss factors of test setups at the four participant test sites, with means and standard deviations.

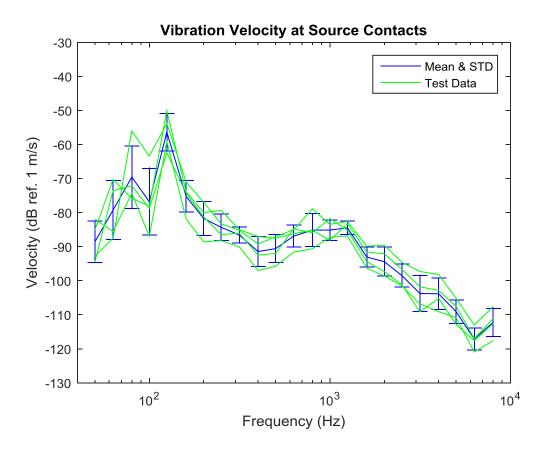


Fig. 4 - Source velocity measurements at four test sites, with means and standard deviations.

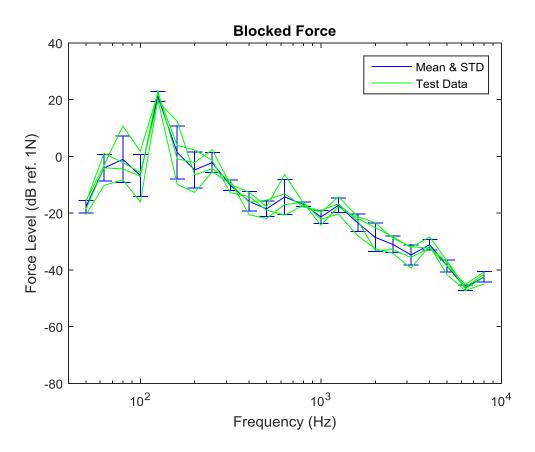


Fig. 5 - Blocked force measurements at four test sites by IFM, with means and standard deviations.

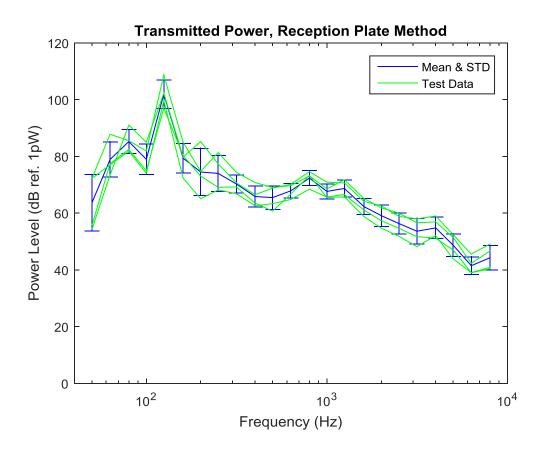


Fig. 6 - Transmitted power measurements at four test sites by RPM, with means and standard deviations.

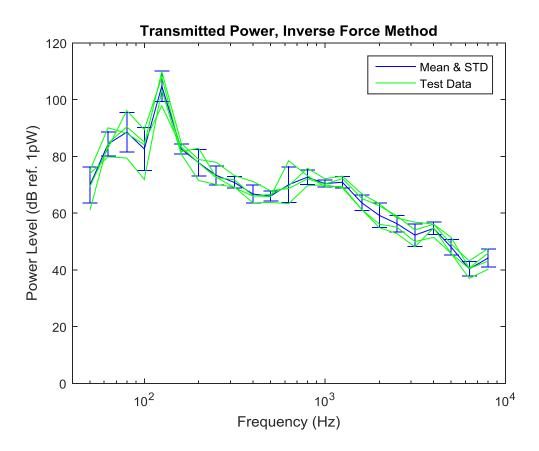


Fig. 7 - Transmitted powers measured at four test sites by IFM, with means and standard deviations.

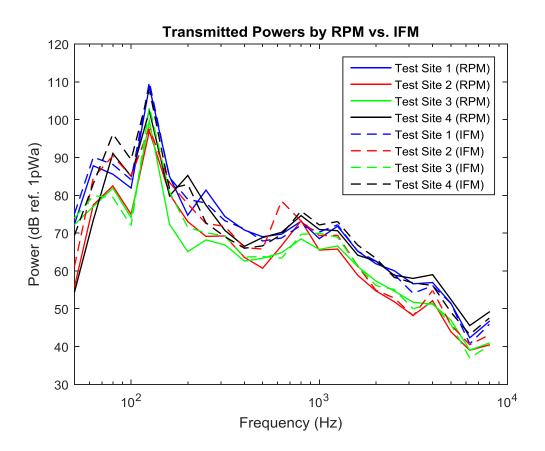
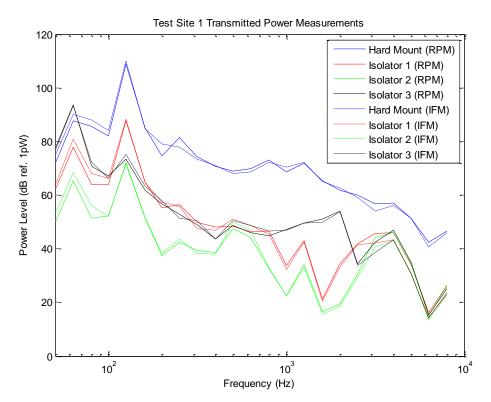


Fig. 8 - Transmitted powers measured by RPM at four test sites (solid lines) vs. IFM (dashed lines)..



*Fig.* 9 - *Transmitted powers measured at Test Site #1, by IFM and RPM, for the pump with and without vibration isolators..*