# **3-D MRI Brain Scan Classification of Epilepsy versus Non-epilepsy**

MIUA 2013 Submission # ??

### Abstract

A 3-D classification method is presented for Magnetic Resonance Imaging (MRI) brain scan volumes of interest. The objective of the classification is to identify volumes that feature indicators of epilepsy against volumes that do not by considering the shape and size of the lateral (left and right) ventricles of the brain. The dataset used with respect to the reported experimentation comprised 210 3-D MRI brain scans of which 105 were from epilepsy patients and the remainder from healthy people. The classification is supported by two proposed point-series based representation techniques: (i) Disc and (ii) Spoke. The reported experimental results indicated that our proposed techniques can classify 3-D MRI brain scan data with a classification accuracy of up to 69.81%.

## **1** Introduction

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Automated (or semi-automated) medical prediction is a challenging real world problem. The 023 effective and efficient automated prediction of medical conditions is clearly of significant 024 benefit especially with respect to the use of resources, even if used as a "first screening". 025 The work presented in this paper is directed at the automated screening for epilepsy from Magnetic Resonance Imaging (MRI) brain scan volumes (although the work has clear appli-027 cation elsewhere). Epilepsy is a medical condition whereby nerve cell activity in the brain is disturbed; it causes abnormal behaviour accompanied by symptoms such as loss of consciousness or convulsions. There are various indicators for the cause of epilepsy, one is the shape and size of the ventricles contained in the brain  $[\Box]$ . This can be measured by manuel inspection of MRI scan data. MRI brain scan data consists of a sequence of 2-D "slices" in three planes: Sagittal (SAG), Coronal (COR), and Transverse (TRA). Collectively we refer to this set of slices as a *volume*. However, although tools exist to support manuel inspection (for example the Brain Voyager range of software products), the process is time consuming, challenging and error prone. Automation of the process therefore seems desirable.

This paper proposes the use of a machine learning approach, more specifically a classification approach. Classification is concerned with the automated allocation of labels to data using a piece of software known as a classifier; in our case the input is a description of the lateral ventricles and the labels are the set {*epilepsy*, ¬*epilepsy*}. However, the classification process also entails a number of challenges, the most significant of which are: (i) the production of the classifier and (ii) the mechanism for representing the input in such a way the key information is retained while at the same time ensuring tractability (the two challenges are related). Classifiers are typically generated using pre-labelled training data (we refer to

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this as *supervised learning*). There are various techniques where by classifiers can be learnt, 046 in this paper we explore the use of two. So as to obtain a level of confidence in a generated 047 classifier it is typically evaluated against pre-labelled test data. 048

The representation of the input data is a key part in the classifier generation process. 049 The image representation will affect both the efficiency and effectiveness of the machine 050 learning. In this paper, two representation techniques, referred to as the Disc-based and 051 Spoke-based representations, are proposed. Both are point-series representation techniques 052 in that they are designed to capture the boundary a Volume Of Interest (VOI) in terms of a 053 series points which in turn can be conceptualised as a curve in 2-D space. Such curves can 054 be used directly for classification purposes using (for example) a kNN (k Nearest Neigbour) process [3] which requires some form of similarity measure; in this paper we use the length 056 of the shortest "warping path" generated using the well established Dynamic Time Warping 057 (DTW) technique. Alternatively the curves can be processed further so that a *feature space* model is derived which will allow for the individual VOI to be represented in terms of a *feature vector*. In this paper we suggest the use of Hough "signature" extraction for this purpose. Feature vector representations are compatible with a number of "standard" classifier 061 generation models, in this paper the Support Vector Machine (SVM) [2] model is used but any other form of classifier generation model may be equally well applicable. Both the Disc and Spoke based representations are described as well as the kNN and SVM classification 064 processes, together with a full evaluation.

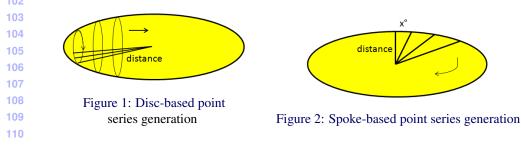
## 2 Point Seres Generation

From the above, two techniques for generating a point series representation are proposed, the 069 Disc-Based technique and the Spoke Based technique. The input in both cases is a previously 070 segmented description of the VOI (the lateral ventricles in our case). With respect to the 071 evaluation presented later in this paper the authors used the *Bounding-Box* segmentation 072 technique proposed and described in [III] together with a thresholding technique for noise 073 removal. Other similar techniques would have sufficed however experiments conducted by 074 the authors, and presented in [1], indicate that the Bounding-Box technique works well with 075 respect to the lateral ventricles (a comparison was conducted against manually identified 076 ventricles and a good correlation was found to exist). Essentially the segmentation results 077 in a *zero-one* representation where voxels that are part of a VOI (the lateral ventricles) are marked with a 1 (black) and voxels that are not part of the VOI are marked with a 0 (white). The Disc-based technique is described in Sub-section 2.1 and the Spoke based technique in Sub-section 2.2 below. 081

## 2.1 Disc-based Representation Technique

The Disc-based representation technique is illustrated in Figure 1. A point series is generated by taking a series of measurements from the centroid of the VOI (the lateral ventricles) to each voxel located on the boundary of the VOI. This is achieved by iteratively moving a 2-D plane along the length of the VOI voxel by voxel along a selected axis. At each iteration the intersection between the plane and the VOI was identified and measurements taking from the centroid of the VOI to the the voxels located along the boundary of the intersection. With respect to the ventricles the intersection typically took the form of a "disc" ogo shape, hence the name "Disc-based" representation. Whatever the case the measurements 091

were then used to describe a 2-D curve with distance along the Y-axis and the sequential 092 093 measurement identification number along the X-axis. In the case of the ventricles three such curves were generated one for each of the three cardinal axes: Sagittal, Coronal and 094 Transverse. A perceived disadvantage of the Disc-based technique is that a large number of 095 points are generated giving rise to substantial curves which in turn might require considerable computational resource to process (it is desirable for screening to be conducted at time 097 of consultation, thus in real time using the processing power available on standard desk top machines). Note also that the Disc-based technique, given a collection of segmented ventri-099 cles, will produce curves of different lengths (ventricles will be of different sizes) which is 100 not ideal for comparison purposes. The Spoke based technique described in the following 101 sub-section seeks to address this issue.



## 112 2.2 Spoke-based Representation Technique

The spoke based point series generation technique is illustrated in Figure 2. The idea is 114 to measure the distance from the centred to the VOI boundary only in the three cardinal 115 planes (Sagittal, Coronal and Transverse in the case of our ventricles). This is achieved by 116 considering each plane in turn and conceptually generate a set of "spokes" radiating out from 117 the centroid, spaced at some angle of separation  $x^{\circ}$ , and then measuring the distance from 118 the centroid to where the spoke cuts the boundary of the volume (when the spoke reaches a 119 back voxel followed by a white voxel). The result was again three point series, but in this 120 case each point series contained fewer points than in the case of the Disc-based technique. 121 In addition the curves will all be of the same length provided the same value of x is used 122 through out 123

## <sup>126</sup> 3 Classification

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128 For classification purposes we require a training set of pre-labelled data (in our case a MRI 129 brain scan dataset with each scan labelled as either *epilepsy* or  $\neg epilepsy$ . Point series 130 (curves) can then be generated from the data and a label associated with each curve. These 131 curves can then be used directly for classification purposes or be processed further and then 132 used for classification purposes (further processing might result in a more effective and/or efficient representation). In the first case classification can be conducted simply be com-134 paring new curves associated with unlabelled VOI with existing curves in our "curve base". The proposed process is described in sub-section 3.1 below. In the second case we translate 136 the point series into a standard feature space representation compatible with many "off-theshelf" classifier generators. This process is described in sub-section 3.2 below.

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### 3.1 Direct Classification

139 Using the generated point series (curves) directly to classify "unseen" data the use of k-140 Nearest Neighbours (kNN) classification  $[\Box]$  is proposed with k set to 1. The kNN classification 141 sification approach requires a distance measure, Euclidean distance is frequently used for 142 this purpose, however this is clearly unsuitable when comparing curves (which may also be 143 of different length). Instead Dynamic Time Warping (DTW) as described in [I] was used 144 to identify a *warping path*. DTW is a well established technique used to compare curves. 145 DTW operates as follows. Given two curves, X with length m and Y with length n, a matrix 146 A is constructed with m rows and n columns. Each element (i, j) within matrix A describes 147 the distance between point i on curve X and the point j on curve Y. The goal is to find the 148 "warping path" through this matrix describing the shortest distance from (0,0) to (m,n). To 149 improve the efficiency with which this warping path can be identified the "Sakoe-Chiba" band [] was used to define a "constraint region". The length of the warping path can then be used as a measure of the similarity between two curves. Using this approach the most 151 similar curve in the curve based to a given new curve (representing a previously unseen ven- 152 tricle extracted from a MRI brain scan) can be identified and the label from the identified 153 curve used to label the new curve.

## 3.2 Classification after Further Processing

The idea behind the further processing of the point series data is that this might result in a <sup>158</sup> more effective representation for classification purposes in that redundant information may 159 be removed. More specifically to idea is to generate a collection of point series using a pre- 160 labelled training set and then converting these point series into a set of "feature vectors" or 161 "signatures" representing key elements of the point series. Collectively the feature vectors 162 (signatures) describe a multi-dimensional feature space (one dimension per feature where 163 each feature has a number of potential values associated with it) in which each point series 164 is described by a single location within the space described by the vector from the origin of 165 the feature space to the location. To this end Hough feature extraction, based on the Hough 166 concept [1], was used to identify signatures from within the point series (curve) data. The 167 curves were firstly transformed into a parameter space (accumulator matrix) A comprised of 168 169 \_\*\*\* and *n* \*\*\* SAY WHAT *n* IS \_\_\_\_\_ -170

## **4** Evaluation

From the foregoing two point series representation methods are proposed (Disc-based and 179 Spoke-based) which can be either used directly for classification purposes (using *k*NN coupled with DTW in our case) or processed further and then used for classification purposes 181 (using Hough signature extraction and the SVM classification model in our case). The comparative evaluation of these four different mechanisms is presented in this section. For the 183

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evaluation a dataset comprised of 210 MRI brain scans, obtained from the Magnetic Reso-184 nance and Image Analysis Research Centre at the University of Liverpool, was used. Each 185 scan consisted of 256 two dimensional (2-D) parallel image slices in each of the three car-186 dinal planes. The resolution of each image slice was 256 x 256 pixels (voxels) with colour 187 defined using 8-bit gray scale (256 colours). The data set is described in more detail in [11]. It should also be noted that it has been used in a number of other studies, for example in [1] 189 it was used to determine the relationship between the size of the corpus callosum (another 190 readily identifiable object in MRI brain scan data) and epilepsy, although in this case the 191 study was conducted in 2D using only the mid-sagittal slice of the collected data. 192

The reported experiments were conducted using Ten-fold Crossed Validation (TCV) 193 where different tenths of the data were used as the test set. In the case of the Spoke-based 194 technique a sequence of values for x were used  $\{1^{\circ}, 2^{\circ}, 3^{\circ}, 4^{\circ}\}$ . The SVM model provided 195 with The Waikato Environment Knowledge Analysis (WEKA) data mining workbench [] 196 was used where required. The classification results obtained are shown in Tables 1 and 2. 197 Table 1 shows the results obtained using direct classification (kNN and DTW similarity measurement) and Table 2 the results after further processing (Hough signature extraction and SVM). Both tables list the accuracy (Accu.), sensitivity (Sens.) and specificity (Spec.) values obtained. From the tables it can be observed that: (i) the spoke based representation outperformed the disc based representation, (ii) the spoke based representation tended to improved as the value of x increased and then drop off (using direct classification  $x = 2^{\circ}$  tended to produced the best results, while with further processing  $x = 3^{\circ}$  tended to produced the best results) and (iii) direct classification produced better overall average results than obtained after further processing. The reason for the Spoke-based representation outperforming the 206 disc based representation is conjectured to be because the spoke based representation was more succinct and therefore less cluttered (less room for ambiguity). The conjectured reason 208 for the direct classification approach outperforming the alternative approach is that the additional processing conducted in the later case had the effect of coarsening the representation 209 210 with the result that some information was lost. The best accuracy, sensitivity and specificity values were all obtained using the Spoke-based representation and direction calcification: 211 69.81 ( $x = 2^{\circ}$ ), 75.47 ( $x = 3^{\circ}$ ) and 67.92 ( $x = 2^{\circ}$ ) respectively. It should also be noted 212 that the Spoke based techniques was also more efficient because the resulting point series 213 encompassed fewer points. 214

215	Technique	Accu.	Sens.	Spec.
216	Disc	62.20	67.50	57.14
217	Spoke ( $x = 1^\circ$ )	64.15	66.04	62.26
218	Spoke ( $x = 2^{\circ}$ )	69.81	71.70	67.92
219	Spoke ( $x = 3^{\circ}$ )	68.87	75.47	62.26
220	Spoke ( $x = 4^{\circ}$ )	60.98	67.50	57.14
221	Average	65.20	69.64	61.34

Technique	Accu.	Sens.	Spec.
Disc	59.43	58.49	60.38
Spoke ( $x = 1^{\circ}$ )	59.43	58.49	60.38
Spoke ( $x = 2^{\circ}$ )	62.20	67.50	57.14
Spoke ( $x = 3^{\circ}$ )	64.63	70.00	59.52
Spoke ( $x = 4^{\circ}$ )	61.32	62.26	60.38
Average	61.40	63.35	59.56

Table 1: Classification results obtained using KNN and DTW

Table 2: Classification results obtained using Hough Signature Extraction and SVM

#### 225 **Conclusions** 5 226

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227 This paper has proposed an approach to 3-D MRI brain scan classification using two pointseries based representations, Disc-based and Spoke-based. These can be used directly (a kNN based approach is suggested) or processed further (a Hough signature extraction ap-

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proach is suggested) and then input to a standard classifier generation model (the SVM 230 model was used with respect to the reported evaluation). The approaches were evaluated 231 in the context of epilepsy classification with respect to lateral ventricle data obtained from 232 3-D MRI brain scans. The main findings were that the Spoke-based representation outper-233 formed the Disc-based representation (especially when  $x = 2^{\circ}$  or  $x = 3^{\circ}$ ) and that direct 234 classification produced better results than when further processing was applied to the point 235 series data. Compare to other previous works the results reported in [1] were slightly better 236 than those reported here, although this work was directed at the corpus callosum which might 237 be a better indicator of epilepsy. Better results were also reported in [1], using an oct-tree 238 representation of the ventricles, although in this case the work was directed at classifying 239 Alzheimer's disease and level of education rather than epilepsy.

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