

# Nuanced Robustness Analysis with Limited Information

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## Abstract

This paper presents a nuanced robustness analysis for structures when only limited information is available. A new methodology based on fuzzy set theory is proposed to cope with scarce information as a major problem in the performance assessment of existing structures. The developed robustness measure provides information on the relationship between structural robustness and the magnitude of uncertainty in the damage of the structure. This feature is enabled through a nuanced consideration of imprecision in the damage assessment via alpha-level discretization. An entropy-based robustness measure is formulated as a function of imprecision in the damage state. On this basis different design solutions can be compared, in a one-swoop analysis, with respect to their robustness for different magnitudes of damage. This approach can, further, be used to assess effort for inspection versus gain in precision of the predicted structural performance. The development is of a general nature. Herein, it is elucidated in the context of a typical offshore en-

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gineering problem in order to demonstrate its application in practical cases. Fixed offshore platforms with different brace configurations are compared in view of robustness with respect to damage from corrosion.

*Keywords:* Robustness assessment; Imprecision; Entropy measure; Fuzziness; Alpha-level discretization; Marine corrosion; Fuzzy modeling

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## 1. Introduction

2 A nuanced robustness assessment is developed to compare structural de-  
3 sign solutions regarding their performance in dependence on the magnitude  
4 of uncertainty in the assessed damage of the structures. To address the partic-  
5 ular relevance of the development to current industrial challenges, we focus  
6 on offshore structures under only vaguely known corrosion damage. In this  
7 context, robustness is a measure to assess a jacket structure's ability to sus-  
8 tain damage with a limited loss of ultimate capacity and, therefore, reliability  
9 [1]. A "robust" structure has inherent redundancies in terms of alternative  
10 load paths that allow the structure to withstand global damage caused by  
11 various events such as ship impact, extreme storms, explosions, etc. For less  
12 robust structures, however, a small damage event may significantly dimin-  
13 ish the platform's global capacity resulting in a high-risk situation which  
14 requires immediate response such as platform de-manning, platform shut-  
15 down, or emergency repair. Robustness consideration in this context usually  
16 aims to mitigate the risk from disproportionate failure or progressive collapse  
17 due to damage caused by extreme loads or accidental loads. In the litera-  
18 ture, robustness of fixed offshore platforms is usually evaluated through the  
19 ultimate strength analysis of structures in both intact and damaged states,

20 which leads to a number of deterministic performance measures using the  
21 concept of reserve strength and residual strength, see [2]. The prescribed  
22 damage scenarios are frequently associated with removal of one critical mem-  
23 ber or several members in the intact state, see [3]. However, there are other  
24 sources of damage that, in contrast to damage suddenly provoked by ac-  
25 cidental actions, arise gradually in time from aging of structures and may  
26 also involve disproportionate effects, including marine corrosion, see [4]. Be-  
27 sides the deterministic performance measures, the inevitable uncertainty in  
28 engineering practice has led to the development of probabilistic robustness  
29 measures based on reliability and risk analysis of structures, see [5, 6, 7]. A  
30 brief review of these measures is given in Section 2.

31 Robustness can also be understood as a structure's capacity to withstand  
32 the normal fluctuations of environmental conditions without noticeable ef-  
33 fects on its serviceability. In this context, robustness denotes a high degree  
34 of independence between the uncertainty of structural parameters and the  
35 associated uncertainty in structural responses. Assessments of this type of  
36 robustness are devoted to obtaining global statements about the degree of  
37 structural response variation with respect to input fluctuations at once. Com-  
38 monly, all uncertain parameters are described as random variables, which  
39 enables the application of probabilistic measures to assess structural robust-  
40 ness. As pertinent developments in robustness assessment in this context rely  
41 heavily on probabilistic models, a proper treatment of uncertainty is of vital  
42 importance for this point of view in understanding robustness. This includes  
43 the characterization of the deterioration of structural strength due to marine  
44 corrosion, which has adverse effects on the safety of offshore structures. The

45 corrosion effects on the reliability of offshore structures has been studied in  
46 [8] where the probabilistic corrosion model from [9] for mild steel immersed  
47 in seawater was adopted to estimate the uncertainty in the corrosion depth  
48 for a relatively short period.

49 In engineering applications, the knowledge about the fluctuations of the  
50 structural parameters can be quite limited so that a clear probabilistic spec-  
51 ification of uncertainty can be problematic. This is associated with rare and  
52 imprecise data. Examples are uncertain quantities for which mere bounds or  
53 linguistic expressions are known. For this type of information, alternative,  
54 non-probabilistic and mixed models provide reasonable properties [10]. Mea-  
55 sures for the associated information content are available [11]. The usefulness  
56 and capabilities of these models and approaches, such as interval analysis,  
57 fuzzy set theory, evidence theory, imprecise probabilities and fuzzy random  
58 variables, have already been demonstrated in the solution of practical prob-  
59 lems in civil and mechanical engineering [12, 8, 13, 14]. For the envisaged  
60 development the concept of fuzziness is selected to cater for the subjective  
61 character of the assessment of deterioration due to imprecise marine corro-  
62 sion. This selection is motivated by the growing demand for quick structural  
63 performance assessments based on quite limited information from coarse in-  
64 spections without detailed measurements as quantification basis. In such  
65 cases, the available information does not provide a proper basis for a prob-  
66 abilistic modeling but can still be sufficient to derive reasonable decisions  
67 when it is coarsely translated into effects on structural performance.

68 In this paper, we propose a nuanced robustness assessment based on fuzzy  
69 set theory and an assessment of fuzziness using an analog to SHANNON's en-

70 tropy [15]. We tap on the robustness measure proposed in [16] and expand  
71 the concept from assessing robustness with a static number to the formula-  
72 tion of a robustness function depending on the magnitude of uncertainty in  
73 the structural conditions. This function enables the exploration of depen-  
74 dencies between structural robustness and the magnitude of uncertainty in  
75 the structural damage, which opens a new kind of insight into the structural  
76 problem and may facilitate a trade-off assessment for inspection effort versus  
77 gain in confidence for performance, safety and robustness predictions. The  
78 developments are elucidated by means of robustness assessment of aging off-  
79 shore structures under marine corrosion with reference to the data provided  
80 in [17]. In the sequel, robustness measures from the literature are reviewed in  
81 Section 2. Section 3 is devoted to the development of the proposed nuanced  
82 robustness assessment. The usefulness of the proposed method is demon-  
83 strated in Section 4 by way of investigations of fixed offshore platforms with  
84 different brace configurations.

## 85 **2. Review of Robustness Measures**

### 86 *2.1. Deterministic performance measures*

87 Robustness is a measure to assess a platform's ability to sustain damage  
88 caused by extreme loads or accidental loads without disproportionate failure  
89 with respect to the causes of the damage itself. According to this under-  
90 standing of structural robustness, deterministic performance measures are  
91 developed through comparing the structural performance in both intact and  
92 damaged states based on ultimate strength analysis. For the investigated  
93 frame structures, the ultimate strength depends on the nonlinear response

94 of components of the frame and the nonlinear structural interaction between  
 95 components through plastic deformation and load redistribution. The frames  
 96 with different bracing configurations have different overall structural perfor-  
 97 mance, usually described as “brittle” or “ductile” behavior. The concept  
 98 of reserve strength and residual strength can be used to evaluate structural  
 99 robustness associated with the ultimate conditions. The following three de-  
 100 terministic performance measures have been tested for a range of structural  
 101 frames in [2].

102 Reserve strength can reflect the ability of an intact structure to sustain  
 103 loads in excess of the design value. The Reserve Strength Ratio (RSR) is  
 104 defined as

$$\text{RSR} = \frac{\text{ultimate resistance of intact structure}}{\text{design environmental load}}. \quad (1)$$

105 Similarly, the Damage Strength Ratio (DSR) is defined to measure the ability  
 106 of a damaged structure to sustain loads in excess of the design value,

$$\text{DSR} = \frac{\text{ultimate resistance of damaged structure}}{\text{design environmental load}}. \quad (2)$$

107 The residual strength reflects the ability of having alternative load paths to  
 108 carry loads shed from damaged members (i.e. redundancy). The Residual  
 109 Resistance Factor (RRF) is defined as

$$\text{RRF} = \frac{\text{ultimate resistance of damaged structure}}{\text{ultimate resistance of intact structure}}. \quad (3)$$

110 In addition, because the value of the residual strength corresponds to a par-  
 111 ticular displacement and different values may be achieved if the load is in-  
 112 creased further, the following non-dimensional measure  $R_{twice}$  can be utilized  
 113 when comparing structures with different brace configurations,

$$R_{twice} = \frac{\text{environmental load at twice the ultimate deflection}}{\text{environmental load at ultimate deflection}}. \quad (4)$$

114 As previously pointed out that damage could also arise gradually in time  
115 from aging of structures, a general approach is presented in [18] to formulate  
116 a measure of time-variant structural robustness of concrete structures sub-  
117 jected to diffusive attacks from environmental aggressive agents based on the  
118 ultimate strength analysis. The amount of local damage is firstly obtained at  
119 the member level by means of a dimensionless damage index  $0 \leq \delta \leq 1$  (for  
120 uniform corrosion  $c$  and original material thickness  $d$ ,  $\delta = \frac{c}{d}$ ) associated with  
121 the progressive deterioration of the material properties for steel bars  $\delta_s(x, t)$   
122 and concrete  $\delta_c(x, t)$  at the spatial point  $x$  and time instant  $t$ . Then a global  
123 measure of damage  $\Delta(t)$  at the cross-sectional level is evaluated by means of  
124 a weighted average of the local damage over the volume of the materials, as  
125 follows:

$$\Delta(t) = [1 - \omega(t)]\Delta_c(t) + \omega(t)\Delta_s(t) \quad (5)$$

$$\Delta_c(t) = \frac{\int_{A_c} w_c(x, t)\delta_c(x, t)dx}{\int_{A_c} w_c(x, t)dx} \quad (6)$$

$$\Delta_s(t) = \frac{\sum_m w_{sm}(x, t)\delta_{sm}(x, t)A_{sm}}{\sum_m w_{sm}(x, t)A_{sm}} \quad (7)$$

128 where  $\omega(t)$ ,  $w_c(x, t)$ ,  $w_{sm}(x, t)$  are weight functions (see [18]),  $A_c$  is the area of  
129 the concrete, and the  $A_{sm}$  is the area of the  $m^{\text{th}}$  steel bar. This cross-section  
130 formulation is finally extended at the structural level by an integration over  
131 all members of the system. By comparing the system performance in the  
132 intact state and in a damaged state, the time-variant measure of structural  
133 performance  $\rho(t)$  is derived as,

$$\rho(t) = \frac{\lambda_c(t)}{\lambda_c(0)} \quad (8)$$

134 where the limit load multiplier  $\lambda_c(t)$  corresponds to the ultimate capacity  
 135 in a damaged state, and its initial value  $\lambda_c(0)$  indicates the ultimate capac-  
 136 ity in the intact state. Then, the structural robustness can be evaluated  
 137 based on the relationship between  $\rho(t)$  and the global damage  $\Delta(t)$ . In this  
 138 approach damage can be defined in any way and gradually. The lambda re-  
 139 flects (quantifies) the degree of damage in the load carrying capacity through  
 140 the structural analysis indirectly.

## 141 2.2. Probabilistic robustness measures

142 In order to take account of the unavoidable uncertainties in the environ-  
 143 mental loading and structural resistance, probabilistic robustness measures  
 144 have been developed based on either reliability analysis or risk assessment.

145 Based on system reliability analysis, the probabilistic measure of redun-  
 146 dancy  $R_\beta$  is proposed in [5]

$$R_\beta = \frac{\beta_{\text{intact}}}{\beta_{\text{intact}} - \beta_{\text{damaged}}}, \quad (9)$$

147 where  $\beta_{\text{damaged}}$  is the reliability index of the damaged structural system and  
 148  $\beta_{\text{intact}}$  is the reliability index of the intact system. Similarly, a probabilistic  
 149 measure called “damage factor” of a system was proposed in [7] as

$$R_d = \frac{P_{f,\text{intact}}}{P_{f,\text{damaged}}} \quad (10)$$

150 to assess its capacity to withstand damage without undesirable response.  
 151  $P_{f,\text{damaged}}$  and  $P_{f,\text{intact}}$  are the failure probabilities corresponding to damage  
 152 and no damage in the system, respectively.

153 A framework of robustness assessment based on decision analysis theory  
 154 has been proposed in [19], where the robustness is evaluated by computing



155 both direct risk ( $R_{Dir}$ ), which is associated with the direct consequences  
156 ( $C_{Dir}$ ) of potential damages (D) to the system when an exposure ( $EX_{BD}$ )  
157 occurs, and indirect risk ( $R_{Ind}$ ), which corresponds to indirect consequences  
158 ( $C_{Ind}$ ) associated with subsequent system failure (F). A quantitative measure  
159 of robustness is then defined as,

$$I_{Rob} = \frac{R_{Dir}}{R_{Dir} + R_{Ind}}, \quad \text{with} \quad (11)$$

160

$$R_{Dir} = \int_x \int_y C_{Dir} f_{D|EX_{BD}}(y|x) f_{EX_{BD}}(x) dy dx \quad (12)$$

$$R_{Ind} = \int_x \int_y C_{Ind} P(F|D=y) f_{D|EX_{BD}}(y|x) f_{EX_{BD}}(x) dy dx \quad (13)$$

161 where  $f_Z(z)$  is the probability density function of a random variable  $Z$ .

### 162 2.3. Entropy-based robustness measures

163 For uncertainty specified with the aid of fuzzy sets, as investigated in  
164 this study, an entropy-based robustness measure  $R(\cdot)$  as proposed in [16] is  
165 useful. This is based on an analog to SHANNON's entropy. This analog to  
166 SHANNON's entropy provides features, which make uncertainties calculated  
167 for random variables and fuzzy variables somewhat related to one another.

168 In classical probability theory, SHANNON's entropy is a measure of the  
169 amount of uncertainty and the associated information, see [11]. Information  
170 comprises the elements  $x$  selected from a declared character set representing  
171 the fundamental set  $\mathbf{X}$ . The SHANNON's entropy  $H$  can be expressed by  
172 a probability distribution function  $P(x)$  on a finite set using a functional of  
173 the form

$$H = - \sum_{x \in \mathbf{X}} P(x) \log_2 P(x) . \quad (14)$$

174 And for the case of an infinite set,

$$H = - \int_{-\infty}^{+\infty} f(x) \cdot \log_2 f(x) dx \quad (15)$$

175 applies. In fuzzy set theory, for assessing the fuzziness of the fuzzy set  $\tilde{A}$  on  
 176  $\mathbf{X}$ , the functional values of the membership function  $\mu(x)$  of  $\tilde{A}$  are applied  
 177 as measure values of the elements. An entropy measure of fuzziness  $H(\tilde{A})$   
 178 analog to Shannon's entropy is introduced in [15] as

$$H(\tilde{A}) = -k \cdot \int_{-\infty}^{+\infty} [\mu(x) \cdot \ln(\mu(x)) + (1 - \mu(x)) \cdot \ln(1 - \mu(x))] dx. \quad (16)$$

179 The coefficient  $k$  is introduced when transforming the dyadic logarithm in  
 180 the Shannon's entropy in Eq. (15) into the natural logarithm in Eq. (16).  
 181 That is,  $\log_2(\mu(x)) = k \cdot \ln(\mu(x))$  and  $k = \frac{1}{\ln(2)}$ . Since entropies appear as  
 182 ratios in our approach,  $k$  is cancelled out and does not have any influence.  
 183 The entropy in Eq. (16) has the following properties:

- 184 •  $H(\tilde{A}) = 0$  if  $\mu(x) = 0$  or  $\mu(x) = 1.0$  for all  $x$ ;
- 185 •  $H(\tilde{A})$  reaches maximum if  $\mu(x) = 0.5$  for all  $x$ ;
- 186 • If  $\tilde{A}_i$  is any sharpened version of  $\tilde{A}_j$  (that is, if  $\mu_{A_j}(x) \leq 0.5$ , then  
 187  $\mu_{A_i}(x) \leq \mu_{A_j}(x)$ , and if  $\mu_{A_j}(x) \geq 0.5$ , then  $\mu_{A_i}(x) \geq \mu_{A_j}(x)$ ), then  
 188  $H(\tilde{A}_i) \leq H(\tilde{A}_j)$ ;
- 189 • The symmetry property holds, i.e.  $H(\tilde{A}) = H(\tilde{A}^c)$  where  $\tilde{A}^c$  is the  
 190 complement of  $\tilde{A}$  and defined as  $\tilde{A}^c = \{(x, \mu_{A^c}(x)) | x \in \mathbf{X}; \mu_{A^c}(\mathbf{x}) =$   
 191  $\mathbf{1} - \mu_{\mathbf{A}}(\mathbf{x})\}$ .

192 For example,  $H(\tilde{z}_j)$  of the fuzzy sets  $\tilde{z}_j$  shown in Fig. 3(b) are  $H(\tilde{z}_1) =$   
193  $0.72$ ,  $H(\tilde{z}_2) = 0.60$ ,  $H(\tilde{z}_3) = 0.60$ ,  $H(\tilde{z}_4) = 0.30$  and  $H(\tilde{z}_5) = 0.30$ . These  
194 examples represent common shapes of membership functions in practical ap-  
195 plications. Generally, this entropy measure evaluates the “steepness” of the  
196 membership function  $\mu(x)$ , which indicates  $H = 0$  for a crisp set and  $H$  is  
197 maximum if  $\mu(x) = 0.5$ . In information theory the elements with  $\mu_A(x) = 0.5$   
198 represent the most interesting range of a fuzzy set  $\tilde{A}$  because  $\mu(x) = 0.5$  char-  
199 acterizes the highest uncertainty in the decision to consider the associated  
200 element  $x$  either as belonging to  $\tilde{A}$  or as not belonging to  $\tilde{A}$ .

201 The derivation of Eq. (16) from a probabilistic basis in information the-  
202 ory ensures reasonable compliance with probabilistic uncertainty measures.  
203 Let  $X$  be a random variable with normal distribution, and its uncertainty  
204 be measured in terms of the standard deviation  $\sigma_X$ . If the cumulative distri-  
205 bution function (CDF)  $F_X(x)$  is substituted in Eq. (16) for the membership  
206 function  $\mu(x)$ , then a change of the standard deviation  $\sigma_X$  is associated with  
207 a proportional change of the entropy  $H$ . For example, let  $X_i \sim (\mu_X, \sigma_{X_i}^2)$   
208 and  $X_j \sim (\mu_X, \sigma_{X_j}^2)$  be two normal random variables with  $\sigma_{X_j} = 2\sigma_{X_i}$ . If  
209  $\tilde{A}_i$  and  $\tilde{A}_j$  are two fuzzy sets with their membership functions having values  
210 as the CDF of  $X_i$  and  $X_j$ , i.e.,  $\mu_{A_i}(x) = F_{X_i}(x)$  and  $\mu_{A_j}(x) = F_{X_j}(x)$ , then  
211  $H(\tilde{A}_j) = 2H(\tilde{A}_i)$ .

212 According to [16], the robustness of a structural system  $R(\cdot)$  can be de-  
213 fined as the ratio between the entropy of input parameters  $\tilde{x}$  and the entropy  
214 of associated structural responses  $\tilde{z}$  when the uncertainty of structural pa-  
215 rameters is quantified as fuzziness,

$$R(\tilde{x}, \tilde{z}) = \frac{H(\tilde{x})}{H(\tilde{z})}. \quad (17)$$

216 And the following properties hold,

- 217 •  $R(\cdot) \geq 0 \forall H(\tilde{x}), H(\tilde{z}) > 0$ ;
- 218 •  $H(\tilde{z}_2) \leq H(\tilde{z}_1) \Rightarrow R_2(\cdot) \geq R_1(\cdot) \mid H(\tilde{x}_1) = H(\tilde{x}_2)$ ;
- 219 •  $H(\tilde{x}) \rightarrow 0 \Rightarrow R(\cdot) \rightarrow 0 \mid H(\tilde{z}) > 0$ ;
- 220 •  $H(\tilde{z}) \rightarrow 0 \Rightarrow R(\cdot) \rightarrow \infty \mid H(\tilde{x}) > 0$ .

221 This robustness measure results in a global statement about the degree of  
222 variations in system output with respect to fluctuations in system input at  
223 once. The second property indicates that the smaller the uncertainty of the  
224 fuzzy outputs is obtained in relation to the uncertainty of the fuzzy inputs,  
225 the bigger the robustness of the structures is assessed. In practice, this  
226 means that moderate changes applied to structural parameters, for example  
227 as changes of design parameters or through quite common deviations from  
228 plans and moderate errors, affect the structural response (i.e. the structural  
229 performance) only marginally. Further, in the case that result uncertainty  
230 occurs even for crisp input, which represents instabilities, the robustness is  
231 zero. Robustness is not defined for the case that both the input uncertainty  
232 and the result uncertainty are zero. For further detailed explanations we  
233 refer to [16].

### 234 **3. Nuanced Robustness Analysis**

235 While deterministic performance measures and probabilistic robustness  
236 measures assess a structure under given conditions and uncertainties, the

237 entropy-based robustness measure considered in Section 2.3 provides a po-  
 238 tential to develop a nuanced robustness assessment in form of a robustness  
 239 function depending on the magnitude of uncertainty in the structural con-  
 240 ditions. Hence, a trade-off assessment for inspection effort versus gain in  
 241 confidence for performance, safety and robustness predictions can be devel-  
 242 oped. We develop this nuanced robustness assessment based on the general  
 243 idea of an entropy-based robustness measure.

### 244 3.1. Practical considerations

#### 245 3.1.1. Applicability of entropy measure

246 One (first) problem that has been addressed by Section 2.3 is associated  
 247 with the applicability of the entropy measure when considering the difference  
 248 between an interval variable and a singleton. Mathematically, they have the  
 249 same entropy values (i.e.,  $H = 0$ ), but it is counterintuitive as the interval  
 250 possesses clearly a larger imprecision.

251 A similar (second) problem arises, as shown in Fig. 1, when the fuzzy  
 252 output  $\tilde{z}_1$  associated with the fuzzy input  $\tilde{x}$  for system (1) and the fuzzy  
 253 output  $\tilde{z}_2$  associated with the same fuzzy input  $\tilde{x}$  for system (2), have similar  
 254 entropy values but quite different width of the system output at various  
 255 membership levels with respect to same degrees of imprecision in the fuzzy  
 256 input, i.e.  $w(z_{1,\alpha_k}) > w(z_{2,\alpha_k})$ . For example, mapping of the same fuzzy  
 257 input  $\tilde{x}$  in Fig. 3(a) through two systems (functions  $f_2(x)$  and  $f_3(x)$ ) gives  
 258 two fuzzy outputs  $\tilde{z}_2$  and  $\tilde{z}_3$  in Fig. 3(b), with  $H(\tilde{z}_2) = H(\tilde{z}_3) = 0.60$  but  
 259  $w(z_{3,\alpha_k=0.5}) = 0.94 > 0.29 = w(z_{2,\alpha_k=0.5})$ .

260 A third problem of the entropy measure, and hence of the robustness  
 261 measure, concerns its dependence on scale and transformations. Since it is

262 not invariant in this sense, an interpretation on the ratio scale is critical.

### 263 *3.1.2. Suggested assumptions and extensions*

264 The first problem is circumvented in this study; we assume that typical  
265 shapes of membership functions, such as triangular or quadratic, are adopted  
266 for the fuzzy inputs (as usually used in practical cases) and that the asso-  
267 ciated fuzzy outputs are obtained as fuzzy sets as well and not as precise  
268 numbers. A polygonal approximation of the shape of the fuzzy outputs us-  
269 ing only a few membership levels is sufficient in most cases. If the analysis  
270 indicates strong nonlinearities in the membership functions, a more detailed  
271 alpha-discretization may be useful. Associated with this assumption, an-  
272 other restriction is made; the fuzzy variables  $\tilde{x}$  considered herein possess one  
273 element  $x \in \tilde{x}$  with  $\mu(x) = 1$ .

274 Next, the second problem raised above is considered. Robustness assess-  
275 ment based on the robustness measure in Eq. (17) leads to the same results  
276 for system (1) and system (2),  $H(\tilde{z}_1) \approx H(\tilde{z}_2)$ , i.e. to the conclusion that  
277 system (1) is as robust as system (2). However, this conclusion is only lim-  
278 ited to a global view at the robustness of the two systems without reflection  
279 of the degree of independence between the imprecision of fuzzy inputs and  
280 the associated imprecision of fuzzy outputs at different membership levels.  
281 To implement this relationship between the  $\alpha$ -level sets, the assessment from  
282 [16] is modified by utilizing alpha-level discretization as proposed in Section  
283 3.2. This enables a consideration of a trade-off between additional informa-  
284 tion and an associated reduction of imprecision in the predicted structural  
285 response or reliability. Additional information and reduction of input impre-  
286 cision can be understood as limitation of the analysis to the set of values

287  $\{x \in \mathbf{X} | \mu(x) \geq \alpha_k\}$  for the fuzzy input  $\tilde{x}$  and the associated set of values  
288  $\{z | \mu_j(z) \geq \alpha_k\}$  for the fuzzy output  $\tilde{z}_j$  in the assessment of robustness. Sub-  
289 sequently, the two systems may not exhibit similar robustness corresponding  
290 to the reduced imprecision in the fuzzy inputs.

291 The third problem concerning lack of invariance is circumvented by us-  
292 ing this robustness measure on an ordinal scale rather than on a ratio scale.  
293 Although the meaning of the ratio value obtained for the robustness of an  
294 individual structure is not meaningful, it provides a useful basis for the com-  
295 parison with a second structure, evaluated for the same problem with the  
296 same input and looking the same responses, in terms of robustness. Relat-  
297 ing the robustness measures of two structures to one another in this manner  
298 translates the assessment to an ordinal scale, which is sufficient to decide  
299 which structure is more robust than the other one - without assessing nu-  
300 merically how big the difference in robustness is. Still, this difference in  
301 robustness between the structures related to the absolute robustness of one  
302 of the structures provides at least a rough sense about the magnitude of this  
303 difference. One can then see whether this difference is significant or not.  
304 Although this is a reasonable basis for deriving decisions in many practical  
305 cases, further research is needed to address this issue more rigorously.

### 306 *3.2. Proposed approach*

#### 307 *3.2.1. General description*

308 The inconsistency explained in Section 3.1, see Fig. 1, can be resolved  
309 by computing the entropy-based robustness  $R(\alpha_k)$  at various membership  
310 levels with respect to the degrees of imprecision in the fuzzy inputs and the  
311 associated imprecision of the fuzzy outputs.

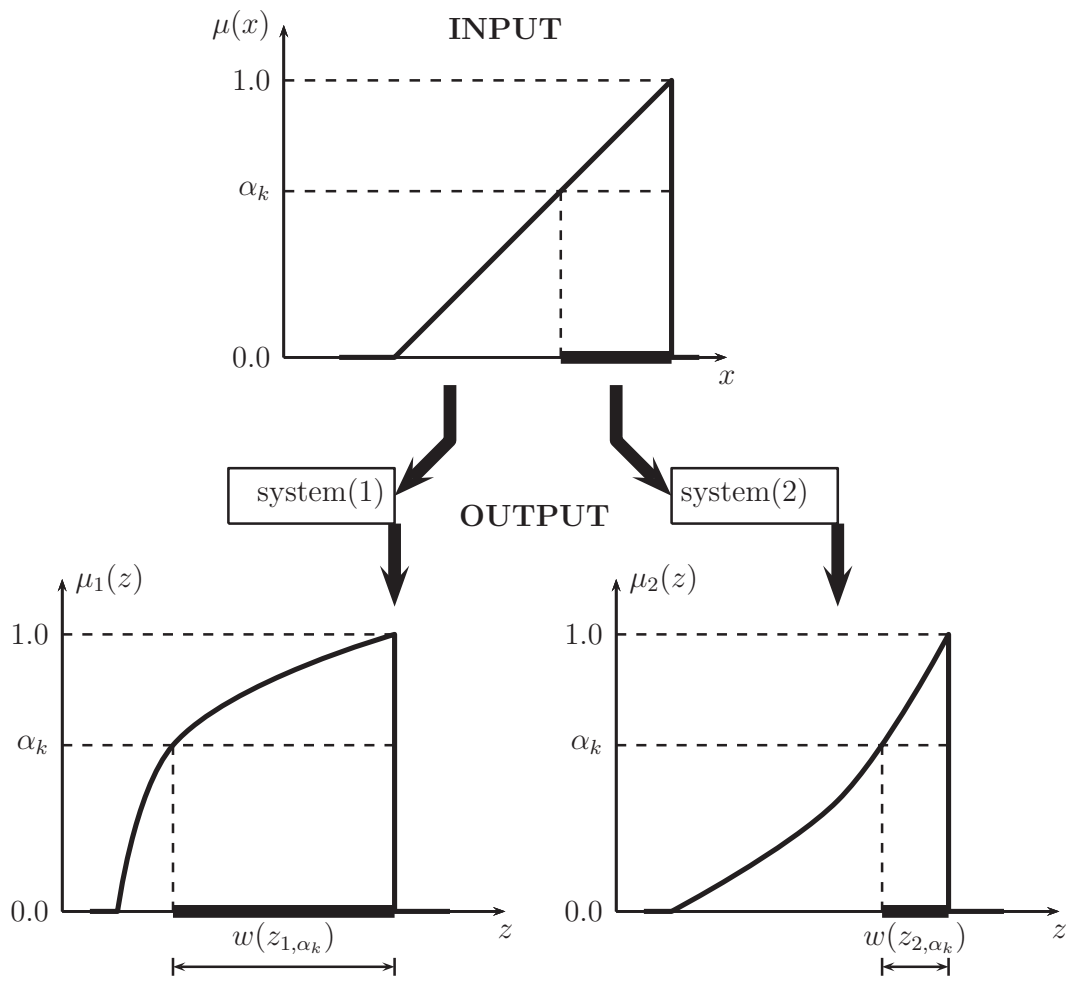


Figure 1: Illustration of problems with the existing robustness measure  $R$



312 Given a fuzzy set  $\tilde{A}$ , at each alpha level  $\alpha_k \in (0, 1]$ , the crisp set  $A_{\alpha_k}$

$$A_{\alpha_k} = \{x \in \mathbf{X} | \mu_A(x) \geq \alpha_k\} \quad (18)$$

313 is called  $\alpha$ -level set. Given another fuzzy set  $\tilde{B}$ , the *intersection*  $\tilde{D}$  of the  
314 fuzzy sets  $\tilde{A}$  and  $\tilde{B}$  on  $\mathbf{X}$  is obtained from

$$\tilde{D} = \tilde{A} \cap \tilde{B} = \{(x, \mu_D(x)) | x \in \mathbf{X}; \mu_D(x) = \min[\mu_A(x), \mu_B(x)]\}. \quad (19)$$

315 Since the fuzzy set theory, which permits the gradual assessment of the mem-  
316 bership of elements in relation to a set, is a generalization of the classical set  
317 theory, the  $\alpha$ -level set  $A_{\alpha_k}$  can be viewed as a special fuzzy set. Thus, a new  
318 fuzzy set can be defined as the intersection of fuzzy set  $\tilde{A}$  and its  $\alpha$ -level set  
319  $A_{\alpha_k}$ , denoted as  $\tilde{A}_{\alpha_k}$ ,

$$\tilde{A}_{\alpha_k} = \tilde{A} \cap A_{\alpha_k}, \quad (20)$$

320 as illustrated in Fig. 2. This concept is then applied to the fuzzy input  $\tilde{x}$   
321 and fuzzy output  $\tilde{z}$  of the structural problem. The entropy-based robustness  
322  $R(\cdot)$  in Eq. (17) is calculated for each  $\tilde{A}_{\alpha_k}$  as the ratio between the entropy  
323 of  $\tilde{x}_{\alpha_k} = \tilde{x} \cap x_{\alpha_k}$  of the fuzzy input  $\tilde{x}$  and the entropy of  $\tilde{z}_{\alpha_k} = \tilde{z} \cap z_{\alpha_k}$  of the  
324 fuzzy output  $\tilde{z}$ ,

$$R(\alpha_k) = \frac{H(\tilde{x}_{\alpha_k})}{H(\tilde{z}_{\alpha_k})}. \quad (21)$$

325 The robustness  $R(\cdot)$  in [16] is obtained as a special case of Eq. (21) for  
326  $\alpha_k = 0 + \varepsilon$  when  $\varepsilon \rightarrow 0$ . The robustness  $R(\alpha_k)$  is not defined at  $\alpha_k = 1$   
327 because  $H(\tilde{x}_{\alpha_k=1})$  and  $H(\tilde{z}_{\alpha_k=1})$  are normally both equal to zero.

### 328 3.2.2. Illustrative example

329 The features of the modified robustness measure in Eq. (21) are demon-  
330 strated in the following illustrative example by means of analytical functions

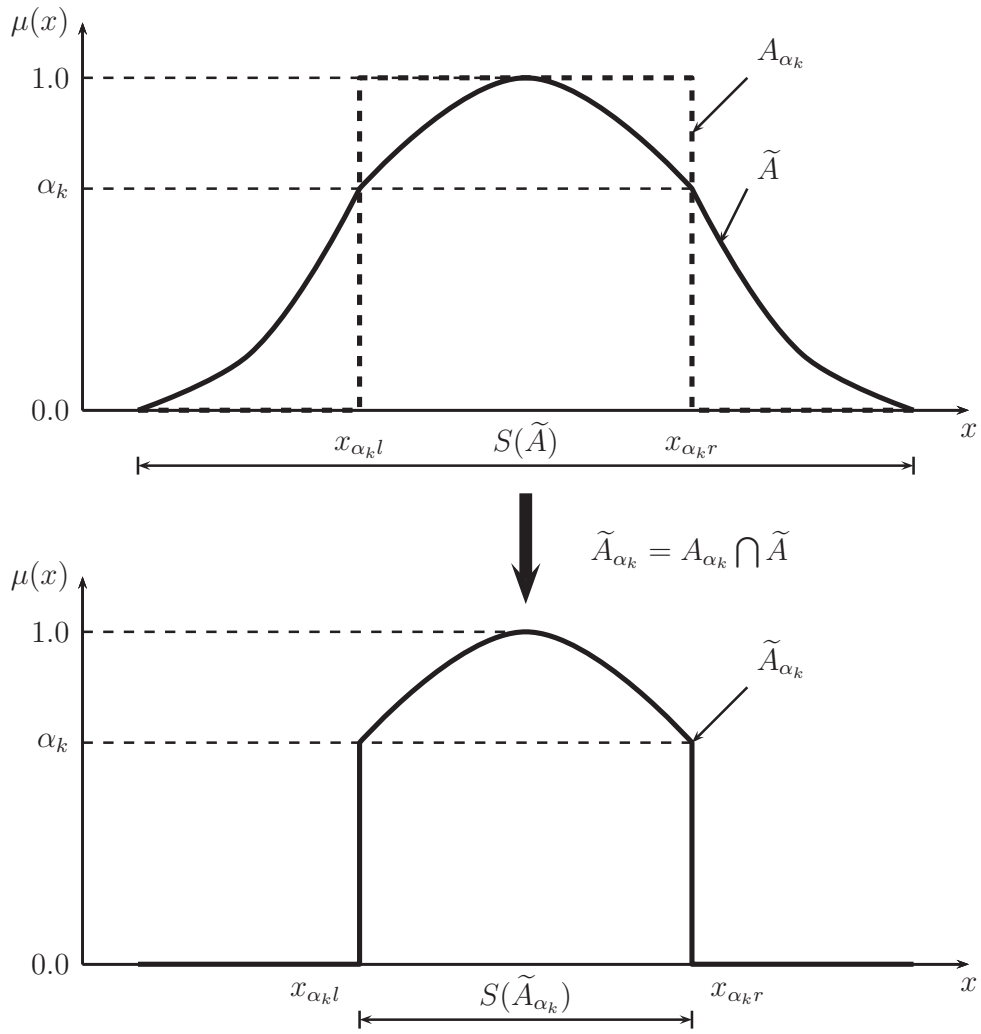


Figure 2: Intersection of the fuzzy set  $\tilde{A}$  with the  $\alpha$ -level set  $A_{\alpha_k}$

331 specifically selected for this purpose. Consider the mapping of fuzzy input  
 332  $\tilde{x}$  in Fig. 3(a) into the fundamental set  $\mathbf{Z}$  with the aid of the following five  
 333 mapping models  $f_j(x)$ :

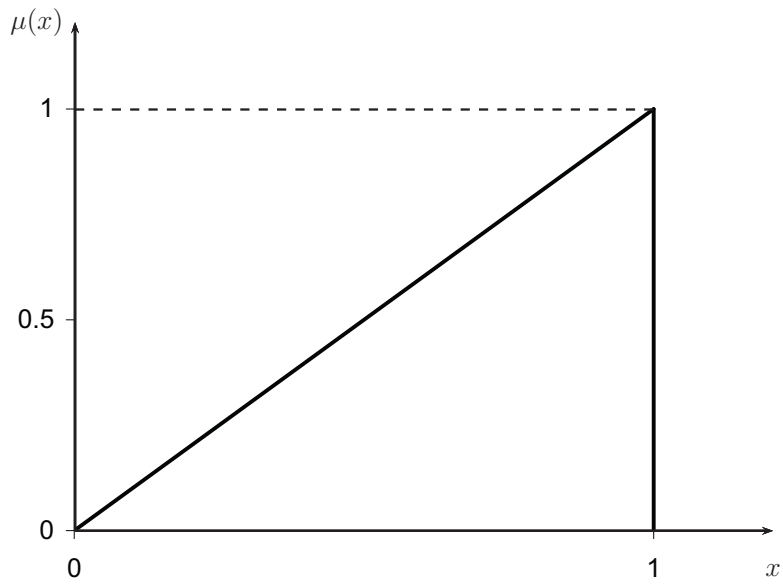
$$\begin{aligned} f_1(x) &= x , \\ f_2(x) &= x^{0.5} , \\ f_3(x) &= x^4 , \\ f_4(x) &= 0.5x^4 + 0.5 , \\ f_5(x) &= 0.5x^{0.5} + 0.5 . \end{aligned}$$

334 The membership functions for the fuzzy outputs  $\tilde{z}_j$  can be obtained ana-  
 335 lytically,

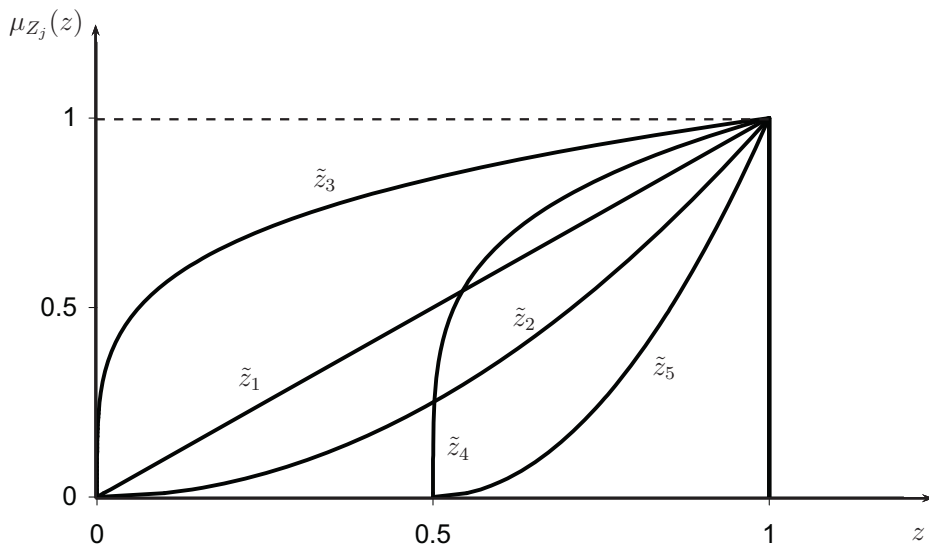
$$\begin{aligned} \mu_1(z) &= z, \quad z \in [0, 1] \\ \mu_2(z) &= z^2, \quad z \in [0, 1] \\ \mu_3(z) &= z^{0.25}, \quad z \in [0, 1] \\ \mu_4(z) &= (2z - 1)^{0.25}, \quad z \in [0.5, 1] \\ \mu_5(z) &= (2z - 1)^2, \quad z \in [0.5, 1] \end{aligned}$$

336 where  $\mu_j(z) = 0$  for other values. The results are shown in Fig. 3(b).

337 The functions  $f_i(x)$  have been chosen to illustrate the effects discussed  
 338 below, which possess particular practical relevance and address the problem  
 339 in Fig. 1. Specifically,  $f_2(x)$  and  $f_3(x)$  are selected to show that the associ-  
 340 ated fuzzy outputs  $\tilde{z}_2$  and  $\tilde{z}_3$  have similar entropy values but different shapes.  
 341 The same applies to the selection of  $f_4(x)$  and  $f_5(x)$ , but with a smaller un-  
 342 certainty in the associated results  $\tilde{z}_4$  and  $\tilde{z}_5$  to work out discussion on this  
 343 effect, as well. One could use further functions, as well, for this study.



(a) Fuzzy input  $\tilde{x}$



(b) Fuzzy outputs  $\tilde{z}_j$

Figure 3: Mapping  $\tilde{x} \rightarrow \tilde{z}_j$  : 3a fuzzy input  $\tilde{x}$  and 3b fuzzy outputs  $\tilde{z}_j$  associated with the mapping model  $z_j = f_j(x)$

344 The entropy values associated with  $\alpha_k$  of  $\tilde{x}$  and  $\tilde{z}_j$ , normalized by  $H(\tilde{x})$ ,  
 345 are shown in Fig. 4. It clearly indicates a reduction of imprecision in the  
 346 fuzzy input  $\tilde{x}$  as  $\alpha_k$  increases (i.e., collection of additional information) and  
 347 the corresponding reduction of imprecision in the fuzzy outputs  $\tilde{z}_j$ . In an en-  
 348 gineering context, it means that collection of additional information to reduce  
 349 input imprecision has a trade-off in a reduction in imprecision of computa-  
 350 tional results, i.e., in predictions regarding structural behavior and reliability.  
 351 However, for different mapping models, the reduction of imprecision in the  
 352 outputs exhibits very different characteristics. For example, the imprecision  
 353 in  $\tilde{z}_{2,\alpha_k}$  and  $\tilde{z}_{5,\alpha_k}$  decreases much faster than the imprecision in  $\tilde{z}_{3,\alpha_k}$  and  $\tilde{z}_{4,\alpha_k}$   
 354 for smaller values of  $\alpha_k$ . It indicates that just a small reduction of imprecision  
 355 in  $\tilde{x}$  (i.e., low effort spent on collecting additional information) can result in a  
 356 significant reduction in imprecision of  $\tilde{z}_2$  and  $\tilde{z}_5$ . Thus, the mapping models  
 357  $f_2$  and  $f_5$  have more desirable properties than  $f_3$  and  $f_4$ . They represent  
 358 economical engineering design in the sense that only little effort in collecting  
 359 input information has a significant trade-off in a substantial quality improve-  
 360 ment of predictions regarding structural performance and reliability. This  
 361 feature is reflected in the robustness measure in Eq. (21), which provides a  
 362 quantitative assessment of the properties of the systems.

363 The entropy-based robustness  $R(\alpha_k)$  is shown in Fig. 5 as a function of  
 364  $\alpha_k$ . Several interesting conclusions can be drawn from the results:

- 365 •  $R(\tilde{x}, \tilde{z}_2) = 1.22 \approx R(\tilde{x}, \tilde{z}_3) = 1.20 > R(\tilde{x}, \tilde{z}_1) = 1.00$  at  $\alpha_k = 0 + \varepsilon$   
 366 when  $\varepsilon \rightarrow 0$ . This observation produces the robustness assessment in  
 367 [16] as a special case. That is, if only the values of  $R(\cdot)$  with respect  
 368 to  $\alpha_k = 0 + \varepsilon$  when  $\varepsilon \rightarrow 0$  are considered to make a decision, it would

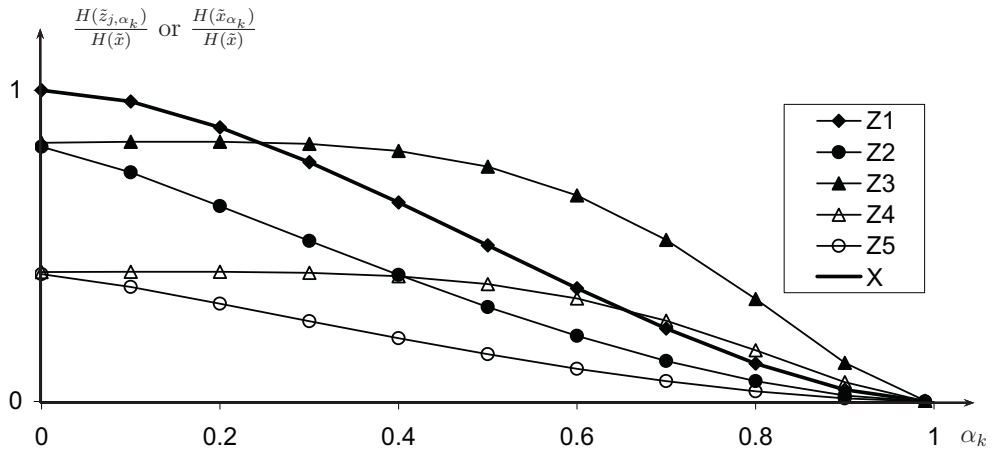


Figure 4: A reduction of imprecision in the fuzzy input  $\tilde{x}$  as  $\alpha_k$  increases and the corresponding reduction of imprecision in the fuzzy outputs  $\tilde{z}_j$  (note: the curve for  $\tilde{x}$  overlaps with that for  $\tilde{z}_1$ )

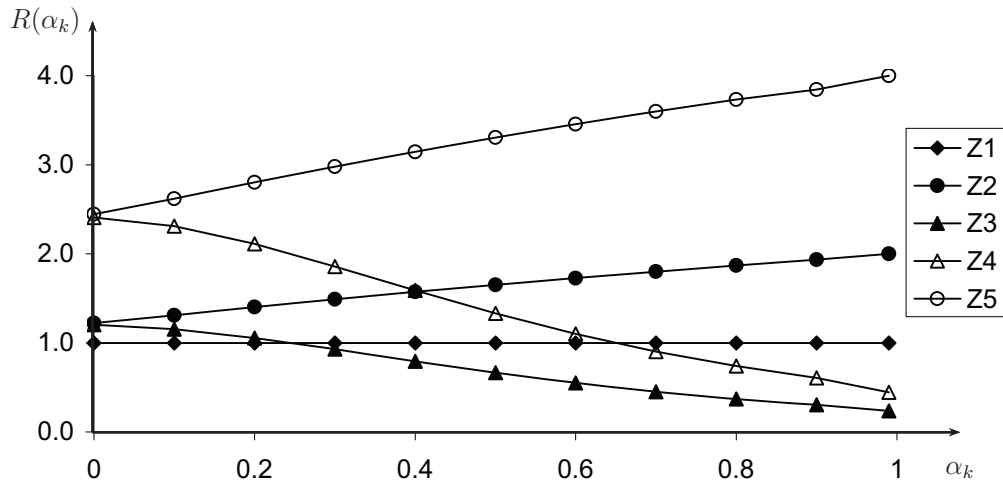


Figure 5: Robustness  $R(\tilde{x}, \tilde{z}_j)$  associated with each mapping model  $f_j(x)$  with alpha-level ( $\alpha_k$ ) discretization

369 be concluded that the mapping models  $f_2(x)$  and  $f_3(x)$  have a similar  
 370 robustness and are both more robust than mapping model  $f_1(x)$ .

371 • Fig. 5 shows significant differences of the values  $R(\cdot)$  corresponding  
 372 to different values of  $\alpha_k$ . As  $\alpha_k$  is increased,  $R(\tilde{x}, \tilde{z}_3)$  keeps decreasing  
 373 while  $R(\tilde{x}, \tilde{z}_2)$  keeps increasing. This indicates that the mapping  
 374 models will exhibit different properties with respect to robustness when  
 375 considering an increase of membership values  $\alpha_k > 0$ , i.e., a reduction  
 376 of imprecision in the fuzzy input. The imprecision in the uncertain  
 377 inputs can be reduced when more information is made available. This  
 378 facilitates a trade-off analysis between collection of additional informa-  
 379 tion and decision for a specific design variant. For example, at  $\alpha_k = 0.4$ ,  
 380  $R(\tilde{x}, \tilde{z}_2) = 1.57 > R(\tilde{x}, \tilde{z}_1) = 1.00 > R(\tilde{x}, \tilde{z}_3) = 0.79$ . Thus, it would  
 381 be concluded that mapping model  $f_2(x)$  is the most robust system  
 382 when input imprecision can be reduced to a degree corresponding to  
 383 membership level 0.4. Furthermore, when considering all the values of  
 384  $\alpha_k \in (0, 1]$ , the mapping model  $f_2(x)$  is more robust in overall than  
 385  $f_3(x)$  although they have similar robustness values at  $\alpha_k = 0 + \varepsilon$ . The  
 386 same situation appears when comparing the mapping models  $f_4(x)$  and  
 387  $f_5(x)$ . Obviously, the mapping model  $f_5(x)$  is a better choice.

388 • The mapping model  $f_4(x)$  is more robust than  $f_2(x)$  when  $\alpha_k \leq 0.4$ ,  
 389 especially,  $R(\tilde{x}, \tilde{z}_4) = 2.41 \approx 2R(\tilde{x}, \tilde{z}_2) = 2.44$  at  $\alpha_k = 0 + \varepsilon$ . How-  
 390 ever, the values of  $R(\cdot)$  associated with  $\alpha_k \geq 0.4$  lead to the opposite  
 391 conclusion that the mapping model  $f_2(x)$  is more robust than  $f_4(x)$ .  
 392 Again, the trade-off between collection of additional information and

393 decision for a variant or improvement of the robustness assessment can  
394 be considered. If the collection of additional information is easy to  
395 facilitate,  $f_2(x)$  would be the preferred model; otherwise  $f_4(x)$ . And  
396 the other may round, if  $f_2(x)$  is selected, collection of additional infor-  
397 mation would be very useful and paid off; whilst for  $f_4(x)$  collection of  
398 additional information does not lead to a benefit.

399 Hence, it is of vital importance to compute the structural robustness  
400 at various membership levels  $\alpha_k$ . Robustness is not only a property  
401 of the structure, it is also dependent on the magnitude of impreci-  
402 sion/uncertainty in the input. It is a relative measure. Reduction of  
403 input imprecision can so lead to both increase and decrease in robust-  
404 ness depending on whether sensitivities are associated with the value  
405 ranges cut away in the reduction of imprecision or not. This consid-  
406 eration can substantially support design decisions in the context of  
407 availability of information and inspection cost.

408 It is noted that the membership functions of the result can be found in  
409 a closed form in the case of the simple illustrative example. In a practical  
410 structural analysis it is normally not possible to determine result membership  
411 functions in a closed form. However, they can be found in general via a  
412 numerical fuzzy analysis. A variety of intrusive and non-intrusive numerical  
413 approaches are available to perform this analysis, see [20, 21, 22, 23, 24].



## 414 4. Application to Offshore Structures

### 415 4.1. Structural models

416 Based on the environmental conditions and the information about the  
417 reference jackets provided in [3], two 2D frames are designed using software  
418 USFOS with some simplifications as well as some changes to the dimensions  
419 of members. USFOS (an acronym for Ultimate Strength for Frame Offshore  
420 Structure) is a numerical tool for nonlinear pushover analysis which helps to  
421 compute the reserve strength and residual strength of the frame structures  
422 before and after damage. The topologies for the X-bracing and K-bracing  
423 jacket structures are shown in Fig. 6. All structures are two-bay frames  
424 in water depth of  $37m$ . The environmental design loads are applied at the  
425 top two elevations of the frames with the values of 1334.5 kN and 667.2 kN,  
426 respectively. The diameter  $D$  and thickness  $t$  of all tubular members are  
427 listed in Table 1.

428 An assumption of fixed boundary conditions is made and all the tubular  
429 joints are assumed to be rigid. The structures are modelled with beam ele-  
430 ments and material non-linearities are modelled by plastic hinges at element  
431 mid-span and element ends. Element formulation of this program also allows  
432 the considerations of large displacement effects and the coupling of lateral  
433 deflection and axial strain. This supports a realistic representation of the  
434 element behavior including column buckling. Nonlinear ultimate strength  
435 analysis can be carried out to determine the reserve and residual strength  
436 representing the degree of redundancy of the jacket structure. In the analy-  
437 sis, the load is applied incrementally until the ultimate resistance is reached  
438 and the load increment is automatically reversed when global instability is

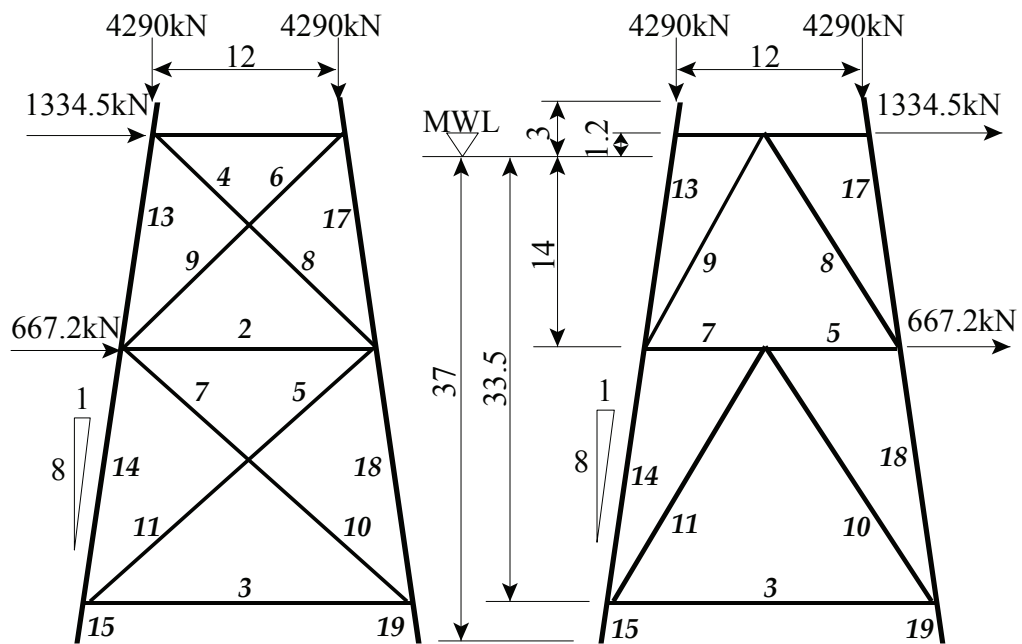


Figure 6: Structural models of the fixed offshore platforms (unit of length: m)

Table 1: Member sizes of the X-frame and K-frame

member	X-	frame	K-	frame
no.	$D(m)$	$t(m)$	$D(m)$	$t(m)$
2	0.32385	0.00953	-	-
3	0.3556	0.00953	0.508	0.0127
4	0.4572	0.0127	-	-
5	0.4572	0.0127	0.559	0.0127
6	0.4572	0.0127	-	-
7	0.4572	0.0127	0.559	0.0127
8	0.4572	0.0127	0.508	0.01588
9	0.4572	0.0127	0.508	0.01588
10	0.4572	0.0127	0.559	0.01715
11	0.4572	0.0127	0.559	0.01715
13	1.1684	0.0254	1.1684	0.0254
14	1.1684	0.03175	1.1684	0.03175
15	1.1684	0.03175	1.1684	0.03175
17	1.1684	0.0254	1.1684	0.0254
18	1.1684	0.03175	1.1684	0.03175
19	1.1684	0.03175	1.1684	0.03175

439 detected. The size of the increments may be varied along the deformation  
440 path, i.e. large steps in the linear range, and smaller steps with increasingly  
441 nonlinear behavior.

#### 442 *4.2. Damage modeling under imprecise marine corrosion*

443 In this practical example, the fixed offshore platforms are assumed to be  
444 subjected to gradual deterioration caused by uniform corrosion. In order to  
445 investigate the corrosion effects with a longer period, the immersion corrosion  
446 data collected until 1994 provided in [17] are taken to specify the corrosion  
447 depth. With this approach we follow the general practise to consider only  
448 uniform corrosion when analyzing structural strength or structural capacity,  
449 see [25]. However, the proposed nuanced robustness analysis is not limited to  
450 this corrosion model. It can also be applied in association with non-uniform  
451 corrosion models. One may consider that corrosion tends to concentrate in  
452 the heat affected zone of the welds, and that stress-concentrations exists at  
453 the same spots. Hence, the damage maybe defined as an accumulation of  
454 those local damages in the connections.

455 Herein, we focus on uniform corrosion and define a fuzzy corrosion depth  
456  $\tilde{c}(t)$  associated with the exposure time  $t$  coarsely derived from the data in  
457 conjunction with a subjective assessment of deterioration, as shown in Fig. 7.  
458 The membership values  $\mu(c)$  express the degree of subjective plausibility that  
459 particular values of  $c(t)$  actually occur. That is, the membership values reflect  
460 a subjective assessment and the specification of the values are characterized  
461 by highly subjective factors. In this example,  $\tilde{c}(t = 16)$  is considered and  
462 subjectively constructed according to the data points plotted in Fig. 7. A  
463 rational approach is to weigh the mean value 0.68 mm with a membership

464 of  $\mu(0.68) = 1.0$ . The 5% and 95% bounds  $[0.32, 1.40]$  mm at  $t = 16$  provide  
 465 a reasonable interval for the support of the fuzzy set  $\tilde{c}(t = 16)$ . However,  
 466 it is observed that there are some outliers at  $t = 15$ , which are considered  
 467 to be possible values but with lower degree of possibility, i.e.,  $\mu(c) \leq 0.1$  for  
 468  $c \geq 1.40$  mm. Since the membership function is only a subjective assessment,  
 469 complicated descriptions are often not necessary for practical purpose. It is  
 470 appropriate to choose linear functional formulations for  $\mu(c)$ , as shown in  
 471 Fig. 8.

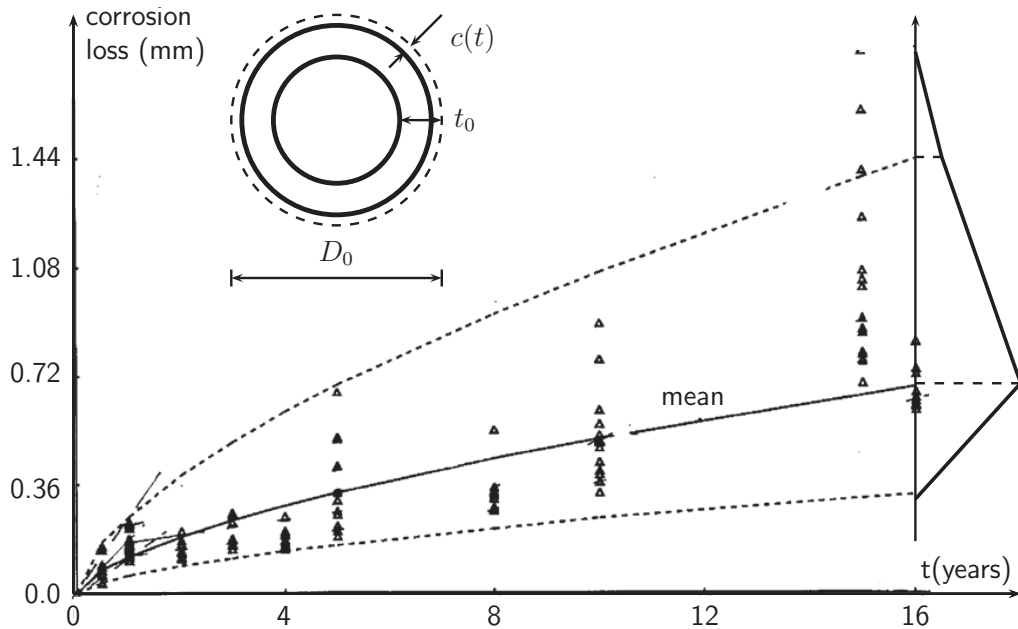


Figure 7: Immersion corrosion data for mild-steel coupons pooled from all available sources until 1994 subjected to an approximate temperature correction in [17] with 5 and 95 percentile bands

472 The concept of structural damage modeling from [4] is utilized herein to  
 473 specify the amount of damage at the member level for a circular cross-section.

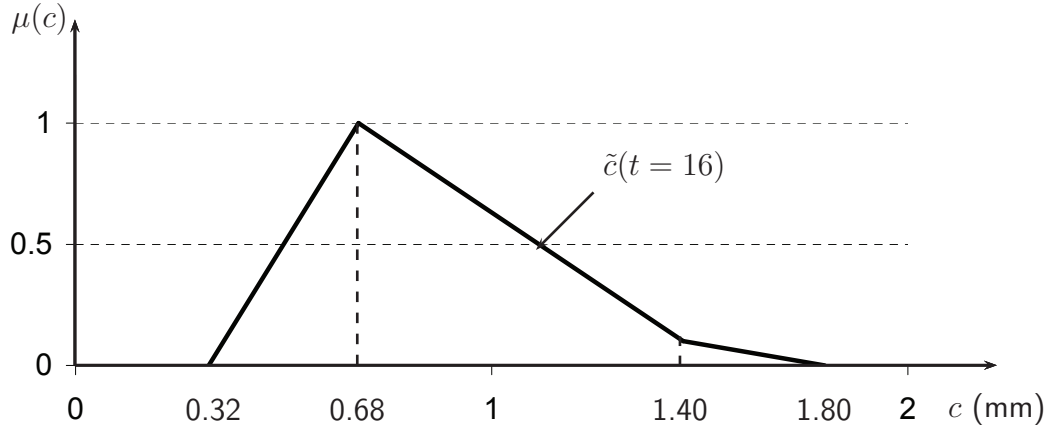


Figure 8: Fuzzy corrosion depth  $\tilde{c}$  at  $t = 16$  years according to the immersion corrosion data in Fig. 7

474 For the hollow steel tubes which are typically used in building offshore plat-  
 475 forms, the damage at cross-sectional level can be represented by a ratio of  
 476 the corroded area  $A_c$  and the original area  $A_0$ ,

$$\beta = \frac{A_c}{A_0} = \frac{D_0}{(D_0 - t_0)t_0}c - \frac{1}{(D_0 - t_0)t_0}c^2 \quad (22)$$

477 where  $D_0$  and  $t_0$  are the diameter and wall-thickness, respectively, before  
 478 deterioration. Finally, the formulation at the cross-sectional level is extended  
 479 to obtain the total damage at the structural level by integration over all  
 480 structural members, which is calculated as  $\beta_{\text{total}}$ ,

$$\beta_{\text{total}} = \frac{\sum \beta_i A_i L_i}{\sum A_i L_i} = \sum \omega_i \beta_i \quad (23)$$

481 where  $\omega_i = A_i L_i / \sum A_i L_i$ , and  $A_i$  is the cross-sectional area of a structural  
 482 member with length  $L_i$  before deterioration.

483 As the corrosion depth is modeled as fuzzy variable  $\tilde{c}(t = 16)$  as shown in  
 484 Fig. 8, the total damage due to the marine corrosion is also a fuzzy variable

485 and represented by  $\tilde{\beta}_{\text{total}} = \sum \omega_i \tilde{\beta}_i$ . Based on Eq. (22),  $\tilde{\beta}_i$  can be calculated.  
 486 It can be observed from the plot of  $\beta = \beta(c)$  in Fig. 9 that there exists  
 487 monotonic relationship between  $\beta$  and  $c$  when  $0 \leq c \leq t_0$ . Hence, the fuzzy  
 488 result  $\tilde{\beta}$  can be easily obtained by computing the alpha-level sets  $[\beta_{\alpha_k l}, \beta_{\alpha_k r}]$   
 489 for  $\alpha_k \in (0, 1]$ , that is,

$$\beta_{\alpha_k l} = \frac{D_0}{(D_0 - t_0)t_0} c_{\alpha_k l} - \frac{1}{(D_0 - t_0)t_0} (c_{\alpha_k l})^2 \quad (24)$$

$$\beta_{\alpha_k r} = \frac{D_0}{(D_0 - t_0)t_0} c_{\alpha_k r} - \frac{1}{(D_0 - t_0)t_0} (c_{\alpha_k r})^2 \quad (25)$$

490 where  $[c_{\alpha_k l}, c_{\alpha_k r}]$  is the alpha-level set at  $\alpha_k \in (0, 1]$  of the fuzzy corrosion  
 491 depth  $\tilde{c}$ . Based on Eq. (24) and Eq. (25), together with the linear function  
 492  $\tilde{\beta}_{\text{total}} = \sum \omega_i \tilde{\beta}_i$ , the total damage represented by  $\tilde{\beta}_{\text{total}}$  can be obtained for  
 the K-braced and X-braced frames, as shown in Fig. 10.

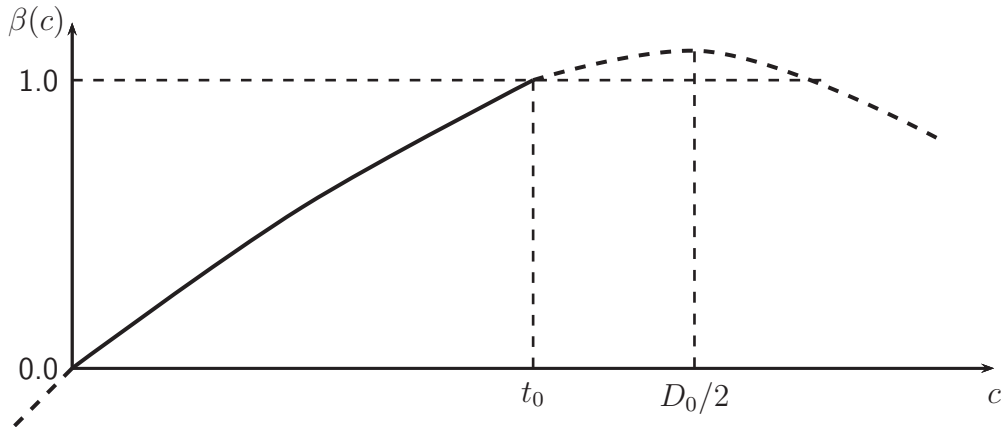


Figure 9: Plot of the damage represented by  $\beta(c)$  for a hollow cross-section with diameter  $D_0$  and thickness  $t_0$ . Note:  $0 \leq c \leq t_0$

493

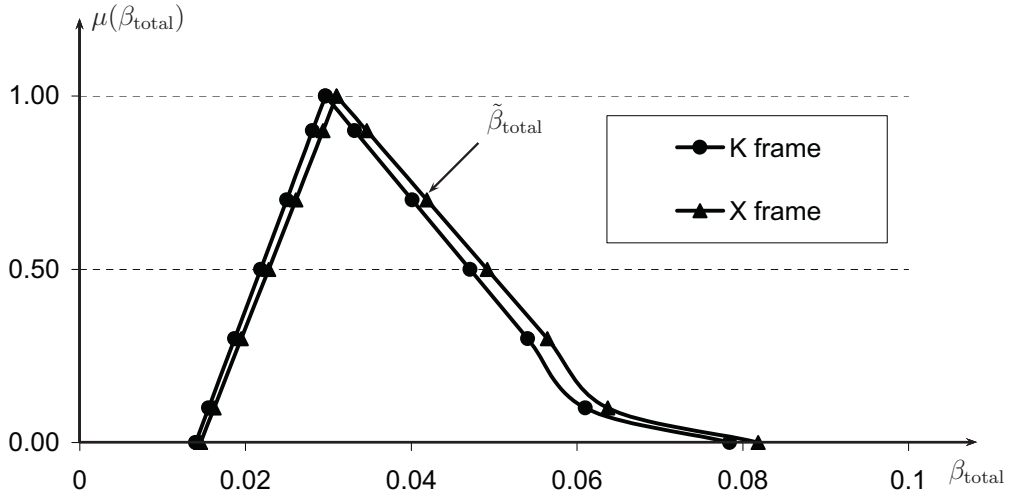


Figure 10: Total damage represented by  $\tilde{\beta}_{total}$  for the K-braced and X-braced frames

494 *4.3. Robustness assessment of fixed offshore platforms*

495 The specified fuzzy variable  $\tilde{c}(t = 16)$  for the corrosion depth is processed  
496 through the fuzzy structural analysis according to [26], which requires a re-  
497 peated calculation of the fuzzy result values for varying corrosion depth. In  
498 this example, the non-dimensional measures based on ultimate strength anal-  
499 ysis,  $RRF$  in Eq. (3) and  $R_{twice}$  in Eq. (4), are selected as fuzzy result values  
500 for each platform, respectively. For this purpose, the fuzzy structural analy-  
501 sis is coupled to the USFOS software and the fuzzy result values,  $\widetilde{RRF}$  and  
502  $\widetilde{R}_{twice}$ , are found by means of an optimization in the kernel of fuzzy structural  
503 analysis. The overall procedure includes two successive steps. First, a fuzzy  
504 structural analysis is performed with USFOS as a deterministic mapping  
505 model, as illustrated in Fig. 11. This deterministic mapping model provides  
506 the nonlinear ultimate strength analysis. And the fuzzy structural analysis



507 delivers the fuzzy outputs to the second step. In the second step the entropy  
508 is calculated for different alpha-levels with the intersection of membership  
509 functions of both fuzzy inputs and outputs. Numerical sensitivities in the  
510 fuzzy structural analysis and in USFOS with respect to the fuzzy outputs can  
511 be minimized by appropriate selection of the algorithm parameters so that  
512 the corrosion effects can be well captured in the fuzzy outputs. The intersec-  
513 tion of member functions, in the second step, is based on the mathematical  
514 operation of fuzzy sets and no additional effects will be introduced during  
515 this operation. Effects from entropy calculation by numerical integration of  
516 Eq. (16) are insignificant. Thus, the corrosion effects can be well reflected  
517 in the main results, which provide a sound basis to the application of the  
518 proposed approach.

519  $\widetilde{\text{RRF}}$  reflects the imprecision of the ultimate capacity of the damaged  
520 platforms under corrosion at different membership levels, see Fig. 12. The  
521 entropy values associated with  $\alpha_k$  of  $\tilde{\beta}_{\text{total},\alpha_k}$  and  $\widetilde{\text{RRF}}_{\alpha_k}$ , normalized by  
522  $H(\tilde{\beta}_{\text{total}})$ , are shown in Fig. 13. It shows that the imprecision in  $\widetilde{\text{RRF}}_{\alpha_k}$   
523 of the K frame decreases much faster than the imprecision in  $\widetilde{\text{RRF}}_{\alpha_k}$  of the  
524 X frame, especially for larger values of  $\alpha_k$ . Thus, the K frame has advanta-  
525 geous properties over the X frame in view of the effects of imprecise marine  
526 corrosion on the ultimate capacity.

527 Based on the proposed approach for robustness assessment in Eq. (20)  
528 and Eq. (21), the entropy-based robustness  $R(\alpha_k)$  at each alpha-level is  
529 calculated as the ratio between the entropy of  $\tilde{\beta}_{\text{total},\alpha_k} = \tilde{\beta}_{\text{total}} \cap \beta_{\text{total},\alpha_k}$  of  
530 the fuzzy input  $\tilde{\beta}_{\text{total}}$  and the entropy of  $\widetilde{\text{RRF}}_{\alpha_k} = \widetilde{\text{RRF}} \cap \text{RRF}_{\alpha_k}$  of the  
531 fuzzy output  $\widetilde{\text{RRF}}$ . The result is shown in Fig. 14, which indicates that

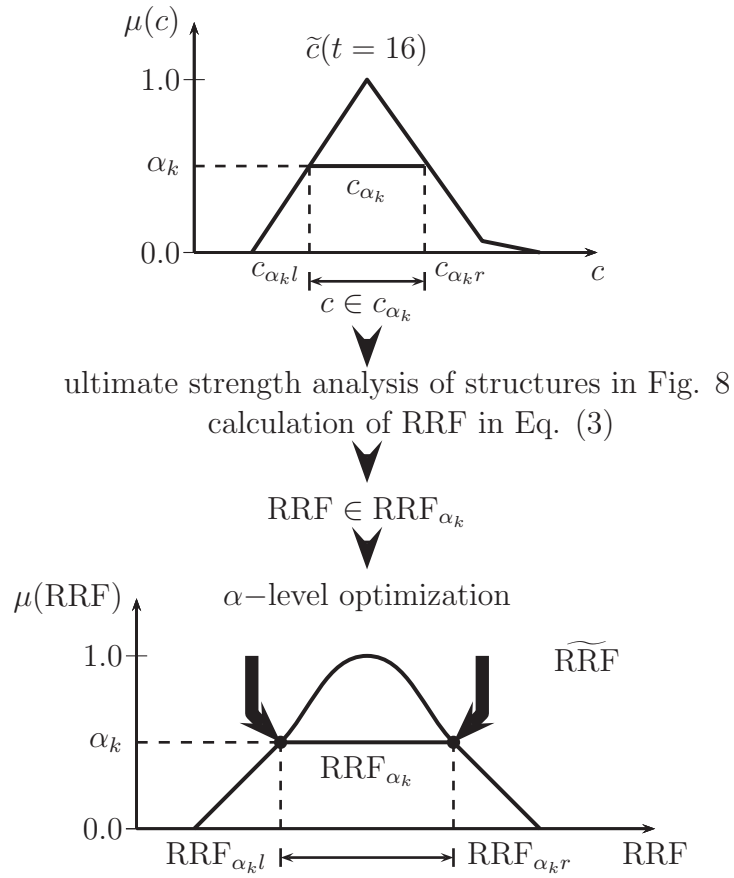


Figure 11: Fuzzy structural analysis with the nonlinear ultimate strength analysis as the deterministic mapping model

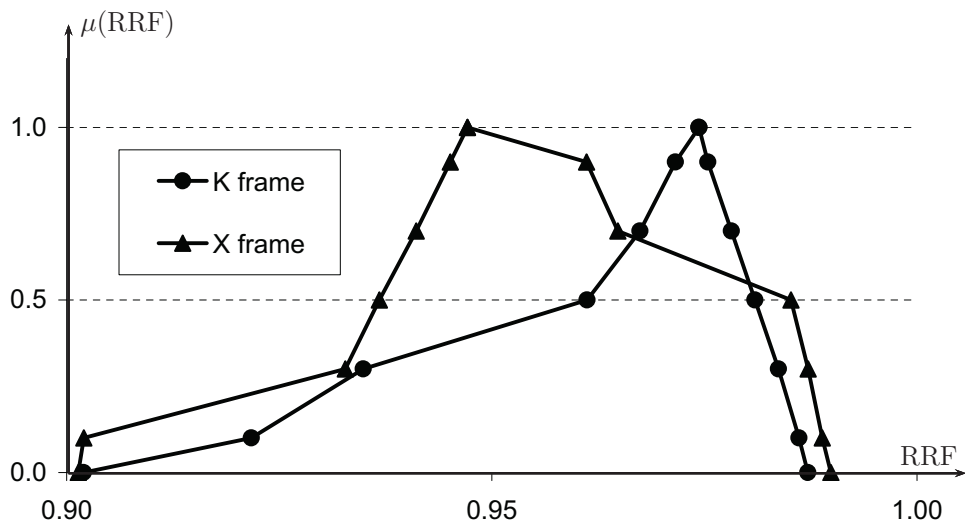


Figure 12: The membership functions of fuzzy RRF for the K-braced and X-braced frames

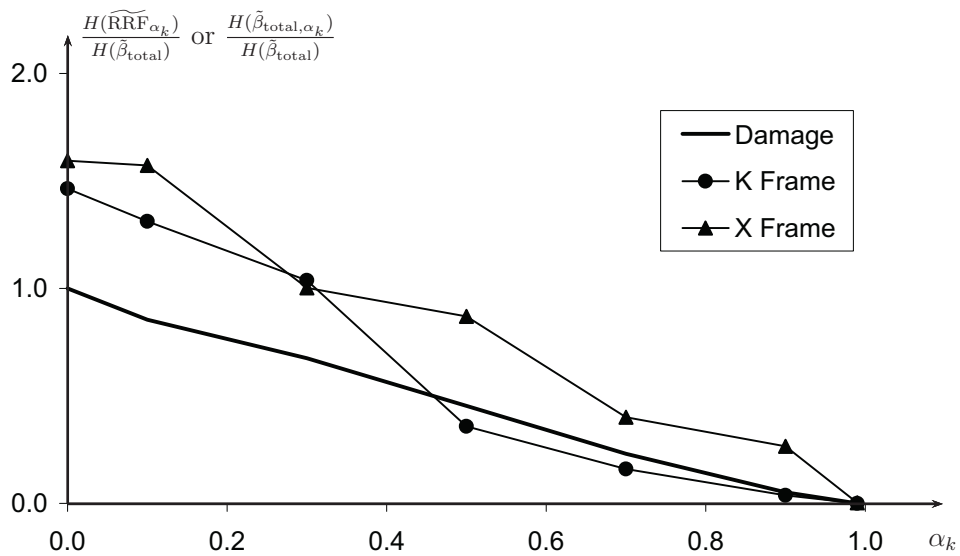


Figure 13: A reduction of imprecision in the fuzzy damage  $\tilde{\beta}_{total}$  as  $\alpha_k$  increases and the corresponding reduction of imprecision in the fuzzy output  $\widetilde{RRF}$

532 the K-frame and the X-frame have a similar robust behavior with respect  
533 to imprecise corrosion effects when  $\alpha_k \leq 0.3$ . However, the K-frame shows  
534 a greater robustness than the X-frame when  $\alpha_k > 0.3$ . This result suggests  
535 that the robustness assessment for the K-frame can be significantly improved  
536 by collecting additional information about the corrosion, i.e. by reduction  
537 of input imprecision. However, collection of additional information regard-  
538 ing long time marine corrosion may be very difficult in offshore engineering  
539 practice. For the K-frame additional effort pays off, whereas for the X-frame,  
540 no clear benefit can be observed. This conclusion illustrates the potential of  
541 the proposed robustness measure for cost reduction and optimal resource  
542 allocation in inspection scheduling.

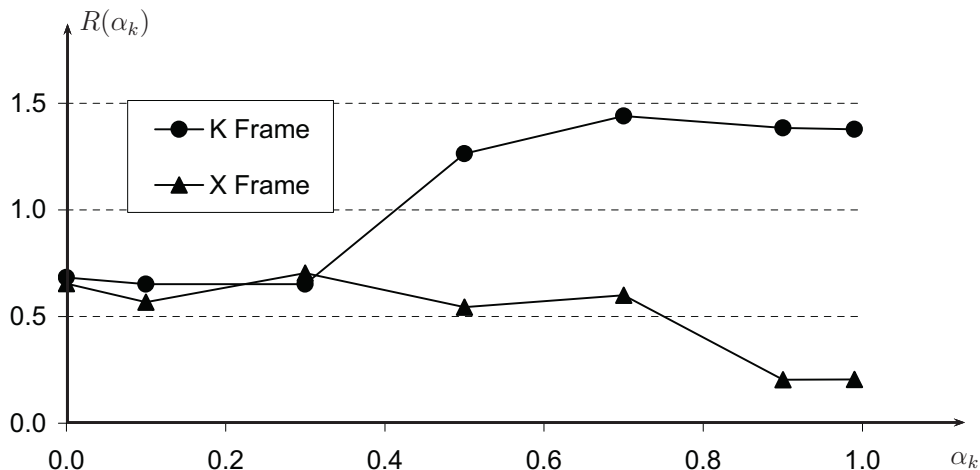


Figure 14: Robustness  $R(\tilde{\beta}_{\text{total}}, \widetilde{\text{RRF}})$  associated with each frame with alpha-level ( $\alpha_k$ ) discretization

543 This observation that the K-frame shows a similar robust behavior as the  
544 X-frame when  $\alpha_k \leq 0.3$  and a greater robustness when  $\alpha_k > 0.3$  is quite dif-  
545 ferent from the statement that the X-frame is more robust than the K-frame

546 using the deterministic performance measures in [1, 2]. Furthermore, it is also  
 547 known that the X-frame shows ductile behavior while the K-frame shows brittle  
 548 behavior. However, these two statements are not conflicting with the new  
 549 results as they refer to different aspects. While the deterministic investigation  
 550 refers to ductility, the robustness assessment considered herein refers to the  
 551 corrosion effects on the ultimate strength of the structure. A consideration of  
 552 the residual load carrying capacity leads to an agreement in the conclusions.  
 553 This can be observed in Fig. 15 by comparing the nominal distances of  $\tilde{R}_{twice}$   
 554 from the value 1.0,  $d_X(\tilde{R}_{twice})$  and  $d_K(\tilde{R}_{twice})$ . In this result,  $\tilde{R}_{twice}$  reflects the  
 555 imprecision of the residual strength of the damaged platforms under corro-  
 556 sion corresponding to twice the ultimate deflection at different membership  
 557 levels. A smaller value of the distance indicates a smaller drop in the post  
 558 ultimate strength, i.e., more ductility. This effect can be included in the  
 559 robustness measures as constraint distance as proposed in [16]. Although  
 560 the X-frame shows a better ductile behavior than the K-frame, as observed  
 561 in Fig. 15, both frames show a similar robustness in view of the imprecise  
 562 damage due to corrosion and the associated imprecision in  $R_{twice}$ , see Fig.  
 563 16. Further, it is indicated in Fig. 16 that  $R(\tilde{\beta}_{total}, \tilde{R}_{twice})$  keeps decreasing  
 564 as  $\alpha_k$  is increased. This indicates that the residual resistance  $\tilde{R}_{twice}$  is insen-  
 565 sitive with respect to extreme values of the corrosion depth and rather shows  
 566 sensitivities when the corrosion depth varies around the mean.

567 It is noted that the entropy results mainly reflect the sensitivities of the  
 568 selected non-dimensional measures RRF and  $R_{twice}$  with respect to the un-  
 569 certainty in corrosion depth. The interpretation of the results is focused on  
 570 the trade-off between the effort for collection of additional information re-

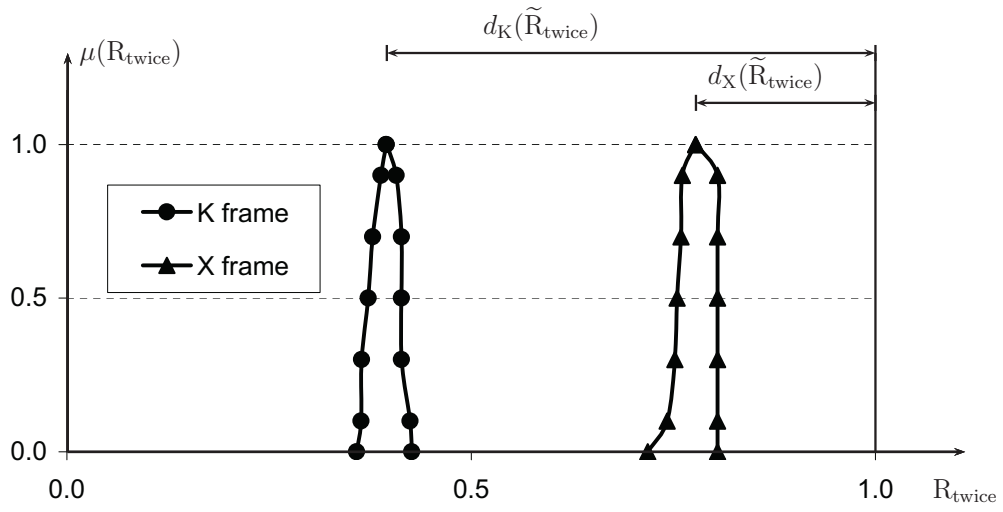


Figure 15: Membership function of  $\tilde{R}_{twice}$  for the K-braced and X-braced frames

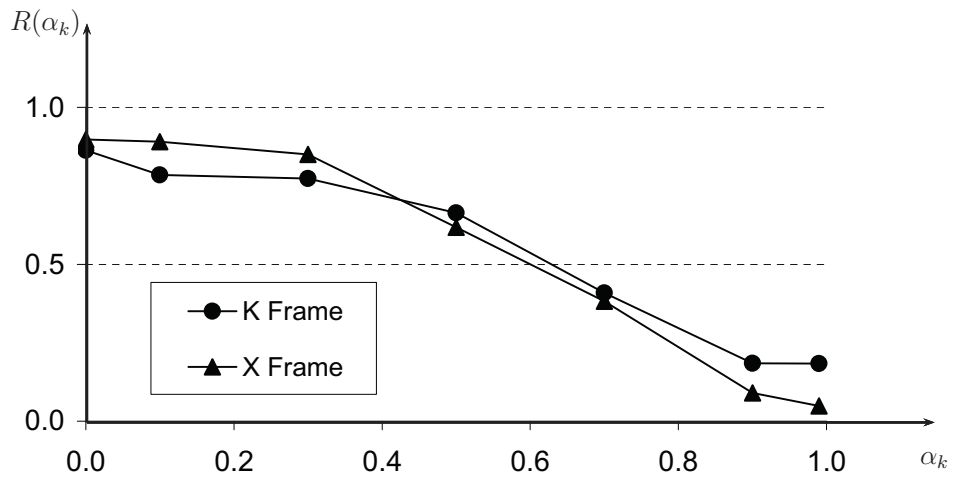


Figure 16: Robustness  $R(\tilde{\beta}_{total}, \tilde{R}_{twice})$  associated with each frame with alpha-level ( $\alpha_k$ ) discretization

571 guarding the corrosion damage and the gain for the robustness assessment of  
572 the structures. However, the fuzzy outputs  $\widetilde{RRF}$  and  $\widetilde{R}_{\text{twice}}$  are related to the  
573 frame behaviors, which becomes particularly clear in Fig. 15. The results  
574 show both the imprecision of the residual strength under corrosion damage  
575 and the property of structural redundancy.

576 The derived statements regarding to the effects of marine corrosion on  
577 the robustness of the two platforms designed in this numerical example may  
578 not be generalized to other gradual effects on the robustness or an alternative  
579 design. But the proposed approach provides a general basis for the robust-  
580 ness assessment of any newly designed or existing platforms with respect to  
581 imprecise effects of deterioration.

582 In summary, the different effects discussed and observed in Fig. 14~16 are  
583 not conflicting with each other but are complementary to formulate diverse  
584 views at the robustness of the X-frame and the K-frame. The influence of  
585 the framing configuration on the robustness of the fixed offshore platforms  
586 can be understood in a comprehensive way based on the proposed approach.

## 587 **5. Conclusions**

588 An improved methodology for nuanced robustness assessment of struc-  
589 tures was proposed and demonstrated for aging offshore structures subjected  
590 to uncertain damage due to imprecise marine corrosion. Fuzzy variables  
591 were utilized to cater for the subjective character of the assessment of the  
592 corrosion effect. Structural robustness was evaluated at various membership  
593 levels to reflect various degrees of imprecision in the damage. It was shown  
594 that diverse views at the structural robustness can be formulated to provide

595 more comprehensive understanding of the influence of the structural layout  
596 on the robustness. Engineering decisions for the design and re-analysis of  
597 structures can so be generated on a broader basis. In the assessment of ex-  
598 isting structures, an improved optimal resource allocation for inspection can  
599 be obtained. The proposed approach provides a general basis for the assess-  
600 ment of structural robustness under the consideration of fuzzy uncertainty  
601 in the structural parameters. It can also be applied to robust design. For  
602 a practical application one needs to implement a fuzzy structural analysis,  
603 as well, which can be numerically demanding for large structures. Further  
604 development on this side would benefit applications. Also, further develop-  
605 ment is needed to address the invariance issue of the entropy measure for  
606 fuzzy sets.

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