

# Wind data extrapolation and stochastic field statistics estimation via compressive sampling and low rank matrix recovery methods

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## Abstract

A methodology based on compressive sampling is developed for incomplete wind time-histories reconstruction and extrapolation in a single spatial dimension, as well as for related stochastic field statistics estimation. This relies on  $l_1$ -norm minimization in conjunction with an adaptive basis re-weighting scheme. Indicatively, the proposed methodology can be employed for monitoring of wind turbine systems, where the objective relates to either reconstructing incomplete time-histories measured at specific points along the height of a turbine tower, or to extrapolating to other locations in the vertical dimension where sensors and measurement records are not available. Further, the methodology can be used potentially for environmental hazard modeling within the context of performance-based design optimization of structural systems.

Unfortunately, a straightforward implementation of the aforementioned approach to account for two spatial dimensions is hindered by significant, even prohibitive in some cases, computational cost. In this regard, to address computational challenges associated with higher-dimensional domains, a methodology based on low rank matrices and nuclear norm minimization is developed next

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for wind field extrapolation in two spatial dimensions. The efficacy of the proposed methodologies is demonstrated by considering various numerical examples. These refer to reconstruction of wind time-histories with missing data compatible with a joint wavenumber-frequency power spectral density, as well as to extrapolation to various locations in the spatial domain.

*Keywords:* Wind data, Stochastic field, Sparse representations, Compressive sampling, Low-rank matrix.

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## 1. Introduction

Estimating wind field model related statistics relies, typically, on information provided by data acquisition systems such as distributed sensor networks and LIDAR acquisition systems (e.g., [1], [2]). In many real-life cases, however, the measured data are corrupted and incomplete. Also, it is often required to extrapolate relevant wind field information to points of interest, where there are no measurements due to limited equipment availability. Clearly, developing methodologies for accurate reconstruction and extrapolation of wind field data is of paramount importance to the analysis, design and monitoring of engineering systems such as wind turbines; see, for instance, [3]. Further, it is worth noting that such methodologies can be used potentially for environmental hazard modeling within the context of performance-based design optimization of structural systems (e.g., [4], [5]).

Indicatively, a wavelet-based fluid motion estimator was developed in [6] for estimating wind fields based on backscatter data. Further, a dimension reduction approach based on computational fluid dynamics data was applied in [7] for wind field reconstruction. Also, several machine learning approaches based on various neural network implementations and configurations were employed recently for wind data reconstruction and extrapolation (e.g., [8–10]). Moreover, surrogate modeling based on Kriging was proposed in [11], whereas Kalman filtering was used in [12] for wind field estimation based on a limited number of LIDAR measurements.

Nevertheless, most of the aforementioned approaches are characterized by significant limitations. For example, in many cases the techniques appear efficacious only for relatively small percentages of missing data, whereas results based on black-box approaches such as neural networks are not always interpretable. Alternatively, various methodologies based on compressive sampling (CS) have been developed recently, which appear promising for stochastic process statistics esti-

29 mation based on realizations with incomplete/missing data (e.g., [13–15]). The  
 30 interested reader is also directed to the recent review paper by Kougioumtzoglou  
 31 et al. [16] for a broad perspective on theoretical concepts and diverse applications  
 32 of sparse representations and CS approaches in engineering mechanics.

33 In this paper, a methodology based on CS is developed, which relies on  $l_1$ -  
 34 norm minimization in conjunction with an adaptive basis re-weighting scheme, for  
 35 incomplete wind field time-histories reconstruction and extrapolation in a single  
 36 spatial (vertical) dimension. Next, to address computational challenges associated  
 37 with higher-dimensional domains, a methodology based on low rank matrices and  
 38 nuclear norm minimization is developed for wind field extrapolation in two spa-  
 39 tial dimensions. The efficacy of the proposed methodologies is demonstrated by  
 40 considering various numerical examples. These refer to reconstruction of wind  
 41 time-histories with missing data compatible with a joint wavenumber-frequency  
 42 power spectral density (PSD), as well as to extrapolation to various locations in  
 43 the spatial domain.

## 44 2. Wind field spectral representation

45 In various engineering applications, the wind field can be conveniently mod-  
 46 eled as a stochastic wave (e.g., [17]). This facilitates the efficient simulation of  
 47 realizations corresponding to a large number of points in the spatial domain, while  
 48 circumventing the need for cross-PSD related calculations; see also [18]. In this  
 49 section, following closely [19], the basic elements associated with Monte Carlo  
 50 simulation (MCS) of a wind field compatible with a joint wavenumber-frequency  
 51 PSD are reviewed for completeness.

### 52 2.1. Wind field time-histories simulation in a single spatial dimension

53 A homogeneous wind field in the vertical dimension is related to a wavenumber-  
 54 frequency PSD (e.g., [17], [19]) given by

$$S^{(\text{WF})}(k, \omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} S^{(\text{F})}(\xi, \omega) e^{-ik\xi} d\xi \quad (1)$$

55 where  $\omega$ ,  $\xi$ ,  $k$  denote the frequency, spatial distance and wavenumber, respectively.  
 56 Further,

$$S^{(\text{F})}(\xi, \omega) = S_0(\omega) \rho(\xi, \omega) = S_0(\omega) \exp\left(-\frac{C_z}{2\pi U_{10}} |\omega| |\xi|\right) \quad (2)$$

57 where  $S_0(\omega)$  is the auto-PSD and  $\rho(\xi, \omega)$  represents the coherence function. Com-  
 58 bining Eq. (1) and Eq. (2),  $S^{(\text{WF})}(k, \omega)$  takes the form

$$S^{(\text{WF})}(k, \omega) = S_0(\omega)\rho^{(\text{WF})}(k, \omega) = S_0(\omega)\frac{C_z}{2\pi^2U_{10}}\frac{|\omega|}{\left(\frac{C_z}{2\pi U_{10}}\right)^2\omega^2 + k^2} \quad (3)$$

59 where  $C_z$  is an exponential decay coefficient and  $U_{10}$  is the mean wind velocity  
 60 at a height of 10m. Next, Eq. (3) can be used in conjunction with the spectral  
 61 representation method (SRM) [20] for generating wind velocity records in the  
 62 form

$$X(z, t) = \sum_{i=1}^{N_k} \sum_{j=1}^{N_\omega} \sqrt{4S^{(\text{WF})}(k_i, \omega_j) \Delta k \Delta \omega} \quad (4)$$

$$\times [\cos(k_i z + \omega_j t + \varphi_{ij}) + \cos(k_i z - \omega_j t + \tilde{\varphi}_{ij})]$$

63 where  $\varphi_{ij}$  and  $\tilde{\varphi}_{ij}$  represent two sets of independent random phase angles uni-  
 64 formly distributed over  $[0, 2\pi]$ ;  $k_i = i\Delta k$  with  $\Delta k = k_u/N_k$  denotes the dis-  
 65 cretized wavenumber domain with an upper cut-off wavenumber  $k_u$ ; and  $\omega_j =$   
 66  $j\Delta\omega$  with  $\Delta\omega = \omega_u/N_\omega$  is the discretized frequency domain with an upper cut-  
 67 off frequency  $\omega_u$ . In the ensuing analysis and numerical examples, the Davenport  
 68 PSD is considered (e.g. [20], [21]); that is,

$$S^{\text{Davenport}}(\omega) = 2.0u_*^2 \frac{\left(\frac{1200}{2\pi U_{10}}\omega\right)^2}{|\omega| \left(1 + \left(\frac{1200}{2\pi U_{10}}\omega\right)^2\right)^{4/3}} \quad (5)$$

69 where  $u_*$  denotes the shear flow velocity. Further, the parameters values used are  
 70  $U_{10} = 31.88$  m/s,  $u_* = 1.691$  m/s and  $C_z = 10$ .

## 71 2.2. Wind field time-histories simulation in two spatial dimensions

72 In this section, following closely [19], a generalization of the results outlined  
 73 in section 2.1 is presented to account for a two-dimensional spatial domain. In

74 this regard, the joint wavenumber-frequency PSD of Eq. (3) takes the form

$$\begin{aligned}
S^{(\text{WF})}(k_y, k_z, \omega) &= S^{\text{Davenport}}(\omega) \cdot \rho^{(\text{WF})}(k_y, k_z, \omega) \\
&= \frac{u_*^2}{\pi C_{1z} C_{1y} \left(\frac{1}{2\pi U_{10}} |\omega|\right)^2} \frac{\left(\frac{1200}{2\pi U_{10}} \omega\right)^2}{|\omega| \left(1 + \left(\frac{1200}{2\pi U_{10}} \omega\right)^2\right)^{4/3}} \\
&\times \frac{1}{\left(1 + \left[\left(\frac{1}{C_{1y}} k_y\right)^2 + \left(\frac{1}{C_{1z}} k_z\right)^2\right] / \left(\frac{1}{2\pi U_{10}} |\omega|\right)^2\right)^{\frac{3}{2}}}
\end{aligned} \tag{6}$$

75 where

$$\begin{aligned}
\rho^{(\text{WF})}(k_y, k_z, \omega) &= \frac{1}{2\pi C_{1z} C_{1y} \left(\frac{1}{2\pi U_{10}} |\omega|\right)^2} \\
&\times \frac{1}{\left(1 + \left[\left(\frac{1}{C_{1y}} k_y\right)^2 + \left(\frac{1}{C_{1z}} k_z\right)^2\right] / \left(\frac{1}{2\pi U_{10}} |\omega|\right)^2\right)^{\frac{3}{2}}}
\end{aligned} \tag{7}$$

76 In Eqs. (6)-(7),  $C_{1z}$  and  $C_{1y}$  are the exponential decay coefficients corresponding  
77 to the vertical and horizontal directions, respectively, and  $k_z$  and  $k_y$  denote the  
78 respective wavenumbers. Next, realizations compatible with the PSD of Eq. (6)  
79 can be generated based on the SRM (e.g., [17], [19]). In this context, Eq. (4)  
80 becomes

$$\begin{aligned}
X(z, y, t) &= \sum_{i=1}^{N_{k_z}} \sum_{j=1}^{N_{k_y}} \sum_{m=1}^{N_\omega} \sqrt{4S^{(\text{WF})}\left(k_i^{(z)}, k_j^{(y)}, \omega_m\right) \Delta k_i^{(z)} \Delta k_j^{(y)} \Delta \omega^{(m)}} \\
&\cdot \left[ \cos\left(k_i^{(z)} z + k_j^{(y)} y + \omega_m t + \varphi_{ijm}^{(1)}\right) \right. \\
&+ \cos\left(k_i^{(z)} z + k_j^{(y)} y - \omega_m t + \varphi_{ijm}^{(2)}\right) \\
&+ \cos\left(k_i^{(z)} z - k_j^{(y)} y + \omega_m t + \varphi_{ijm}^{(3)}\right) \\
&\left. + \cos\left(k_i^{(z)} z - k_j^{(y)} y - \omega_m t + \varphi_{ijm}^{(4)}\right) \right]
\end{aligned} \tag{8}$$

81  $k_j^{(y)} = j\Delta k_y, j = 1, 2, \dots, N_{k_y}$  and  $k_i^{(z)} = i\Delta k_z, i = 1, 2, \dots, N_{k_z}$  are the dis-  
82 cretized wavenumber domains in  $y$  and  $z$  directions with a number of points  $N_{k_y}$

83 and  $N_{k_z}$ , respectively. Further,  $\varphi_{ijm}^{(1)}$ ,  $\varphi_{ijm}^{(2)}$ ,  $\varphi_{ijm}^{(3)}$  and  $\varphi_{ijm}^{(4)}$  represent four dif-  
84 ferent sets of independent random phase angles uniformly distributed in  $[0, 2\pi]$ .

85 Regarding computational implementation aspects, it is readily seen that the  
86 Davenport PSD of Eq. (5) exhibits a singularity at the origin, which can be ad-  
87 dressed, however, based on a frequency shift scheme (e.g., [17], [22]). In this re-  
88 gard, it is reasonable to consider an uneven discretization scheme, which is denser  
89 near the origin of the wavenumber domains.

### 90 **3. Wind field reconstruction and extrapolation in the joint space-time do- 91 main: A compressive sampling treatment**

92 Research efforts during the past fifteen years have focused on identifying and  
93 exploiting low-dimensional representations of high-dimensional data, as well as  
94 on establishing conditions guaranteeing unique representation in the low-dimensional  
95 space (e.g., [23], [24]). These theoretical results, coupled with potent convex opti-  
96 mization numerical algorithms, have triggered the birth of the currently expanding  
97 field of CS and have led to numerous impactful contributions in a wide range of  
98 application areas (e.g., [25]). The interested reader is also directed to the recent  
99 review paper by Kougioumtzoglou et al. [16] and to references therein for a broad  
100 perspective on theoretical concepts and diverse applications of sparse representa-  
101 tions and CS approaches in engineering mechanics.

102 In this section, first, a CS approach based on  $l_1$ -norm minimization in conjunc-  
103 tion with an adaptive basis re-weighting scheme is developed for wind field time-  
104 histories reconstruction and extrapolation in a single spatial dimension. Second,  
105 to address computational challenges associated with multi-dimensional domains,  
106 a CS approach based on nuclear norm minimization is developed for wind field  
107 extrapolation in two spatial dimensions.

#### 108 *3.1. Reconstruction and extrapolation in a single spatial dimension: $l_1$ -norm 109 minimization in conjunction with an adaptive basis re-weighting scheme*

##### 110 *3.1.1. Theoretical aspects*

111 In this section, the CS-based methodology developed in [26] for extrapolation  
112 of random wave field data in the joint space-time domain is adapted and extended  
113 to account for wind stochastic field extrapolation. Indicatively, this methodology  
114 can be employed for cases of monitoring wind turbine systems, where the objec-  
115 tive is to either reconstruct incomplete time-histories measured at specific points  
116 along the height of a turbine tower, or to extrapolate to other locations in the ver-  
117 tical dimension where sensors and measurement records are not available.

118 Consider an  $n_0 \times 1$  column vector  $\mathbf{y}_0$  denoting a measured time history, which  
119 can be expanded by employing a basis matrix  $\mathbf{A}_0$  of dimensions  $n_0 \times n_0$  in the form  
120  $\mathbf{y}_0 = \mathbf{A}_0 \mathbf{x}$ , where  $\mathbf{x}$  is the corresponding coefficient vector. Clearly, the sparsity  
121 degree of the coefficient vector  $\mathbf{x}$  (i.e., number of non-zero elements) depends on  
122 the choice of the basis matrix  $\mathbf{A}$  (e.g, polynomial, Fourier, etc). Resorting to a  
123 CS-based solution approach and considering a relatively high degree of sparsity,  
124 the coefficient vector  $\mathbf{x}$  can be determined with satisfactory accuracy even if the  
125 system of equations  $\mathbf{y}_0 = \mathbf{A}_0 \mathbf{x}$  is underdetermined. Specifically, consider an  
126  $(n_0 - n_m) \times 1$  column vector  $\mathbf{y}$  representing an under-sampled time history at a  
127 specific location along the height of a wind turbine.  $n_0$  denotes the original sample  
128 and  $n_m$  is the number of randomly missing data. Further, considering a sampling  
129 matrix  $\mathbf{A}$  of dimensions  $(n_0 - n_m) \times n_0$  leads to the underdetermined system  
130 of equations  $\mathbf{y} = \mathbf{A} \mathbf{x}$ , where the objective relates to determining the coefficient  
131 vector  $\mathbf{x}$  assumed to be sparse. According to CS theory (e.g., [16]), the problem  
132 can be cast in a convex optimization setting via minimizing the  $l_1$ -norm of  $\mathbf{x}$ ; that  
133 is,

$$\min \|\mathbf{x}\|_{l_1} \text{ subject to } \mathbf{y} = \mathbf{A} \mathbf{x} \quad (9)$$

134 Clearly, the use of the  $l_1$ -norm promotes sparsity, whereas Eq. (9) can be readily  
135 solved by standard gradient optimization algorithms (e.g., [16]). Alternatively, the  
136 constraint in Eq. (9) can be relaxed and replaced by  $\|\mathbf{y} - \mathbf{A} \mathbf{x}\|_{l_2} \leq \varepsilon$  to account  
137 for possible presence of noise.

138 Nevertheless, as also shown in [27], [4], [15], an adaptive basis re-weighting  
139 scheme can further promote sparsity and yield solution estimates of enhanced  
140 accuracy. In this regard, Eq. (9) becomes

$$\min \|\mathbf{x}\|_{l_1} \text{ subject to } \mathbf{y} = \mathbf{A} \mathbf{W} \mathbf{x} \quad (10)$$

141 where  $\mathbf{W}$  is a re-weighting diagonal matrix. The rationale of the scheme relates  
142 to matrix  $\mathbf{W}$  being used to appropriately weigh the columns of the basis matrix  $\mathbf{A}$ .  
143 To this aim, the entries of  $\mathbf{W}$  correspond to the magnitudes of the components of  
144  $\mathbf{x}$ . This promotes sparsity as it reduces the contribution of the smaller components  
145 of vector  $\mathbf{x}$ . Concisely, the mechanization of the re-weighting scheme is shown  
146 in Fig. (1), whereas the interested reader is directed to [4], [15] for a detailed  
147 presentation and discussion.

148 Clearly, the scheme is best suited to problems where an ensemble of time-  
149 histories with incomplete data points is available and the objective relates to de-  
150 termining statistics based on the ensemble average, such as estimating the under-  
151 lying process PSD. Nevertheless, even in cases where only a single (relatively

- Initialize re-weighting matrix  $\mathbf{W}$ ,  $\mathbf{W}_2 = \mathbf{I}_{n_0}$  where  $\mathbf{I}$  is the identity matrix

```

while |  $\mathbf{W}_2 - \mathbf{W}$  | > threshold do
 $\mathbf{W} = \mathbf{W}_2$ 
 $\mathbf{W}_2 = \text{zeros}(n_0, n_0)$ 

- Generate re-weighting matrix via least squares


```

for  $i = 1$  to  $m$  do ▷  $m =$  number of available time-histories
 $\mathbf{x} = (\mathbf{A}\mathbf{W})^T ((\mathbf{A}\mathbf{W})(\mathbf{A}\mathbf{W})^T)^{-1} \mathbf{y}_i$ 
 $\mathbf{x} = [\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3, \dots, \mathbf{x}_{n_0-1}, \mathbf{x}_{n_0}]$ 
 $\mathbf{W}_2 = \mathbf{W}_2 + \text{diag}([\|\mathbf{x}_2, \mathbf{x}_1\|, \|\mathbf{x}_2, \mathbf{x}_1\|, \|\mathbf{x}_3, \mathbf{x}_2\|, \|\mathbf{x}_3, \mathbf{x}_2\|, \dots,$ 
 $\|\mathbf{x}_{n_0/2}, \mathbf{x}_{n_0/2-1}\|, \|\mathbf{x}_{n_0/2}, \mathbf{x}_{n_0/2-1}\|])$ 

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end for
 $\mathbf{W}_2 = \frac{\mathbf{W}_2}{\text{Mean}(\mathbf{W}_2)} + \text{bias} \cdot \mathbf{I}_{n_0}$ 
end while

```



- Use  $l_1$  minimization to compute the coefficient vector  $\mathbf{x}$



```

 $\mathbf{x} = \min \|\mathbf{x}\|_{l_1}$  subject to  $\mathbf{y} = \mathbf{A}\mathbf{W}_2\mathbf{x}$ 

```


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Fig. 1: Mechanization of  $l_1$ -norm minimization with an adaptive basis

152 long) time-history is available, the scheme can be still implemented under the as-  
153 sumptions of stationarity and ergodicity by considering a partition of the record  
154 into smaller time intervals.

155 Further, it is shown that the above methodology can be readily adapted to be  
156 used for extrapolating wind time-histories corresponding to specific points along  
157 the vertical dimension based on measured data at neighboring locations. Specif-  
158 ically, consider a number of  $N + M$  wind velocity records, each composed of  
159 length  $n$  data points and corresponding to a vertical height  $z_i$ . The objective refers  
160 to inferring wind velocity time histories at  $M$  distinct points from  $N$  measure-  
161 ment locations as depicted in Fig. (2). In this regard, the measured records can be  
162 represented as a column vector  $\mathbf{y}$  of dimension  $nN \times 1$  to be used in the formula-  
163 tion of Eq. (9), or alternatively, of Eq. (10). Next, the sampling matrix  $\mathbf{A}$  can be  
164 constructed based on the SRM of Eq. (4). In particular, matrix  $\mathbf{A}$  is formed as the  
165 tensor product of trigonometric basis functions (e.g., [28]) spanning the frequency  
166 and wavenumber domains. For the frequency domain a basis can be constructed  
167 as

$$\mathbf{B}_1 = [\cos(\omega_0 t) \quad \sin(\omega_1 t) \quad \dots \quad \sin(\omega_{\frac{n}{2}-1} t) \quad \cos(\omega_{\frac{n}{2}} t)] \quad (11)$$

168 with  $\omega_\ell = 2\pi\ell/n$ ,  $\ell = 0, \dots, n/2$ , whereas for the wavenumber domain the

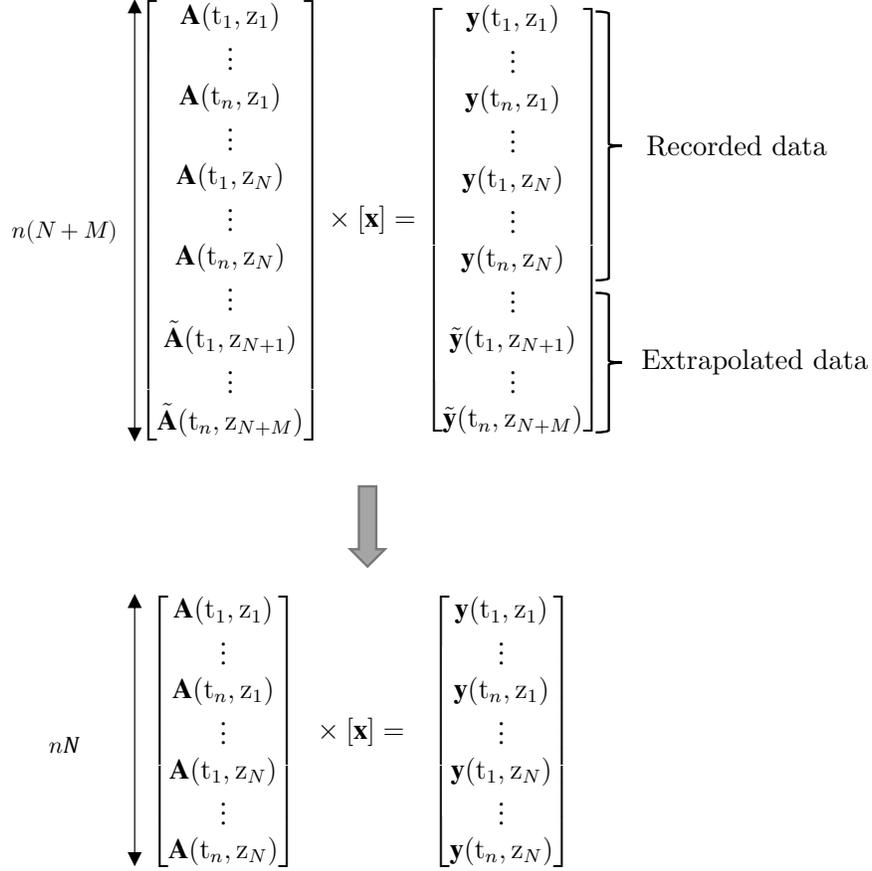


Fig. 2: Sampling matrix construction for CS-based extrapolation in a single spatial dimension.

169 basis becomes

$$\mathbf{B}_2 = [\cos(k_0 z) \quad \sin(k_1 z) \quad \cdots \quad \sin(k_{N/2-1} z) \quad \cos(k_{N/2} z)] \quad (12)$$

170 with  $k_m = 2\pi m/N$ ,  $m = 0, \dots, N/2$ . The tensor product of  $\mathbf{B}_1$  and  $\mathbf{B}_2$  produces  
 171 a new basis for the joint wavenumber-frequency domain in the form

$$\mathbf{B} = \mathbf{B}_1 \otimes \mathbf{B}_2 \quad (13)$$

172 The complete matrix  $\mathbf{B}$  is of dimensions  $n(N+M) \times n(N+M)$ . However, con-  
 173 sidering that time-histories at  $M$  locations of interest are not available,  $\mathbf{B}$  becomes  
 174 an  $nN \times n(N+M)$  **sampling** matrix  $\mathbf{A}$  to be used in Eq. (9) (or, alternatively, in  
 175 Eq. (10)) for extrapolating for the  $M$  locations; see also Fig. (2). **Obviously, com-**

176 paring with the dimensions of matrix  $\mathbf{A}$  defined in Eq. (9) yields  $n_0 - n_m = nN$   
 177 and  $n_0 = n(N + M)$ . In passing, it is noted that over-complete dictionaries can be  
 178 employed as well for constructing matrices  $\mathbf{B}_1$  and  $\mathbf{B}_2$  to enhance the respective  
 179 domain resolution (e.g., [29], [30]).

### 180 3.1.2. Numerical examples

181 In this section, the efficacy of the proposed CS-based approach is assessed,  
 182 first, in conjunction with the problem of reconstructing wind time-histories with  
 183 missing data, and second, in conjunction with extrapolating to various locations  
 184 in the one-dimensional spatial domain.

185 To this aim, 50 time-histories compatible with the PSD of Eq. (3) are gener-  
 186 ated by the SRM of Eq. (4). The parameter values used are: time duration  $T_0$   
 187 = 255.75 s; upper cut-off frequency  $w_u = 8\pi$  rad/s;  $dt = 2\pi/w_u = 0.0125$  s;  
 188  $\Delta\omega = 2\pi/T_0 = 0.0246$  rad/s; upper cut-off wavenumber  $k_u = \pi$  rad/m;  $\Delta k =$   
 189 0.002 rad/m. Next, for each time-history, 40% of missing data are introduced in  
 190 uniformly random gaps. The records are then reconstructed based on the adaptive  
 191 basis re-weighting approach by utilizing Eq. (10).

192 Two indicative wind velocity time-histories are shown in Fig. (3) correspond-  
 193 ing to vertical heights of 50m and 62m, together with their reconstructed counter-  
 194 parts. It is seen that although there are notable discrepancies between the target  
 195 and the reconstructed records, the main features of the time-histories are estimated  
 196 satisfactorily in an average sense. This is very encouraging considering that the  
 197 proposed CS-based approach in this paper focuses on estimating stochastic field  
 198 statistics (e.g., PSD) defined as averages over an ensemble of realizations. In-  
 199 deed, in Fig. (4) the PSD corresponding to a vertical height of 62m is shown,  
 200 estimated as the ensemble average of the Fourier transform of the reconstructed  
 201 time-histories with 40% missing data. Similarly, the cross-correlation and the  
 202 coherence function referring to the two locations at 50m and 62m are also esti-  
 203 mated based on the ensemble average of the reconstructed time-histories and are  
 204 shown in Fig. (5). Clearly, in all cases, comparisons with the target quantities  
 205 demonstrate the capability of the CS-based methodology to estimate stochastic  
 206 field statistics based on an ensemble of realizations with a relatively high degree  
 207 of accuracy considering the rather large amount of missing data.

208 Next, the configuration shown in Fig. (6) is considered where the objective  
 209 is to extrapolate for the entire time-history at a height of 62m and determine re-  
 210 lated statistics by utilizing measured records corresponding to heights of 50, 56,  
 211 68 and 74m. In this regard, Fig. (7) shows an indicative target time-history at 62m  
 212 generated via Eq. (4) together with its estimated counterpart based on Eq. (9).

213 Further, the CS-based estimated PSD at 62m is plotted in Fig. (8) and compared  
214 with the target PSD, whereas the estimated cross-correlation and the coherence  
215 function between the extrapolation point at 62m and two other indicative points  
216 are shown in Figs. (9) and (10), respectively. It is readily seen that the accuracy  
217 degree exhibited by the proposed CS-based methodology is, in general, satisfac-  
218 tory. As anticipated, however, and also observed in Fig. (10), the accuracy degree  
219 of the technique in estimating coherence values decreases for increasing distance  
220 between the considered points in the spatial domain.

### 221 *3.2. Reconstruction and extrapolation in two spatial dimensions: Low-rank ma-* 222 *trices and nuclear norm minimization*

#### 223 *3.2.1. Theoretical aspects*

224 In this section, an alternative CS approach based on nuclear norm minimiza-  
225 tion is developed to account for wind field extrapolation in two spatial dimen-  
226 sions. The rationale relates to the fact that a straightforward application of the  
227 CS approach proposed in section 3.1 based on  $l_1$ -norm minimization becomes  
228 computationally intensive, and even prohibitive in some cases, for an increasing  
229 number of dimensions. In particular, adapting the methodology in section 3.1 for  
230 addressing two spatial dimensions yields a sampling matrix  $\mathbf{A}$  in Eq. (13) with  
231 a prohibitively large number of elements. Clearly, this renders the subsequent  
232 numerical implementation of the methodology at least a rather daunting, if not  
233 impossible, task. Thus, there is a need for developing alternative, more compu-  
234 tationally efficient, approaches to address more sophisticated and realistic wind  
235 field modeling accounting for two spatial dimensions.

236 In this regard, the concept of a matrix norm is invoked in this section, and  
237 specifically, the nuclear norm of a matrix is employed (given as the sum of its  
238 singular values), which can be construed as a generalization of the  $l_1$ -norm to ac-  
239 count for matrices (e.g., [31], [32]). In fact, minimizing the nuclear norm of low  
240 rank matrices can be viewed as an extension of minimizing the  $l_1$ -norm of sparse  
241 vectors, and thus, low rank matrices with a relatively large number of missing  
242 entries can be reconstructed with high probability [33]. Based on the above ar-  
243 gument, the data extrapolation problem in two spatial dimensions can be recast  
244 as a "basis-free" matrix completion problem at each time instant by appropriately  
245 re-arranging the measured data in matrix form. In passing, it is worth mentioning  
246 that nuclear norm minimization in conjunction with low rank matrices has been  
247 used recently in various civil engineering applications. Indicatively, by proposing  
248 a matrix reshape scheme, a low-rank representation of large-scale structural seis-  
249 mic and typhoon responses was identified in [34], which proved to be beneficial

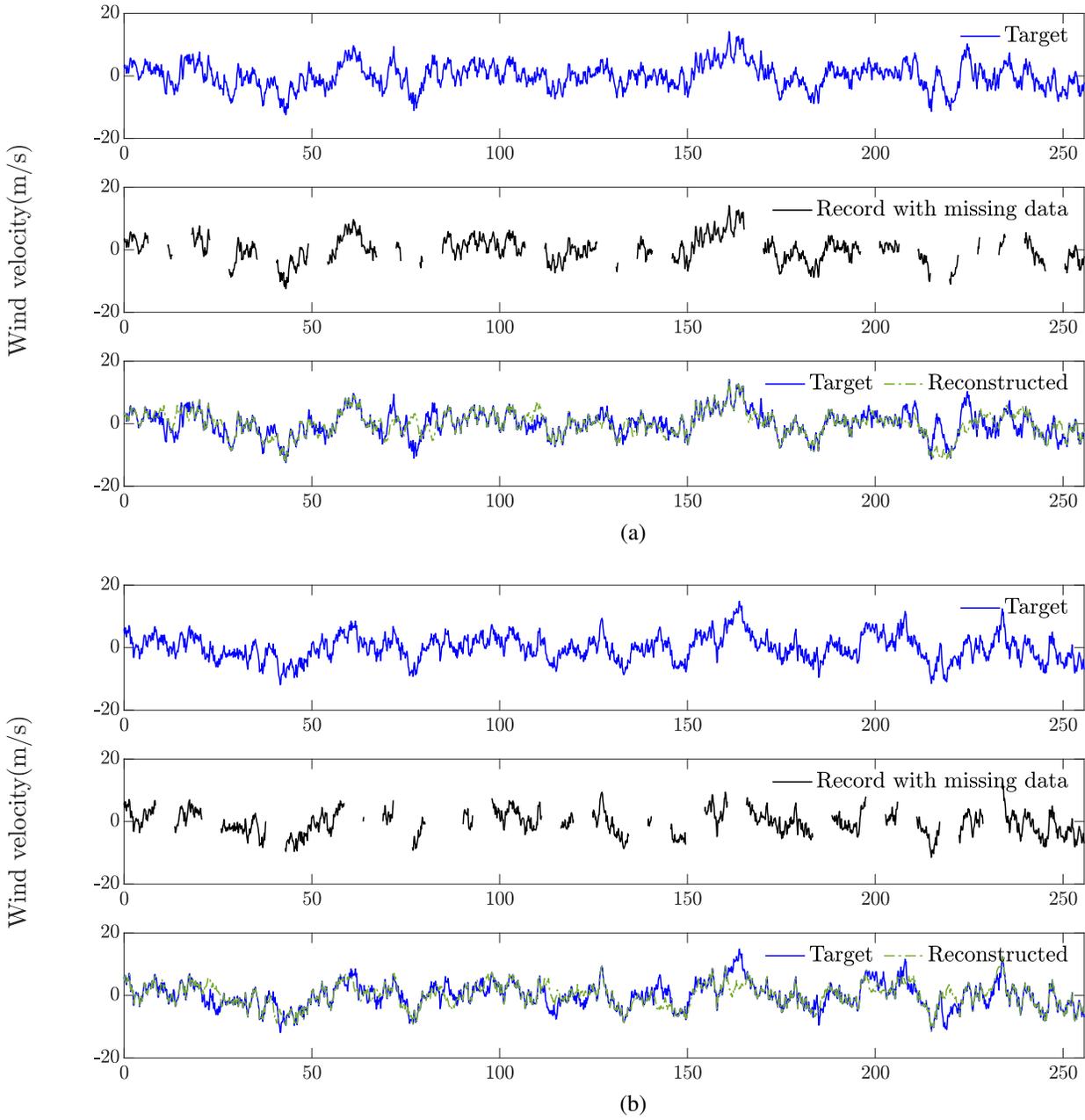


Fig. 3: Indicative wind velocity time-histories at a height of (a) 50m and (b) 62m; comparisons between the target and the CS-based reconstructed records considering 40% missing data.

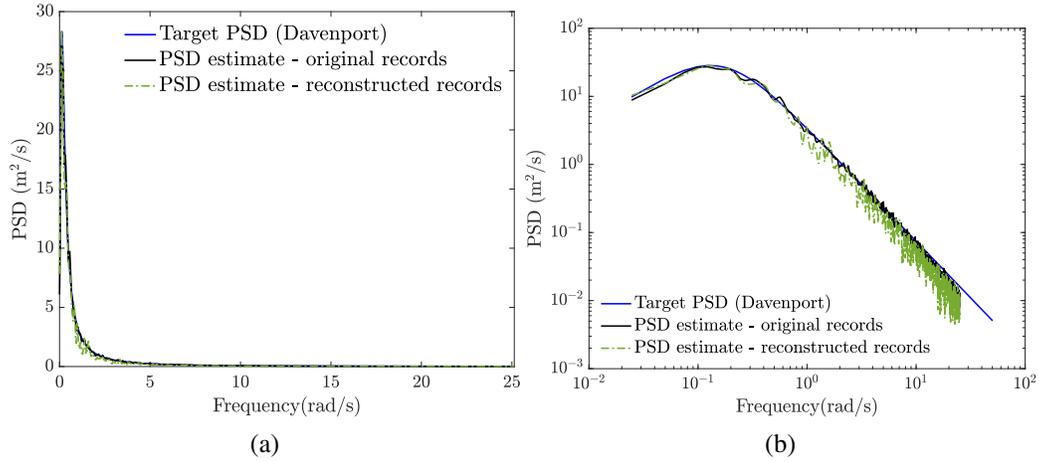


Fig. 4: Estimated PSD corresponding to a vertical height of 62m based on the ensemble average of reconstructed time-histories with 40% missing data; (a) linear scale and (b) logarithmic scale.

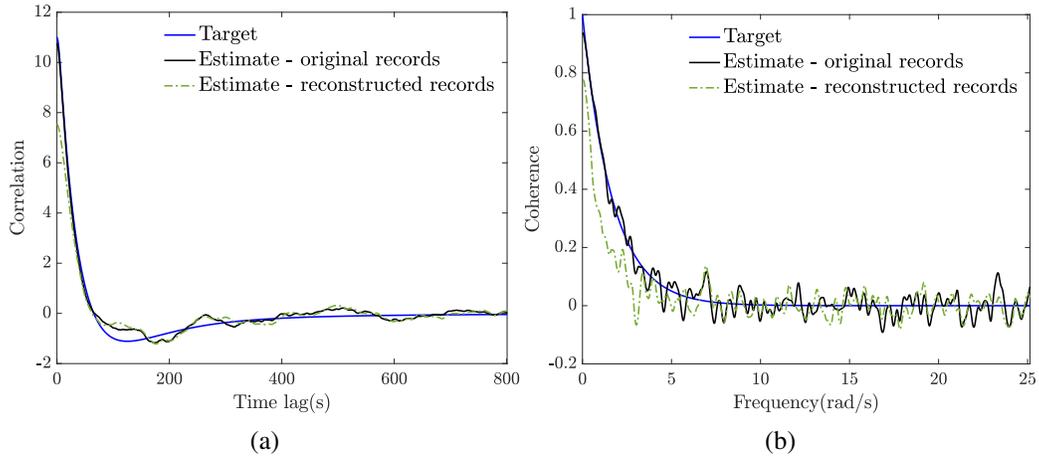


Fig. 5: (a) Cross-correlation and (b) coherence function estimated based on the ensemble average of reconstructed time-histories with 40% missing data corresponding to vertical heights of 50 and 62m.

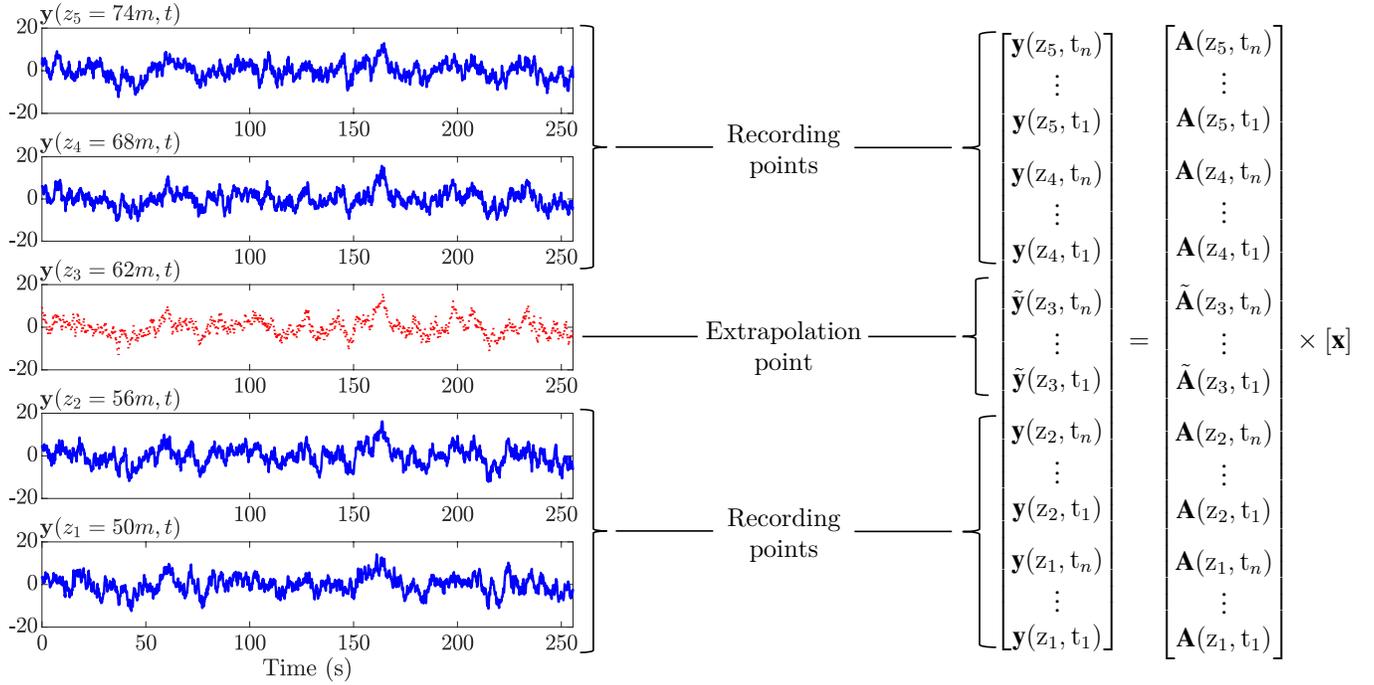


Fig. 6: Schematic representation of the extrapolation scheme in a single spatial dimension via compressive sampling.

250 for efficient data compression. The scheme was coupled in [35] with a nuclear  
 251 norm minimization algorithm for recovering of multi-channel structural response  
 252 time-histories with randomly missing data.

253 Next, considering a matrix  $\mathbf{M} \in \mathbb{R}^{n \times n}$  of rank  $r \ll n$ , with only  $l < n^2$   
 254 of its entries observed, the problem of reconstructing the complete matrix can be  
 255 formally expressed as

$$\begin{aligned} & \text{minimize} && \|\mathbf{Y}\|_* \\ & \text{subject to} && Y_{k,l} = M_{k,l}, \quad (k,l) \in \Omega, \end{aligned} \quad (14)$$

256 where  $\|\cdot\|_*$  denotes the nuclear norm and  $\Omega$  is the index set of observed entries. In  
 257 general, a smaller value of rank  $r$  dictates fewer required observed matrix entries  
 258 for successful matrix completion. More specific relationships between  $n$ ,  $r$ , and  $l$   
 259 can be found, indicatively, in [33]; see also [16] for a broader perspective. Eq. (14)  
 260 represents a convex optimization problem, and a variety of algorithms have been  
 261 developed for its solution; see, for instance, [36], [37] as well as [16] and refer-  
 262 ences therein. In the ensuing analysis, the Augmented Lagrangian Method (ALM)

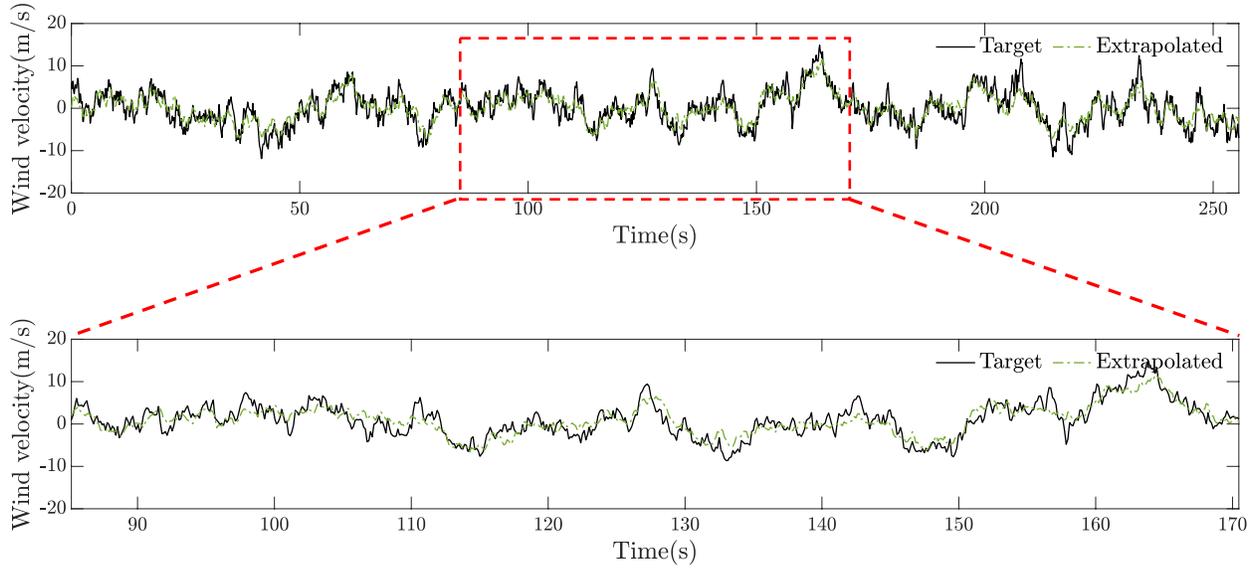


Fig. 7: Indicative wind velocity time-history at a height of 62m; comparisons between the target and the extrapolated records.

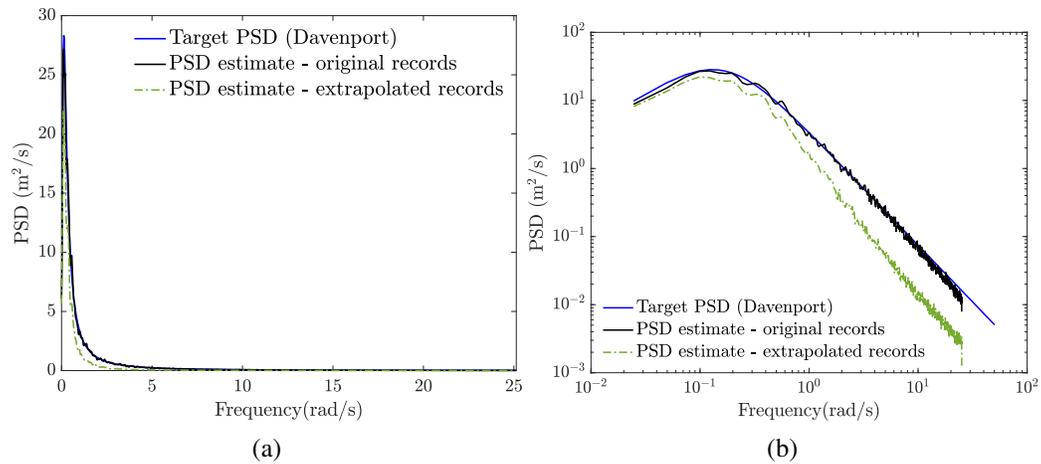


Fig. 8: Estimated PSD corresponding to a vertical height of 62m based on the ensemble average of CS-based extrapolated time-histories; (a) linear scale and (b) logarithmic scale.

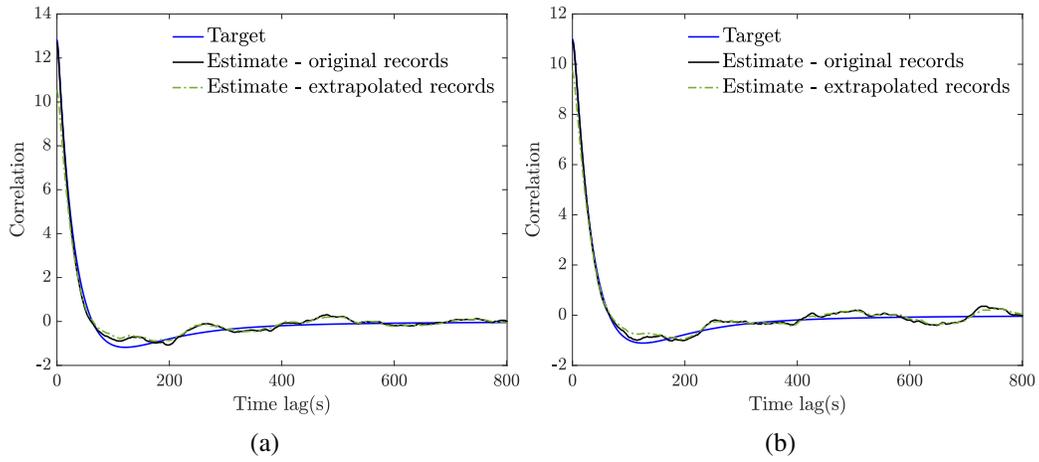


Fig. 9: Cross-correlation function estimated by employing CS-based extrapolated time-histories at 62m and original records at (a) 56m and (b) 74m.

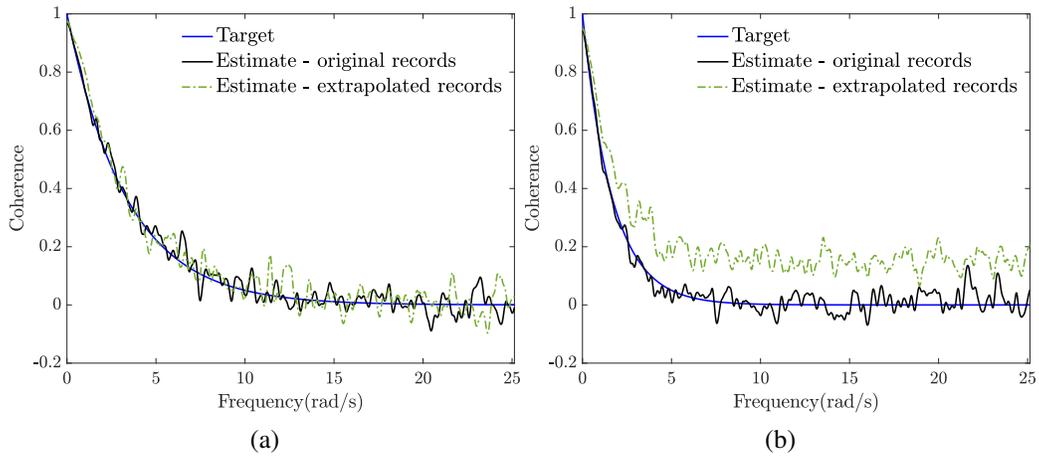


Fig. 10: Coherence function estimated by employing CS-based extrapolated time-histories at 62m and original records at (a) 56m and (b) 74m.

263 is employed [37] for recasting Eq. (14) into an unconstrained optimization prob-  
264 lem and for determining the missing matrix entries; see also [38–40]. An indica-  
265 tive mechanization of ALM is shown in Fig. (11), whereas the interested reader is  
266 directed to [37] for more details.

### 267 3.2.2. Numerical examples

268 In this section, the efficacy of the proposed CS methodology based on low-  
269 rank matrices and nuclear norm minimization is assessed in conjunction with ex-  
270 trapolating to various locations in the two-dimensional spatial domain.

271 Specifically, the extrapolation configuration considered in this section is shown  
272 in Fig. (12), where 50 two-dimensional wind velocity realizations compatible with  
273 the PSD of Eq. (6) are generated based on the SRM of Eq. (8). Next, time-histories  
274 at 12 out of the 36 grid points are considered missing. It is readily seen that,  
275 at a given time instant, extrapolating for the aforementioned 12 locations in the  
276 two-dimensional domain can be formulated as a matrix completion problem in  
277 the form of Eq. (14), where  $\mathbf{Y}$  represents a matrix with 36 elements. Note that  
278 the low-rank assumption, required for a successful implementation of the nuclear  
279 norm minimization solution approach, can be adequately justified by considering  
280 the dependence (by construction based on Eqs. (6)-(7)) between time-histories  
281 corresponding to different locations in the two-dimensional spatial domain. In this  
282 regard, applying the ALM shown in Fig. (11), the time-histories corresponding to  
283 the 12 grid points are determined. An indicative extrapolated record associated  
284 with location  $P_2$  in Fig. (12) is shown in Fig. (13). Next, the PSD estimated based  
285 on the ensemble average of the extrapolated time-histories corresponding to lo-  
286 cation  $P_2$  is shown in Fig. (14), whereas the estimated cross-correlation and the  
287 coherence function between points  $P_1$  and  $P_3$  are presented in Fig. (15). Clearly,  
288 the proposed methodology exhibits a high degree of accuracy in estimating related  
289 statistics. To further assess its performance, the more challenging configuration  
290 shown in Fig. (16) is considered, where only 18 out of the 36 grid points are mea-  
291 surement locations. Indicatively, Fig. (17) shows the estimated PSD at location  $P_1$   
292 as shown in Fig. (16). The estimated cross-correlation and coherence functions  
293 between points  $P_1$  and  $P_2$  and between points  $P_1$  and  $P_3$  are shown in Figs. (18)  
294 and Figs. (19), respectively. The accuracy degree exhibited remains satisfactory,  
295 although it tends to deteriorate as the distance between the locations increases.

**Input:** observation set  $\Omega$ , sampled entries  $\mathcal{P}_\Omega(M_j)$  **Output:**  $A_k, E_k$   
 $Y_0 = 0; E_0 = 0;$   
**while** not converged **do**  
    // solve:  $A_{k+1} = \arg \min_A L(A, E_k, Y_k, \mu_k)$   
     $[U, S, V] = \text{svd}(D - E_k + \mu_k^{-1} Y_k)$   
     $A_{k+1} = US_{\mu_k^{-1}}[S]V^T$        $\triangleright S$ : soft thresholding (shrinkage) operator  
    // solve:  $E_{k+1} = \arg \min_{\pi_\Omega(E)=0} L(A_{k+1}, E, Y_k, \mu_k)$   
     $E_{k+1} = \pi_{\Omega}(M_j - A_{k+1} + \mu_k^{-1} Y_k)$   
     $Y_{k+1} = Y_k + \mu_k (M_j - A_{k+1} - E_{k+1}); \mu_{k+1} = \rho \mu_k$   
     $k \quad k + 1$   
**end while**

Fig. 11: Augmented Lagrange Multipliers (ALM) Method based on [37]

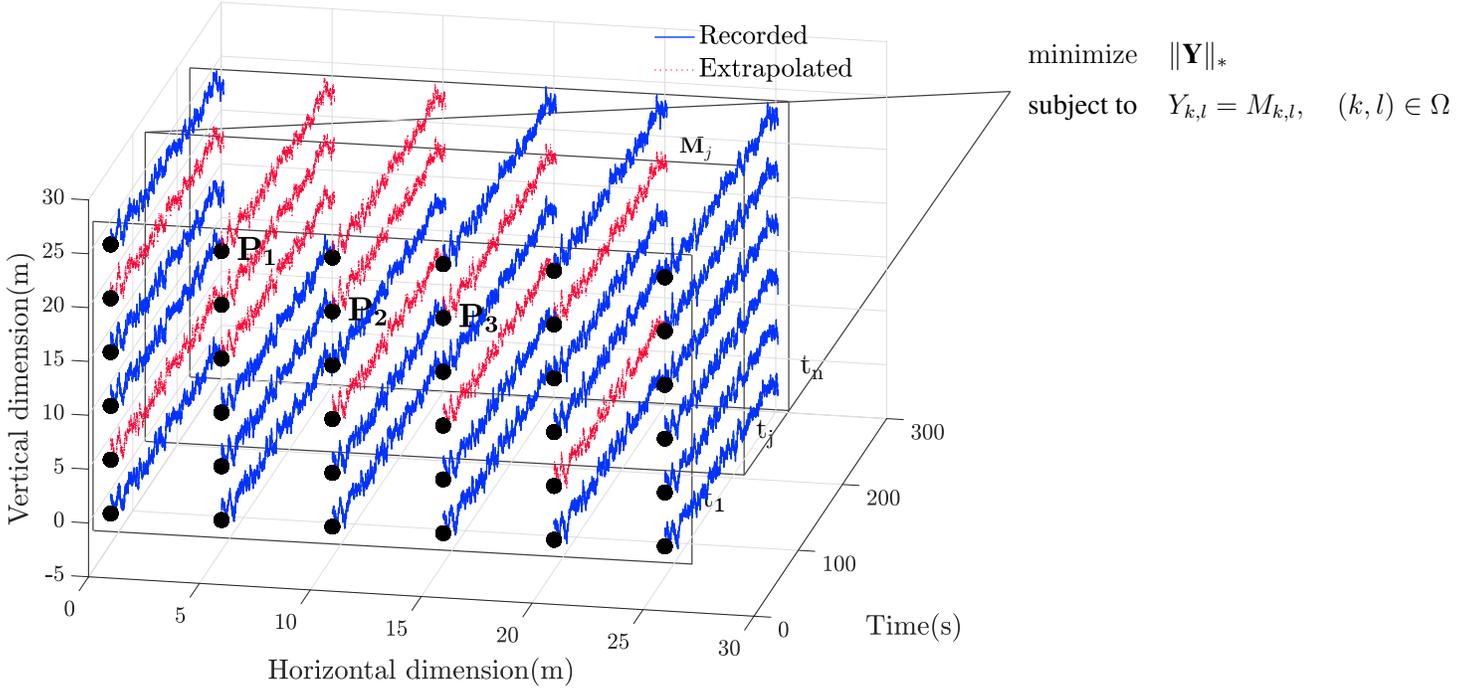


Fig. 12: Schematic representation of the extrapolation scheme in two dimensions via nuclear norm minimization; extrapolating to 12 grid points based on 24 measurement locations

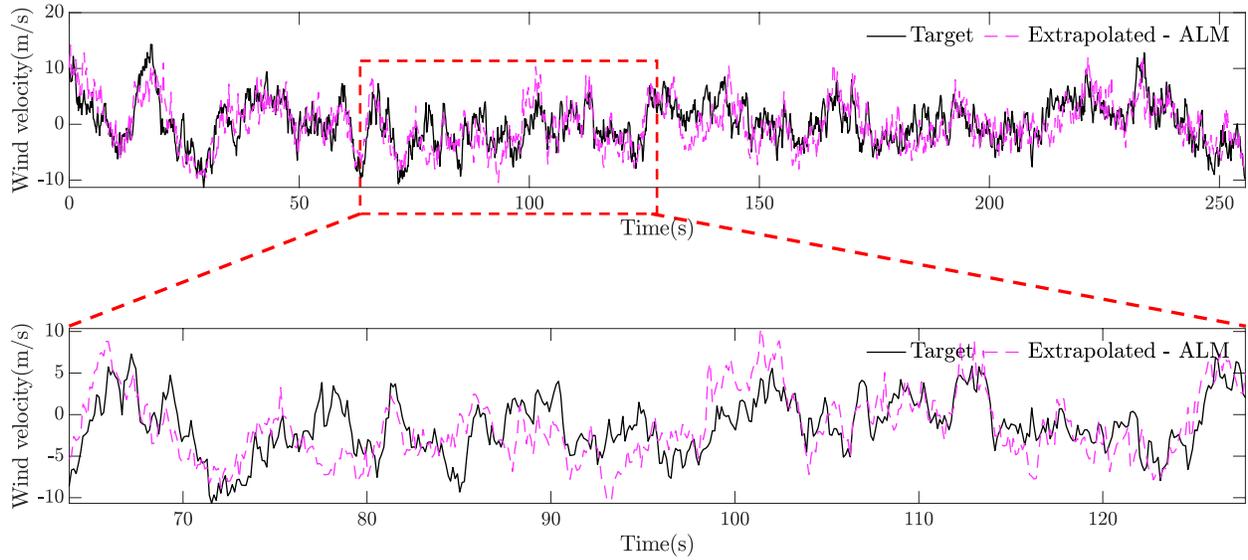


Fig. 13: Extrapolated time history at point  $P_2$  of Fig. (12)

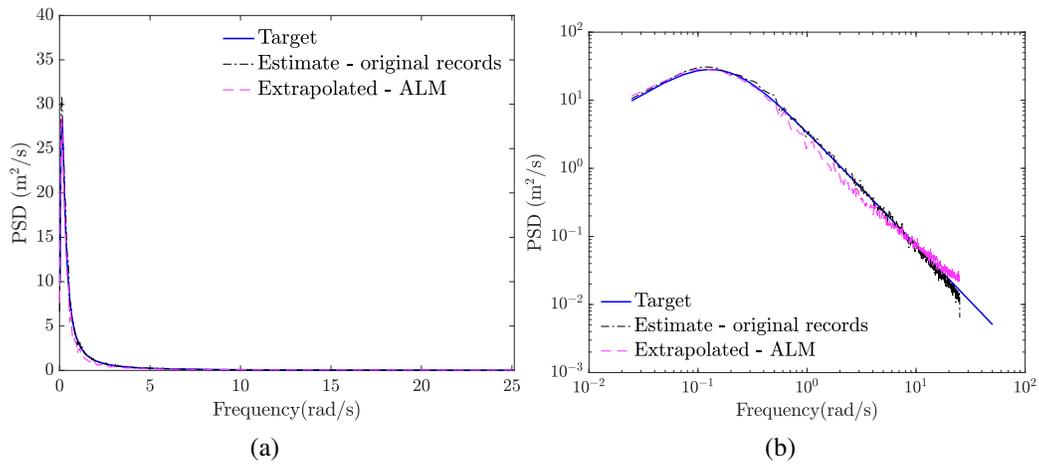


Fig. 14: Estimated PSD corresponding to point  $P_2$  as shown in Fig. (12) based on the ensemble average of ALM-based extrapolated time-histories; (a) linear scale and (b) logarithmic scale.

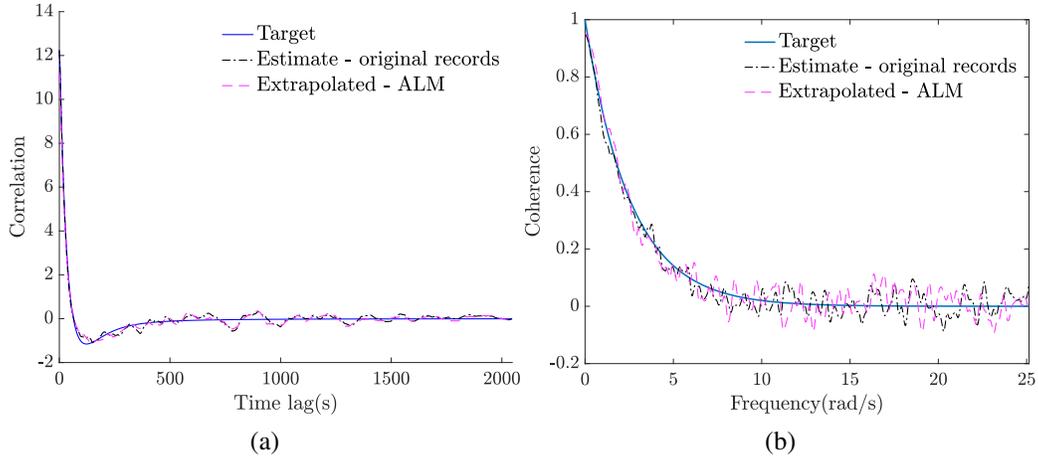


Fig. 15: (a) Cross-correlation and (b) coherence function between the ALM-based extrapolated time histories of points  $P_1$  and  $P_3$  as shown in Fig. (12)

#### 296 4. Concluding remarks

297 In this paper, first, a CS approach based on  $l_1$ -norm minimization in conjunc-  
 298 tion with an adaptive basis re-weighting scheme has been developed for wind field  
 299 time-histories reconstruction and extrapolation in a single spatial dimension. Sec-  
 300 ond, to address computational challenges associated with higher-dimensional do-  
 301 mains, a CS approach based on nuclear norm minimization has been developed for  
 302 wind field extrapolation in two spatial dimensions. Various numerical examples  
 303 have been considered for demonstrating the reliability of the proposed methodolo-  
 304 gies regarding reconstruction and extrapolation of wind field data compatible with  
 305 a joint wavenumber-frequency PSD. It has been shown that the methodologies ex-  
 306 hibit a relatively high degree of accuracy in estimating relevant statistics of the un-  
 307 derlying stochastic field based on the ensemble of the reconstructed/extrapolated  
 308 realizations, even for a large percentage of missing data. However, as anticipated,  
 309 the accuracy degree in estimating coherence values decreases for increasing dis-  
 310 tance between the considered locations in the spatial domain. Finally, it is worth  
 311 noting that the developed methodologies can be used potentially for environmen-  
 312 tal hazard modeling within the context of performance-based design optimization  
 313 of structural systems.

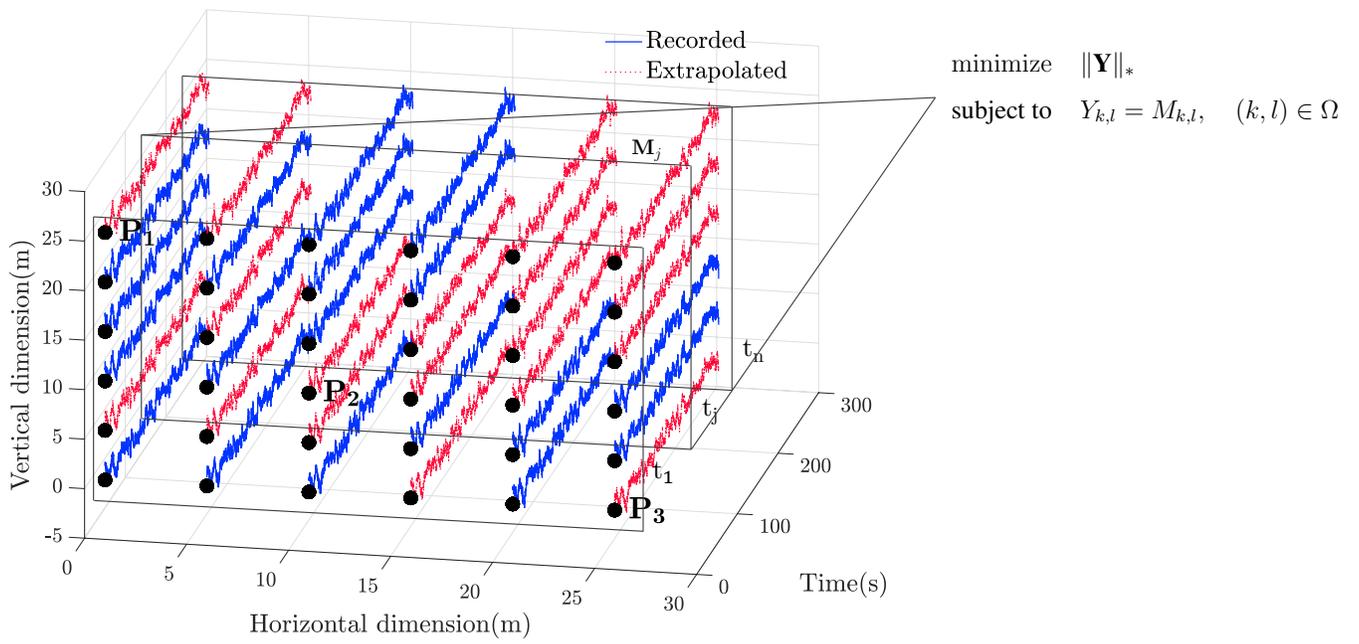


Fig. 16: Schematic representation of the extrapolation scheme in two dimensions via nuclear norm minimization; extrapolating to 18 grid points based on 18 measurement locations

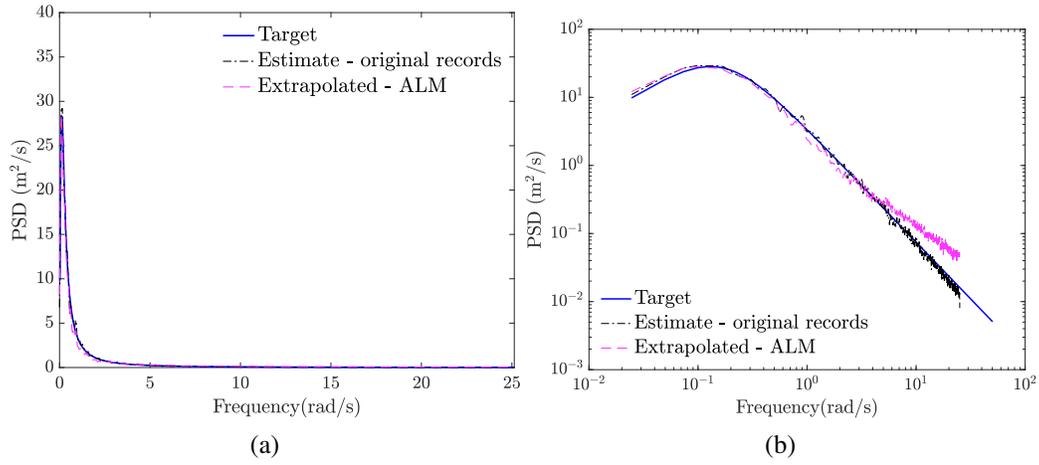


Fig. 17: Estimated PSD corresponding to point  $P_1$  as shown in Fig. (16) based on the ensemble average of ALM-based extrapolated time-histories; (a) linear scale and (b) logarithmic scale.

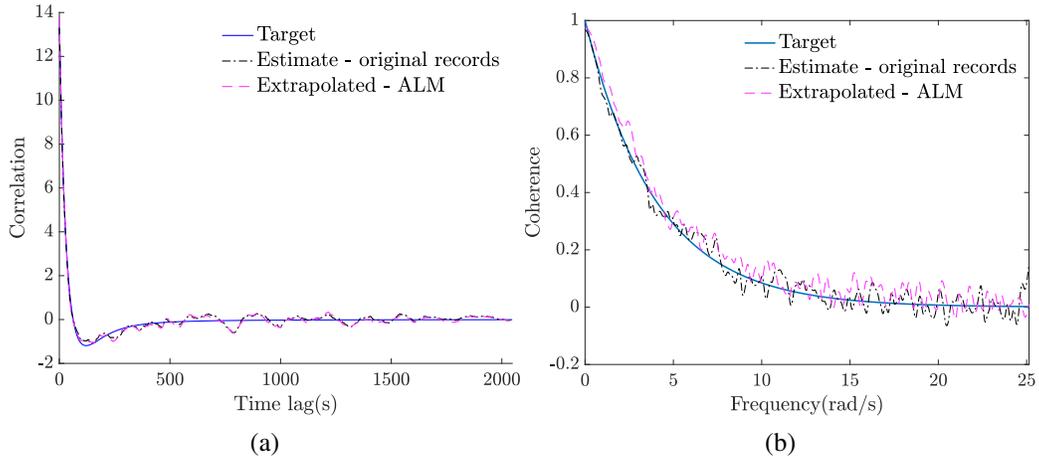


Fig. 18: (a) Cross-correlation and (b) coherence function between the ALM-based extrapolated time histories of points  $P_1$  and  $P_2$  as shown in Fig. (16).

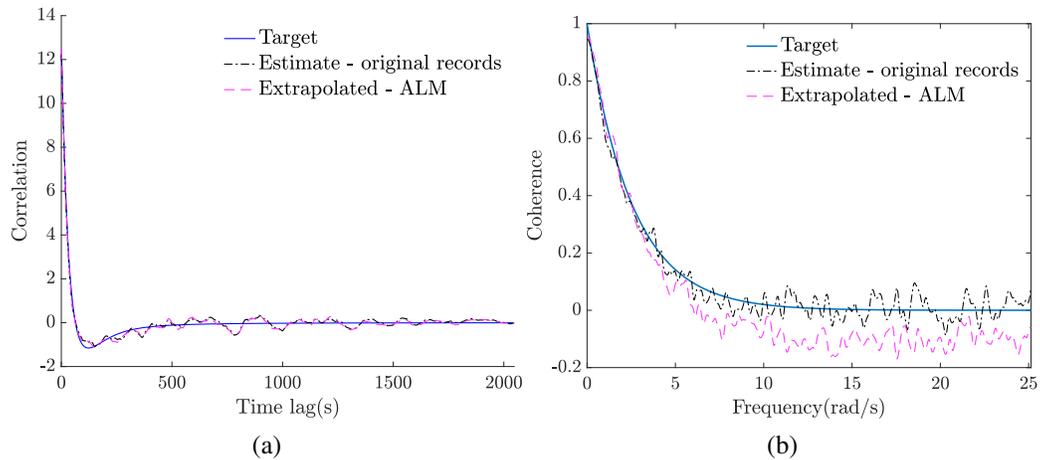


Fig. 19: (a) Cross-correlation and (b) coherence function between the ALM-based extrapolated time histories of points  $P_1$  and  $P_3$  as shown in Fig. (16).

314 **CRedit authorship contribution statement**

315 George Pasparakis: Conceptualization, Methodology, Software, Writing - orig-  
 316 inal draft, Visualization, Validation. Ketson dos Santos: Conceptualization, Method-  
 317 ology. Ioannis A. Kougioumtzoglou: Conceptualization, Methodology, Writ-  
 318 ing - review & editing, Supervision, Project administration, Funding acquisition.  
 319 Michael Beer: Supervision, Funding acquisition.

320 **Declaration of Competing Interest**

321 The authors declare that they have no known competing financial interests or  
 322 personal relationships that could have appeared to influence the work reported in  
 323 this paper.

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